

Induction Shimming for Superconducting Wigglers and Undulators

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Outline

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- Superconductive Undulators
- Mechanical Deviations
- Field errors in Undulators and Wigglers

2 Induction-Shimming: Theory

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- Rectangular Fields Model
- Biot-Savart Model

3 Induction-Shimming: Measurements

- Setup
- Results

4 Conclusion

Introduction - Subject

Induction shimming is a tool both for

- superconducting undulators to minimize phase variations of the emitted photons (to obtain a high brilliance)

(D. Wollmann et al., Phys. Rev. STAB, 12:040702, 2009)

- superconducting damping wigglers to minimize the generation of spurious dispersion (to obtain a low emittance)

Introduction - Superconductive Undulators

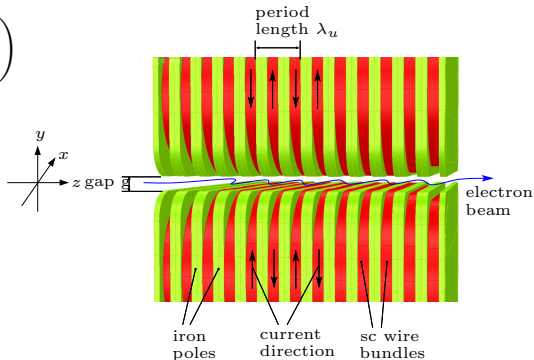
Structure of a superconductive undulator
(Vectorfields Opera3D)

Undulator equation:

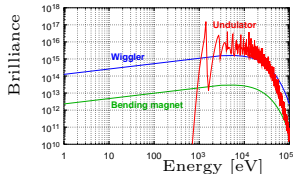
$$\lambda_L = \frac{\lambda_u}{2k\gamma^2} \left(1 + \frac{K^2}{2} + \Theta^2\gamma^2 \right)$$

with

$$K = 0.0934 \cdot \lambda_u [mm] \cdot \tilde{B} [T].$$



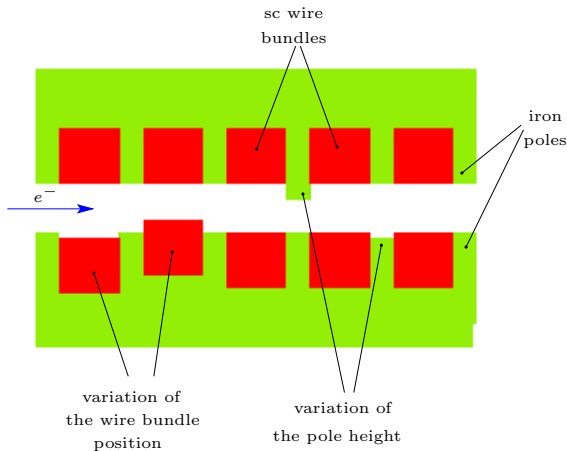
Spectra of SR sources:



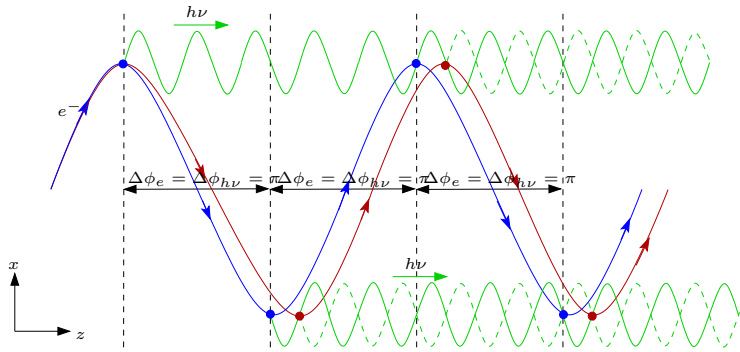
Courtesy R. Butzbach

Introduction - Mechanical Deviations

- Variation of the pole position
- Variation of the wire-bundle position
- Variation of the period-length



