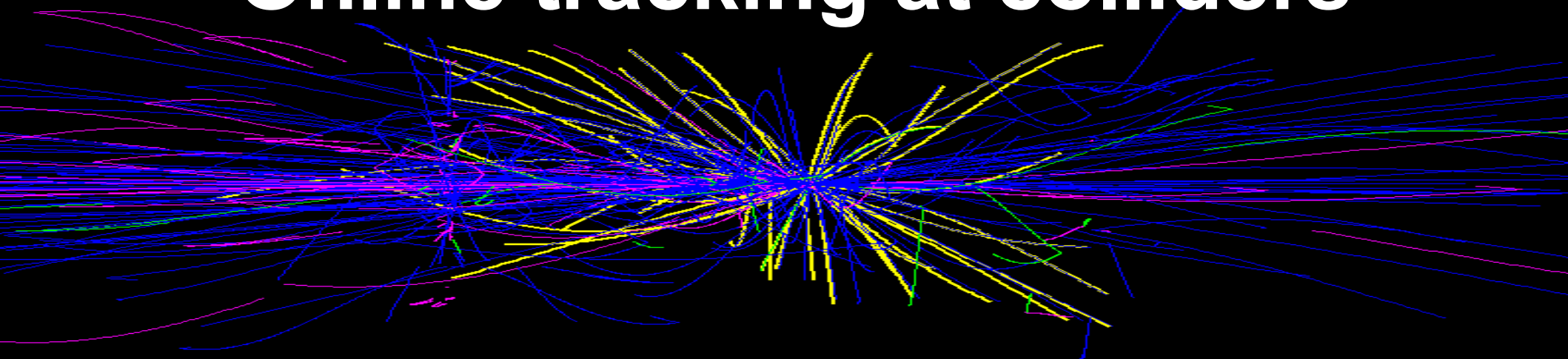




35th International Conference
on High Energy Physics
Paris, 22-28 July 2010

Online tracking at colliders



Silvia Amerio
INFN Padova



Why online tracking?

A good trigger system needs to combine **data reduction** with **sophisticated physics selection** to increase the purity of the collected sample.

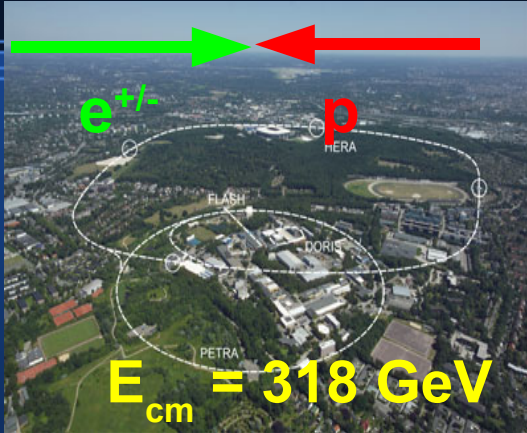
Online tracking allows accurate reconstruction of crowded events (high luminosity --> pile-up) in time for a trigger decision:

- a calorimetric tower integrates energy from all the particles in the event --> it cannot distinguish between hard scattering and pile-up
- online tracking **can distinguish particles based on their z and p_T**

Online tracking is challenging!

