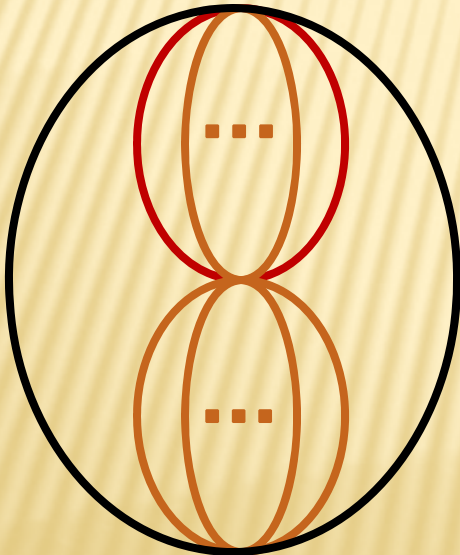


# DIFFERENTIAL REDUCTION TECHNIQUES FOR THE EVALUATION OF FEYNMAN DIAGRAMS

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Stable reduction methods will be important in the evaluation of high-order perturbative diagrams appearing in QCD and mixed QCD-electroweak radiative corrections at the LHC. We describe differential reduction techniques in the hypergeometric function representation of Feynman diagrams and present some representative examples.

# HYPERGEOMETRIC FUNCTION APPROACH

- ✘ Regge proposed (about 45 years ago) that Feynman diagrams could be represented in terms of **hypergeometric functions**.
- ✘ This proposal was based on a study of the singularities of Feynman diagrams as a function of complex momenta (Landau singularities). Matching the HG function to the diagram would determine the appropriate representation.
- ✘ Much work has been done on finding the representation of various diagrams in terms of HG functions, and finding recursion relations among them which can be the basis for a reduction algorithm.

# HYPERGEOMETRIC SERIES

A Laurent series in  $r$  variables

$$\Phi(\vec{x}) = \sum C(\vec{m}) x_1^{m_1} \cdots x_r^{m_r}$$

is **hypergeometric** if for each  $i$ , the ratio  $C(\vec{m} + \vec{e}_i) / C(\vec{m})$

is a rational function in the multi-index  $\vec{m}$ , with

$$\vec{e}_i = (0, \dots, 0, 1, 0, \dots, 0) \leftarrow \begin{matrix} i^{\text{th}} \\ \text{place} \end{matrix}$$

This type of HG series called a **Horn series**.



# HORN-TYPE HYPERGEOMETRIC FUNCTIONS

- ✗ In general, starting with the Feynman parameterization, any Feynman diagram containing arbitrary powers of propagators of the form  $(k^2 - m^2)^{-j}$  can be written in terms of a multiple Mellin-Barnes integral leading to a linear combination

$$\sum_{\vec{\alpha}} C_{\vec{\alpha}} x_1^{\alpha_1} \cdots x_r^{\alpha_r} \Phi(\vec{A}; \vec{B}; \vec{x})$$

of Horn-type hypergeometric functions, where  $x_j$  are rational functions of masses and momenta,  $\alpha_j$  depends on the powers of propagators and dimension of space-time, and  $C$ 's are ratios of  $\Gamma$  functions with arguments depending on the  $\alpha$ 's.

# HORN-TYPE HYPERGEOMETRIC FUNCTIONS

Specifically,

$$\Phi(\vec{A}; \vec{B}; \vec{x}) = \sum_{\vec{m}=\vec{0}}^{\infty} \left( \frac{\prod_{j=1}^K \Gamma\left(\sum_{a=1}^r \mu_{ja} m_a + A_j\right)}{\prod_{k=1}^L \Gamma\left(\sum_{b=1}^r \nu_{kb} m_b + B_k\right)} \right) x_1^{m_1} \cdots x_r^{m_r}$$

with  $\mu_{ja}$ ,  $\nu_{kb}$  rational,  $A_j$ ,  $B_k$  complex.

An important property of Horn-type hypergeometric functions is the existence of a set of differential **contiguous relations** between functions with shifted arguments.