Introduction - Field errors in undulators



Measure for undulator field quality:

$$\Phi_{error} = \sqrt{\frac{\sum_{i=1}^{2n} (\tilde{\Phi}_i)^2}{2n}}$$

Introduction - Field errors in damping wigglers

Equilibrium emittance:

$$\epsilon_0 = C_q \gamma^2 \frac{I_5}{j_x I_2}$$

- Damping wigglers contribute to:
 - I_2 via photon emission \rightarrow damping
 - I_5 via dispersion \rightarrow excitation
- Field errors increase dispersion in wigglers
- Measure for minimal contribution to I_5 : first field integral
 - $\int_{z_i}^{z_i+\lambda_w} B_{y,w}(s) ds = 0$ (locally - single periods i)
 - $\int_{z_0}^{z_0+l_w} B_{y,w}(s) ds = 0$ (globally - full wiggler)

$$C_q = 3.832 \cdot 10^{-13} m$$

$$j_x = 1 - \frac{I_4}{I_5} \approx 1$$

$$I_2 = \oint \frac{1}{\rho^2} ds$$

$$I_5 = \oint \frac{\mathcal{H}}{|\rho|^3} ds$$

$$\mathcal{H} = \gamma\eta^2 + 2\alpha\eta\eta' + \beta\eta'^2$$

Induction-Shimming: Faraday's law of induction

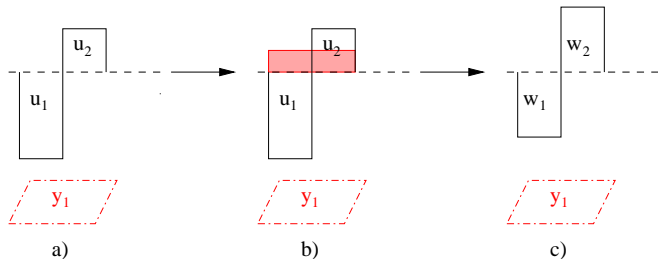
$$\oint_C \tilde{\mathbf{E}} d\vec{l} = -\frac{d}{dt} \int_S \tilde{\mathbf{B}} d\vec{A},$$

- $\tilde{\mathbf{B}}$ is the magnetic flux density over the area S with the contour C
- $\tilde{\mathbf{E}}$ is the electrical field strength
- $d\vec{A}$ is the surface element

Using a superconductive closed-loop along the contour C , yields

$$0 = \frac{d}{dt} \int_S \tilde{\mathbf{B}} d\vec{A}.$$

Induction-Shimming: Rectangular fields, one closed-loop



$$y_1 + u_1 + u_2 = 0 \quad (1)$$

$$w_1 = u_1 + \frac{1}{2}y_1 \quad (2)$$

$$w_2 = u_2 + \frac{1}{2}y_1 \quad (3)$$

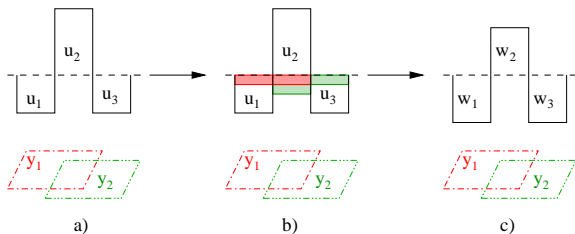
$$\rightarrow w_2 = -w_1 = w \quad (4)$$

$$w = -u_1 - \frac{1}{2}y_1$$

$$w = u_2 + \frac{1}{2}y_1$$

$$\rightarrow w = \frac{-u_1 + u_2}{2} \quad (5)$$

Induction-Shimming: Rectangular fields, two closed-loops



$$y_1 + u_1 + u_2 + \frac{1}{2}y_2 = 0 \quad (6)$$

$$y_2 + u_2 + u_3 + \frac{1}{2}y_1 = 0 \quad (7)$$

$$w_1 = u_1 + \frac{1}{2}y_1 \quad (8)$$

$$w_2 = u_2 + \frac{1}{2}y_1 + \frac{1}{2}y_2 \quad (9)$$

$$w_3 = u_3 + \frac{1}{2}y_2 \quad (10)$$

$$\rightarrow w_2 = -w_1 = -w_3 = w \quad (11)$$

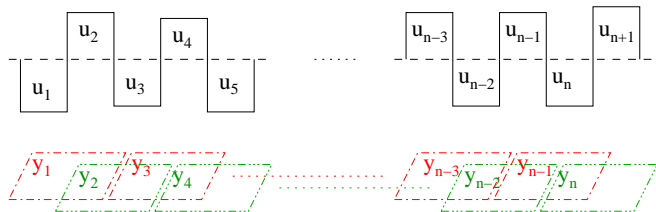
$$w = -u_1 - \frac{1}{2}y_1$$

$$w = u_2 + \frac{1}{2}y_1 + \frac{1}{2}y_2$$

$$w = -u_3 - \frac{1}{2}y_2$$

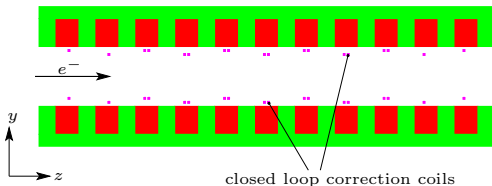
$$\rightarrow w = \frac{-u_1 + u_2 - u_3}{3} \quad (12)$$