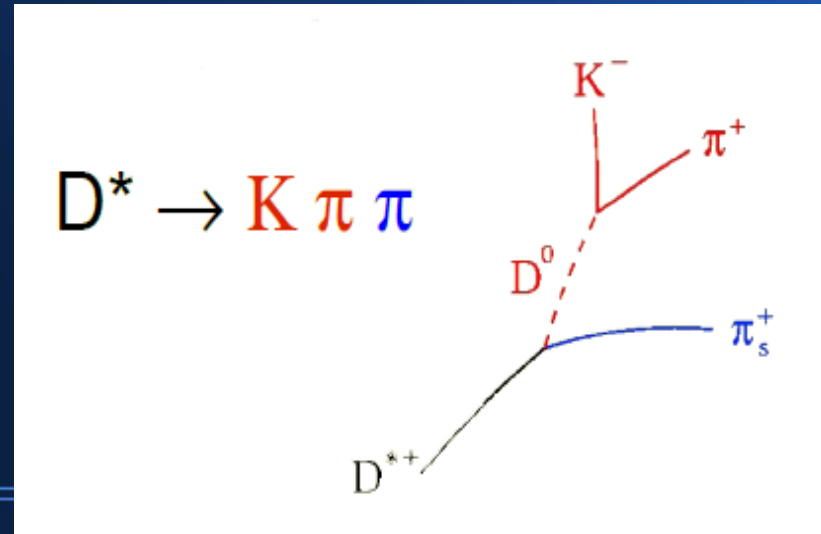
- Time constraints: track reconstruction in few μs at L1, \sim tens of μs at L2
- High number of readout channels
- High occupancy --> large combinatorics

Why online tracking?

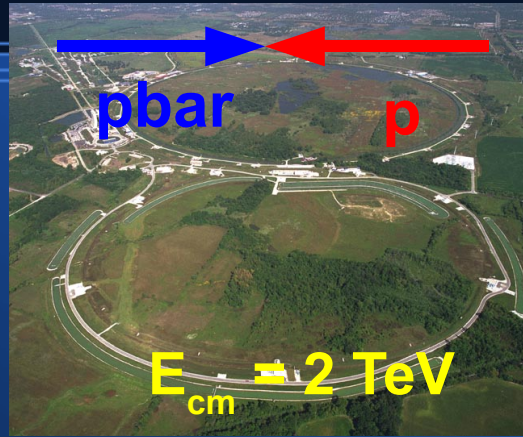
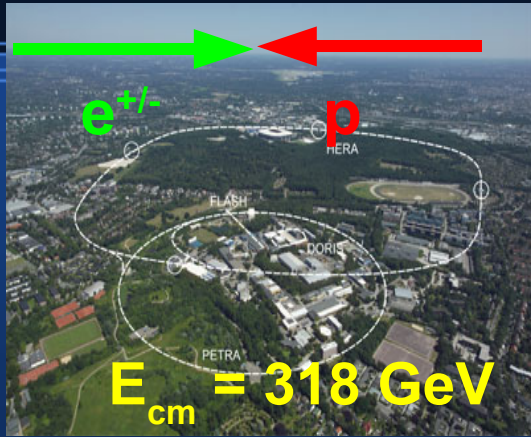


$$L = 2 \cdot 10^{31} \text{ cm}^{-2}\text{s}^{-1}$$

Fast **T**rack **T**rigger
(FTT, 2004-2007)



Why online tracking?