# DIFFERENTIAL REPRESENTATION

The Horn-Type HG series can be shown to satisfy a system of differential equations of the form

$$Q_j \left( \sum_{k=1}^r x_k \frac{\partial}{\partial x_k} \right) \frac{\Phi(\vec{x})}{x_j} = P_j \left( \sum_{k=1}^r x_k \frac{\partial}{\partial x_k} \right) \Phi(\vec{x}), \quad j = 1, \dots, r$$

with polynomials  $P_j$ ,  $Q_r$  satisfying

$$\frac{C(\vec{m} + \vec{e}_j)}{C(\vec{m})} = \frac{P_j(\vec{m})}{Q_j(\vec{m})}$$



# DIFFERENTIAL CONTIGUOUS RELATIONS

- ✘ Both the upper ( $A$ ) and lower ( $B$ ) arguments can be shifted by applying differential operators:

$$\Phi(\vec{A} + \vec{e}_c; \vec{B}; \vec{x}) = \left( \sum_{b=1}^r \mu_{ca} x_a \frac{\partial}{\partial x_a} + A_c \right) \Phi(\vec{A}; \vec{B}; \vec{x}) = U_{[A_c \rightarrow A_c+1]}^+ \Phi(\vec{A}; \vec{B}; \vec{x})$$

$$\Phi(\vec{A}; \vec{B} - \vec{e}_c; \vec{x}) = \left( \sum_{b=1}^r \nu_{cb} x_b \frac{\partial}{\partial x_b} + B_c \right) \Phi(\vec{A}; \vec{B}; \vec{x}) = L_{[B_c \rightarrow B_c-1]}^- \Phi(\vec{A}; \vec{B}; \vec{x})$$

- ✘ If inverse operators  $U_{[A_c \rightarrow A_c-1]}^-$ ,  $L_{[B_c \rightarrow B_c+1]}^+$  can be found, they can be applied to form the basis of a reduction algorithm relating all HG functions related by integer shifts in the arguments to a single HG function.

# TAKAYAMA ALGORITHM

- ✗ The complete differential reduction for  ${}_2F_1$  was constructed by Gauss (1823). The inverse operators for the general Horn-type functions can be constructed by the Takayama algorithm.  
[Nobuki Takayama, Japan J. Appl. Math 6 (1989) 147].

- ✗ The functions  $\Phi(\vec{A}; \vec{B}; \vec{x})$  satisfy differential equations  $D_j \Phi(\vec{A}; \vec{B}; \vec{x}) = 0$ ,  $j = 1, \dots, r$   
with

$$D_j = Q_j \left( \sum_{k=1}^r x_k \frac{\partial}{\partial x_k} \right) \frac{1}{x_j} - P_j \left( \sum_{k=1}^r x_k \frac{\partial}{\partial x_k} \right).$$



# TAKAYAMA ALGORITHM

- ✗ Let  $\mathcal{D}$  be the ring of differential operators with rational functions of  $\vec{x}$  as coefficients. Let  $\mathfrak{I}$  be the left ideal in  $\mathcal{D}$  of generated by the differential operators  $D_j$  and construct a Gröbner basis  $\mathfrak{G} = \{G_i \mid i = 1, \dots, q\}$  of  $\mathfrak{I}$ .

- ✗ Then  $U_{[A_c \rightarrow A_c - 1]}^-$ ,  $L_{[B_c \rightarrow B_c + 1]}^+$  are solutions to the linear equations

$$\sum_{i=1}^q f_i(\vec{x}) G_i + U_{[A_c + 1 \rightarrow A_c]}^- U_{[A_c \rightarrow A_c + 1]}^+ = 1,$$

$$\sum_{i=1}^q g_i(\vec{x}) G_i + L_{[B_c - 1 \rightarrow B_c]}^+ L_{[B_c \rightarrow B_c - 1]}^- = 1.$$

where  $f_i$ ,  $g_i$  are arbitrary rational functions. Solutions exist if the left ideal generated by  $\mathfrak{G} \cup \{U_{\gamma_c}^+\}$  [or  $\{L_{\sigma_c}^-\}$ ] spans  $\mathcal{D}$ .