Induction-Shimming: Rectangular fields, n closed-loops



$$w = \frac{\pm u_1 \mp u_2 \pm \dots \pm u_n \mp u_{n+1}}{n+1} \quad (13)$$

Induction-Shimming: Biot-Savart Model



Faraday's law of induction for one closed-loop:

$$\dot{I}_i = -\frac{1}{L}\dot{\Phi}_i. \quad (14)$$

The coupling between loop i and loop j with a mutual inductance M_{ij} :

$$\dot{I}_i = M_{ij}\dot{I}_j. \quad (15)$$

Combining equation (14) and (15), solving for $\dot{\Phi}$:

$$\dot{\Phi}_i = L \left(\sum_{j \neq i} M_{ij} \dot{I}_j - \dot{I}_i \right) \quad (16)$$

The self-inductance L and the mutual inductances M_{ij} are defined by the geometrical arrangement and the design of the closed-loops.

Induction-Shimming: Biot-Savart Model

Integration of equation (16) yields

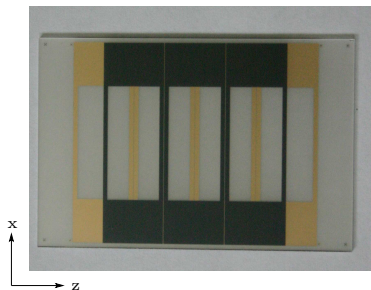
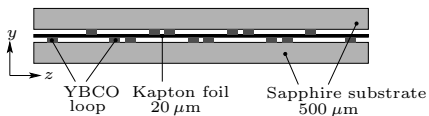
$$\begin{pmatrix} \Phi_1 \\ \Phi_2 \\ \vdots \\ \Phi_{2N-1} \end{pmatrix} = -M_{cc} \cdot \begin{pmatrix} I_1 \\ I_2 \\ \vdots \\ I_{2N-1} \end{pmatrix}, \quad (17)$$

with the symmetrical matrix

$$M_{cc} = \begin{pmatrix} L & a_1 & a_2 & \cdots & a_{2N-1} \\ a_1 & & & \ddots & \vdots \\ a_2 & & \ddots & & a_2 \\ \vdots & \ddots & & & a_1 \\ a_{2N-1} & \cdots & a_2 & a_1 & L \end{pmatrix}, \quad (18)$$

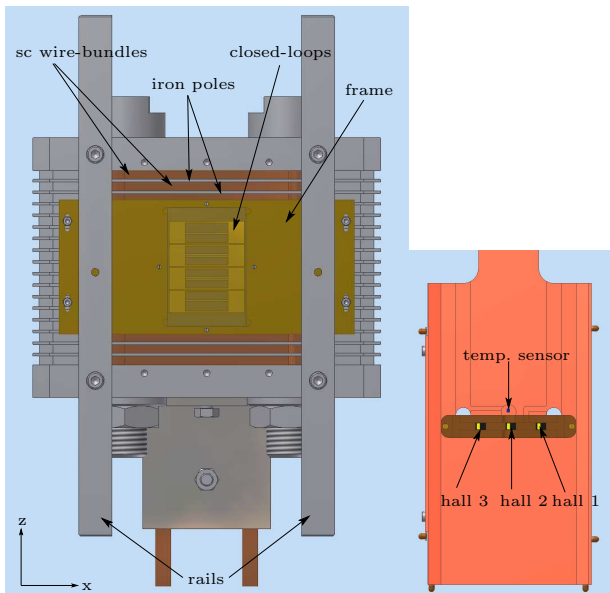
with $a_k = L \cdot M_{i,j}$ and $k = |j - i|$.

Measurements - Setup

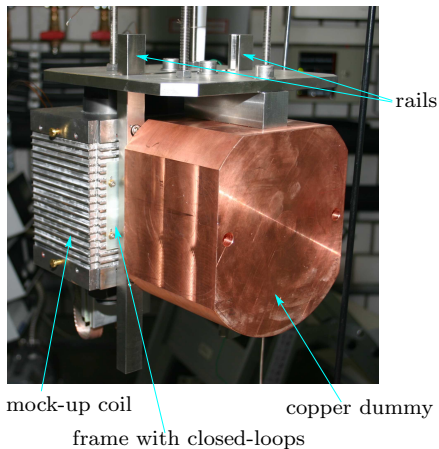


- 330 nm thick YBCO loops on a 500 μm sapphire substrate
- YBCO structures are covered by 200 nm thick gold layer
- dimensions (z-x-plane): 14 × 44 mm²
- two structures (4 loops, 3 loops) stacked, results in a system of 7 overlapping closed-loops
- mounted in a frame on the surface of a mock-up coil
- measured in the cryostat CASPER at ANKA with Hall-probe slide