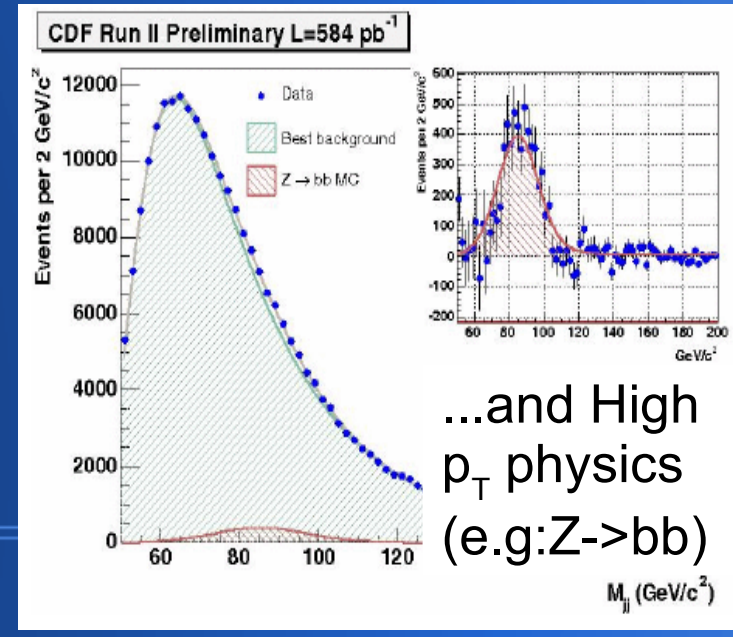
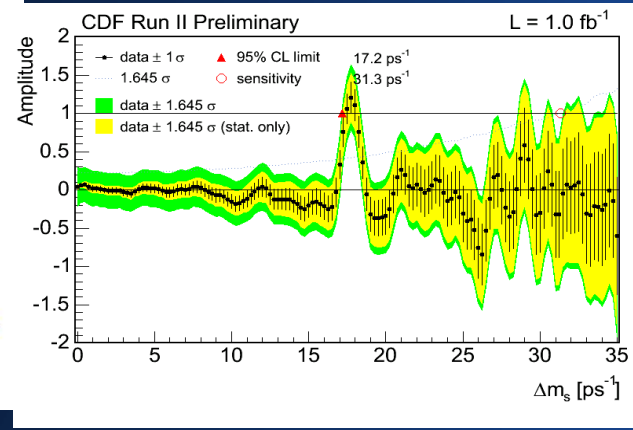
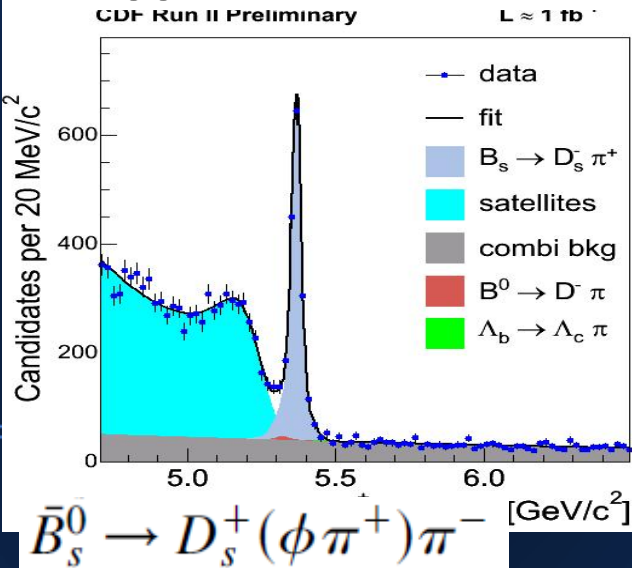
Silicon Vertex Tracker (SVT)

$L = 2 \cdot 10^{31} \text{ cm}^{-2} \text{ s}^{-1}$

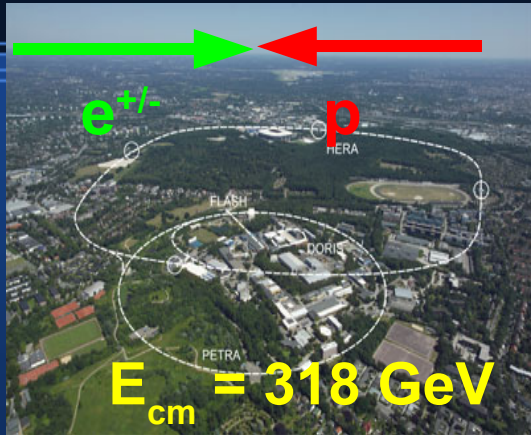
$L = 3 \cdot 10^{32} \text{ cm}^{-2} \text{ s}^{-1}$