# DIFFERENTIAL REDUCTION

Once the raising and lowering operators are available, it is possible to express all HG functions with integer shifts in terms of an original function  $\Phi(\vec{A}; \vec{B}; \vec{x})$  and polynomials such that  $P_0(\vec{x}), P_{m_1, \dots, m_r}(\vec{x})$

$$P_0(\vec{x})\Phi(\vec{A} + \vec{a}; \vec{B} + \vec{b}; \vec{x}) = \sum_{m_1, \dots, m_r} P_{m_1, \dots, m_r}(\vec{x}) \prod_{i=1}^r \left( \frac{\partial}{\partial x_i} \right)^{m_i} \Phi(\vec{A}; \vec{B}; \vec{x})$$

Cases where  $x_i = x_j$  or  $P_0(\vec{x}) = 0$  require a limiting procedure to define the reduction.

# GENERALIZED HYPERGEOMETRIC FUNCTIONS

Generalized HG Functions have the form

$${}_pF_{p-1}(\vec{a}; \vec{b}; z) = {}_pF_{p-1}\left(\begin{matrix} a_1, & \dots, & a_p \\ b_1, & \dots, & b_{p-1} \end{matrix} \middle| z\right) = \sum_{n=0}^{\infty} \frac{\prod_{i=1}^p (a_i)_n}{\prod_{j=1}^{p-1} (b_j)_n} \frac{z^n}{n!}$$

with the Pochhammer symbol  $(a)_n = \Gamma(a + n)/\Gamma(a)$

✘ They satisfy a differential equation

$$\left[ z \prod_{i=1}^p \left( z \frac{d}{dz} + a_i \right) - z \frac{d}{dz} \prod_{k=1}^{p-1} \left( z \frac{d}{dz} + b_k - 1 \right) \right] {}_pF_{p-1}(\vec{a}; \vec{b}; z) = 0$$

✘ The raising and lowering operators are

$$U_{[a_i \rightarrow a_i+1]}^+ = 1 + \frac{z}{a_i} \frac{d}{dz}, \quad L_{[b_i+1 \rightarrow b_i]}^- = 1 + \frac{z}{b_i-1} \frac{d}{dz}.$$



# RESULT OF REDUCTION

- ✗ This allows a given HG function  ${}_{p+1}F_p(\vec{a} + \vec{m}, \vec{b} + \vec{n}; z)$  to be expressed in terms of a basic function  ${}_{p+1}F_p(\vec{a}, \vec{b}; z)$  and  $p$  derivatives:

$$\begin{aligned}
 S(\vec{a}, \vec{b}, z) {}_{p+1}F_p(\vec{a} + \vec{m}, \vec{b} + \vec{n}; z) \\
 = \sum_{k=0}^p R_k(\vec{a}, \vec{b}, z) (z\partial_z)^k {}_{p+1}F_p(\vec{a}, \vec{b}; z).
 \end{aligned}$$

where  $S$ ,  $R_k$  are polynomials in all parameters.

- ✗ A program HYPERDIRE has been written to automate differential reduction.

V.V. Bytev, M. Kalmykov, and B. Kniehl, in preparation. See Nucl. Phys. B836[FS] (2010) 129 for the theory and some examples which follow.

# CRITERIA FOR REDUCIBILITY

For certain cases of the parameters, the r.h.s. is further **reducible**: can be expressed in terms of lower-order HG functions or with fewer derivatives.

- I:** If one of the  $a_i$  is an integer, only  $p - 1$  derivatives are needed: the  $p^{\text{th}}$  term becomes a polynomial.
- II:** If one of the differences  $a_i - b_i$  is a positive integer (or 0) and certain conditions hold for the  $a_i$ , the r.h.s. can be expressed in terms of lower-order HG functions.
- III:** If at least two of the differences  $a_i - b_i - 1$  are positive integers, and certain conditions hold on the  $a_i$ , the r.h.s. can be expressed in terms of lower-order HG functions.
- IV:**  ${}_{p+1}F_p(\vec{A} + \vec{m}, \vec{a} + \vec{k}, \vec{A} + \vec{m} + \vec{1}, \vec{b} + \vec{l}; z)$  with integers  $\vec{m}, \vec{k}, \vec{l}$  can be expressed in terms of  ${}_{p+1}F_p(\vec{A}, \vec{a}, \vec{A} + \vec{1}, \vec{b}; z)$  HG functions of lower order, and derivatives.