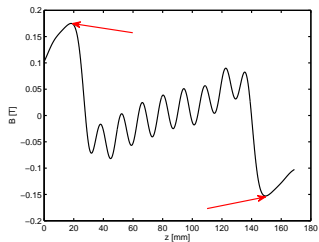
Measurements - Setup



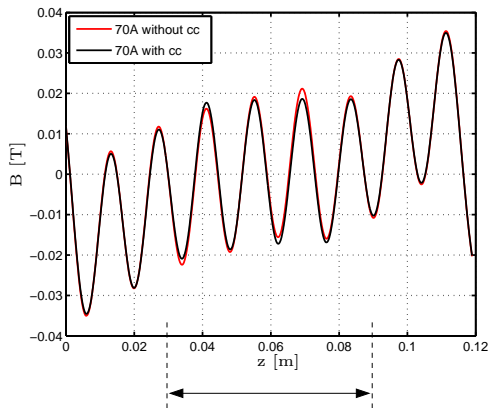
Measurements - Setup



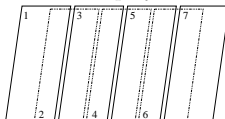
Field at 350A without
Induction-Shimming



Measurements - Results (70 A)

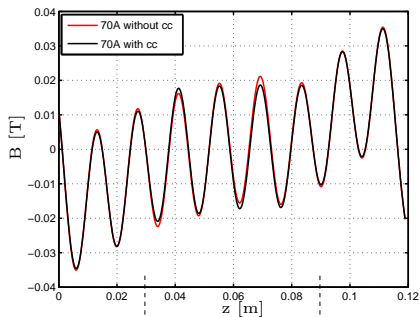


closed-loop system



Measurements - Results (70 A)

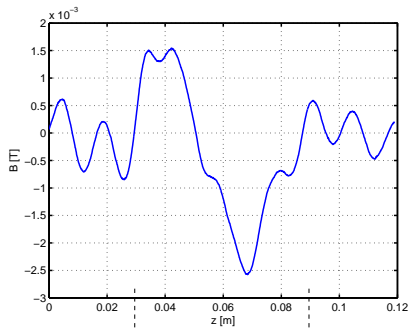
Field comparison



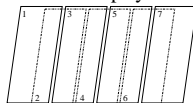
closed-loop system



Difference field

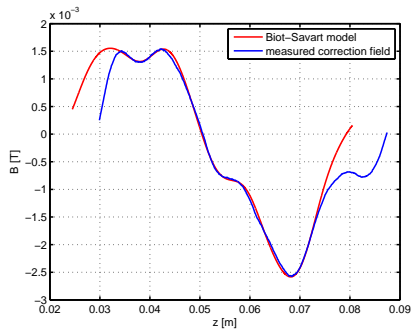


closed-loop system

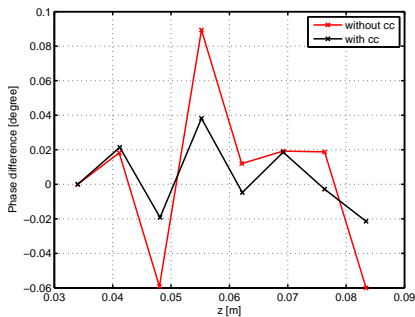


Measurements - Results (70 A)

Diff. field & Biot-Savart model



Phase difference

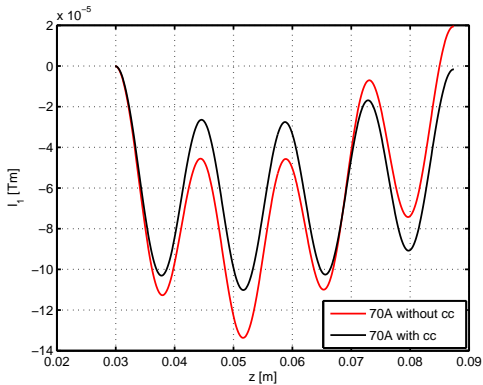


Correction currents induced into the loops:

	loop 1	loop 2	loop 3	loop 4	loop 5	loop 6	loop 7
current [A]	56	-2.0	61	-51.5	13.5	-86	-23