# EXAMPLE: SUNSET DIAGRAMS

The  $q$ -loop sunset diagram with 2 lines of mass  $m$  and  $q - 1$  massless lines is

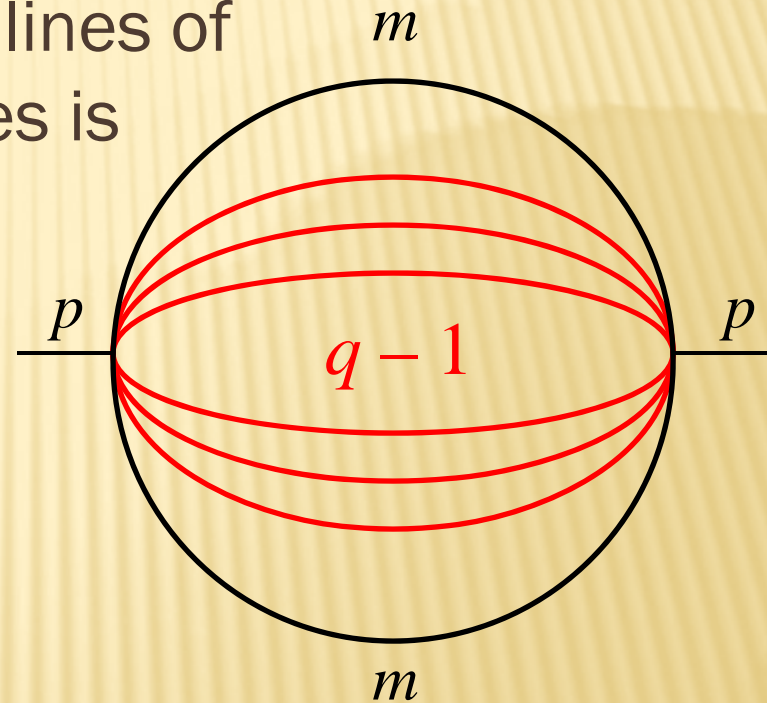
$$J_{22}^q \left( m^2, p^2, \alpha_1, \alpha_2, \sigma_1, \dots, \sigma_{q-1} \right)$$

with massive denominators

$$\left( k_q^2 - m^2 \right)^{\alpha_1}, \quad \left[ \left( p + \sum k_i \right)^2 - m^2 \right]^{\alpha_1}$$

and massless denominators

$$\left( k_1^2 \right)^{\sigma_1}, \dots, \left( k_{q-1}^2 \right)^{\sigma_{q-1}}.$$



The Mellin-Barnes representation leads to

$${}_4F_3 \left( \alpha_1 + \sigma - \frac{n}{2}(q-1), \alpha_2 + \sigma - \frac{n}{2}(q-1), \sigma - \frac{n}{2}(q-2), \alpha + \sigma - \frac{n}{2}q \mid \frac{p^2}{4m^2} \right)$$

$$\frac{n}{2}, \sigma + \frac{1}{2}(\alpha - n(q-1)), \sigma + \frac{1}{2}(\alpha + 1 - n(q-1))$$

where  $\alpha, \sigma$  are the sums of the two kinds of exponent.



# EXAMPLE: SUNSET DIAGRAMS

The one-loop case can be further reduced:

For  $q = 1$  ( $\sigma = 0$ ) and integer  $a_i$ , the hypergeometric function is reducible via Criterion II. The  $n/2$  upper and lower parameters can be removed:

$${}_4F_3\left(\alpha_1, \alpha_2, \frac{n}{2}, \alpha - \frac{n}{2} \middle| \frac{p^2}{4m^2}\right) = {}_3F_2\left(\alpha_1, \alpha_2, \alpha - \frac{n}{2} \middle| \frac{p^2}{4m^2}\right)$$

Compare Boos & Davydychev, Theor. Math. Phys. 89 (1991) 1052

This still satisfies Criterion II, since for even  $\alpha$ , either  $\alpha_1 - \alpha/2$  or  $\alpha_2 - \alpha/2$  must be a positive integer or 0, while for odd  $\alpha$ , similar reasoning applies to  $(\alpha + 1)/2$ .