Measurements - Results (70 A)

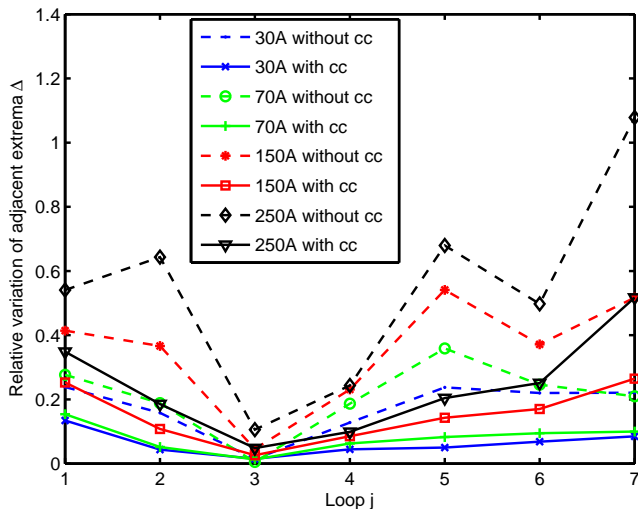
First field integral



- local reduction
- reduction over length of shimming device

Measurements - Results

Variation of adjacent extrema



Conclusion - Results

- Induction-shimming is an field error dependent passive correction scheme
- Theoretically described by Faraday's law of induction
- Experimentally proven with a 7 closed-loop test device
- Correction fields up to 10% of main field measured
- Correction does not fail when critical current in YBCO is exceeded

Conclusion - Outlook



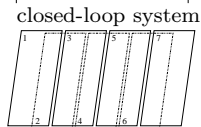
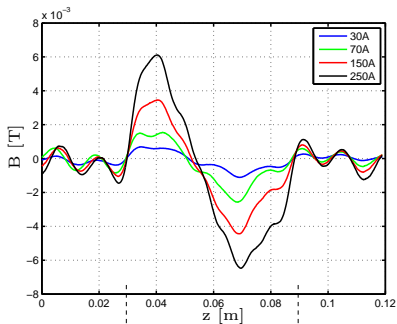
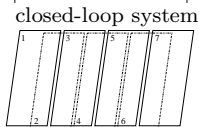
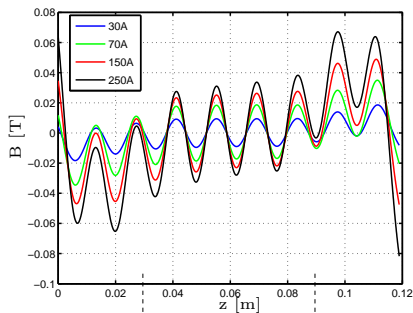
- Test with a complete undulator (12 periods short prototype) and two 12 loop induction-shimming devices
- Reduction of substrate thickness
- Longer induction-shimming systems (from 15 up to 100 periods)

Measurements - Results

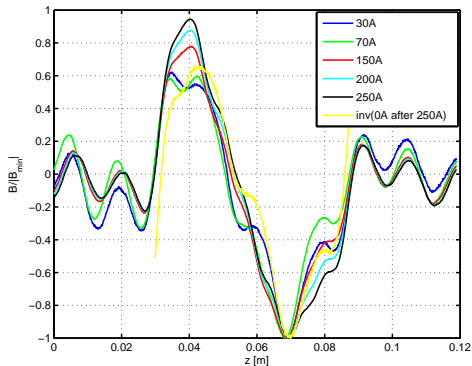
Current in mock-up coil	Induced currents in closed-loop [A]						
	1	2	3	4	5	6	7
30 A	22.8	1.3	21.5	-25.8	8.4	-39.5	-7
50 A	43	-1.0	47	-39	15.7	-63.2	-13
70 A	56	-2.0	61	-51.5	13.5	-86	-23
100 A	45	34	49.5	-29	-10	-92.5	-46
150 A	54	67	66.5	-20.5	-23	-111	-76
200 A	62	102	81	-20.7	-40	-119.5	-110.5
250 A	60	150	75	-25.8	-50	-160	-110
0 A after 250 A	-3	-4.5	-6.7	6.3	-3.5	14.3	4.5

Measurements - Results

Change of correction field pattern from lower to higher currents I_{main}



Hysteretic behaviour after $I_{main} = 250$ A



Possible reasons:

- 1** eddy currents around vortices in the type-II superconductor
 - 2** critical current density reached in parts of the loop system
- shape of residual field (yellow) implies second