Thus, we can reduce the result to  ${}_2F_1$  with one integer upper parameter.

# EXAMPLE: SUNSET DIAGRAMS

The two-loop case can also be further reduced:

For  $q = 2$  and  $\sigma, a_i$  integers, the parameters become

$${}_4F_3\left(\alpha_1 + \sigma - \frac{n}{2}, \alpha_2 + \sigma - \frac{n}{2}, \sigma, \alpha + \sigma - n \middle| \frac{p^2}{4m^2}\right)$$

which has integer parameter differences and an integer upper parameter, so it can be reduced to  ${}_3F_2$  and its first derivative, plus a rational function, with  ${}_3F_2$  of the form

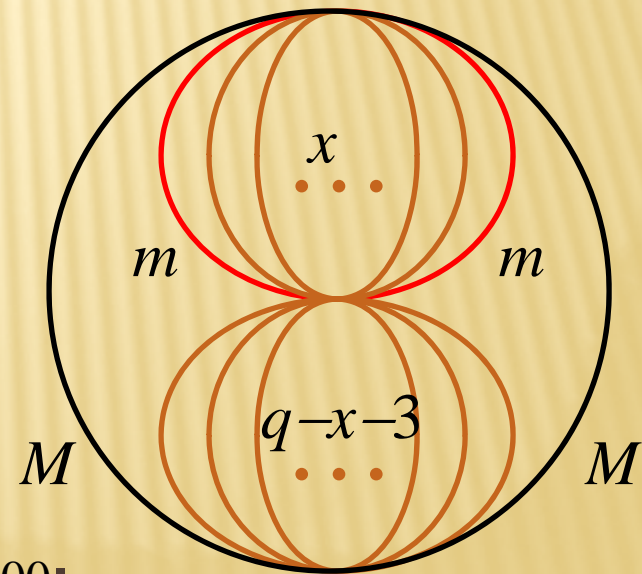
$${}_3F_2\left(1, I_1 - \frac{n}{2}, I_2 - n \middle| \frac{p^2}{4m^2}\right) \cdot$$

# EXAMPLE: BUBBLE DIAGRAM

Consider the  $q$ -loop vacuum bubbles where the two black lines have mass  $M$ , the two red lines have mass  $m$ , and the  $q - 3$  gold lines are all massless.

The propagators of mass  $m$  have exponents  $\alpha_1, \alpha_2$ , the propagators of mass  $M$  have exponents  $\beta_1, \beta_2$ , the  $x$  upper massless propagators have exponents  $\sigma_i$ , and the  $q - x - 3$  lower ones have exponents  $\rho_i$ .

This Feynman diagram is denoted  $B_{112200}^q$ .





# EXAMPLE: BUBBLE DIAGRAM

In this case, a lengthy expression is obtained giving a sum of four HG functions  ${}_7F_6$ . These can be reduced to

$$\left(z\partial_z\right)^k {}_4F_3\left(\begin{matrix} I_1 - \frac{n}{2}(x-1), I_2 - \frac{n}{2}x, I_3 - \frac{n}{2}(x+1), I_4 + \frac{1}{2} + \frac{n}{2}(q-x-2) \\ I_5 + \frac{n}{2}, I_6 + \frac{n}{2}(q-x-1), I_7 + \frac{1}{2} - \frac{n}{2}x \end{matrix} \middle| \frac{M^2}{m^2}\right)$$

$$\left(z\partial_z\right)^k {}_4F_3\left(\begin{matrix} I_1 - \frac{n-1}{2}, I_2 - \frac{n}{2}(q-2), I_3 - \frac{n}{2}(q-1), I_4 - \frac{n}{2}q \\ I_5 + \frac{n}{2}(q-x-1), I_6 + \frac{n}{2}(q-x-2), I_7 + \frac{1}{2} - \frac{n}{2}(q-1) \end{matrix} \middle| \frac{M^2}{m^2}\right)$$

$$\left(z\partial_z\right)^k {}_4F_3\left(\begin{matrix} 1, I_1 + \frac{1}{2}, I_3 - \frac{n}{2}(q-1), I_2 - \frac{n}{2}(q-2), I_4 - \frac{n}{2}(q-3) \\ I_5 + \frac{n}{2}, I_6 + \frac{1}{2} - \frac{n}{2}(q-2), I_7 - \frac{n}{2}(q-x-2), I_8 - \frac{n}{2}(q-x-3) \end{matrix} \middle| \frac{M^2}{m^2}\right)$$

for  $k = 0, 1, 2, 3$  and  $I_i$  integers.

## EXAMPLE: BUBBLE DIAGRAM

- ✘ In the special case  $x = 0$ , the first of these HG functions can be further reduced to

$$\left(z\partial_z\right)^k {}_3F_2\left(\begin{matrix} 1, I_2 - \frac{n}{2}, I_3 + \frac{1}{2} + \frac{n}{2}(q-2) \\ I_4 + \frac{n}{2}(q-1), I_5 + \frac{1}{2} \end{matrix} \middle| \frac{M^2}{m^2}\right)$$

for  $k = 0, 1$  and  $I_i$  integers.

- ✘ In the special case  $x = 1$ , the first of these HG functions can be reduced to

$$\left(z\partial_z\right)^k {}_4F_3\left(\begin{matrix} 1, I_1 - \frac{n}{2}, I_2 - n, I_3 + \frac{1}{2} + \frac{n}{2}(q-3) \\ I_4 + \frac{n}{2}, I_5 + \frac{n}{2}(q-2), I_5 - \frac{n-1}{2} \end{matrix} \middle| \frac{M^2}{m^2}\right)$$

for  $k = 0, 1, 2$  and  $I_i$  integers.

# ENUMERATING MASTER INTEGRALS

All examples we considered give a Feynman diagram of the form

$$\Phi(n, \vec{j}; z) = \sum_{i=1}^k z^{l_i} C_{l_i}(n, \vec{j}) {}_{p+1}F_p \left( \begin{matrix} \vec{A}_i \\ \vec{B}_i \end{matrix} \middle| \kappa z \right)$$

where  $\vec{j}$  is a list of powers of propagators,  $n$  is the dimension, and  $z$  is a ratio of kinematic parameters, while  $\kappa$  are rational numbers, and  $C_{l_i}$  are products of  $\Gamma$  functions depending only on  $n$  and  $\vec{j}$ .

The number of basis elements in the differential reduction is the highest power  $\nu$  of the differential operator in the expansion

$${}_{p+1}F_p \left( \begin{matrix} \vec{A} \\ \vec{B} \end{matrix} \middle| z \right) = \sum_{l=1}^{\nu} R_l(z) (z \partial_z)^l {}_{s+1}F_s \left( \begin{matrix} \vec{A} - \vec{I}_1 \\ \vec{B} - \vec{I}_2 \end{matrix} \middle| z \right).$$

Where  $R_l$  are rational functions and  $\vec{I}_i$  are lists of integers.



# ENUMERATING MASTER INTEGRALS

- ✗ The Feynman diagram  $\Phi(z)$  can alternatively be expressed in terms of a set of master integrals  $\Phi_k(z)$  that may be derived from  $\Phi(z)$  via integration by parts (IBP), symbolically

$$\Phi(n, \vec{j}; z) = \sum_{k=1}^h B_k(n, \vec{j}; z) \Phi_k(n; z)$$

where terms expressible solely in terms of gamma functions are not counted.

- ✗ The number of terms in this expansion is related to the number of derivatives in the differential reduction:

$$h = \nu + 1.$$

This is independent of the number  $k$  of hypergeometric functions in the original expression.