6 pp int/evt

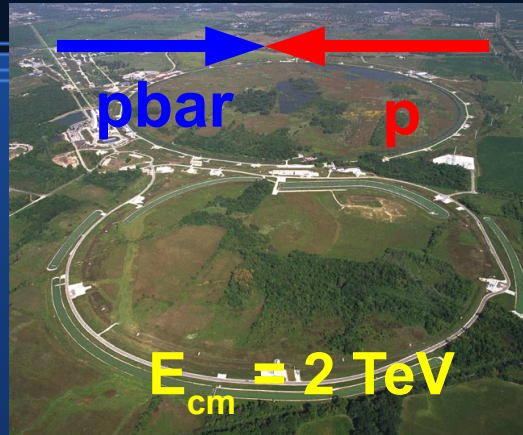
Trigger on displaced tracks for B



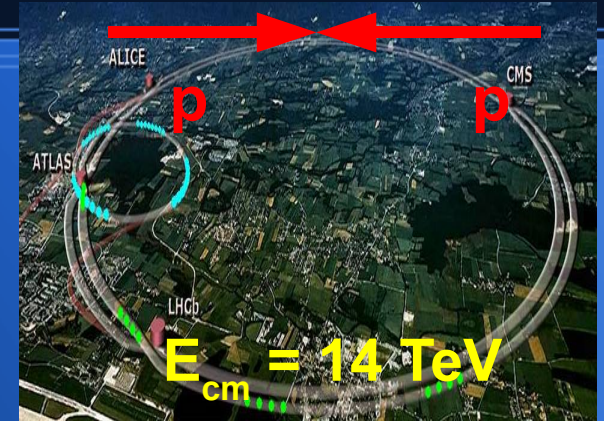
Why online tracking?



$$L = 2 \cdot 10^{31} \text{ cm}^{-2} \text{ s}^{-1}$$



$$L = 3 \cdot 10^{32} \text{ cm}^{-2} \text{ s}^{-1}$$



$$\text{LHC} : 10^{34} \text{ cm}^{-2} \text{ s}^{-1}$$

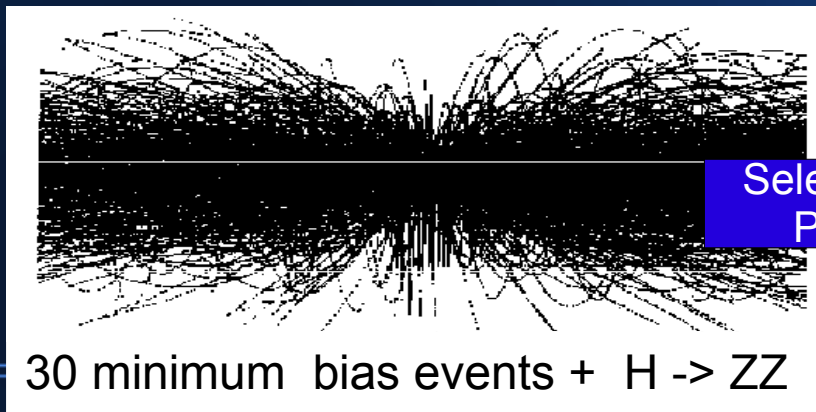
$$\text{SLHC} : 3 \cdot 10^{34} \text{ cm}^{-2} \text{ s}^{-1}$$

$$10^{35} \text{ cm}^{-2} \text{ s}^{-1}$$

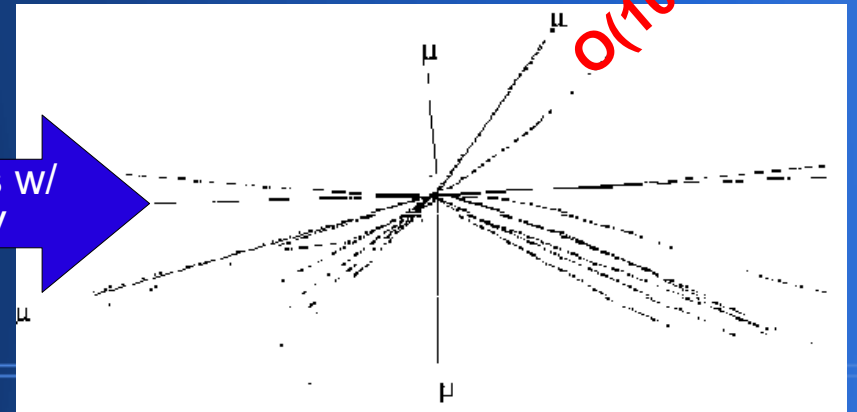
ATLAS and CMS proposals for SLHC

6 pp int/evt

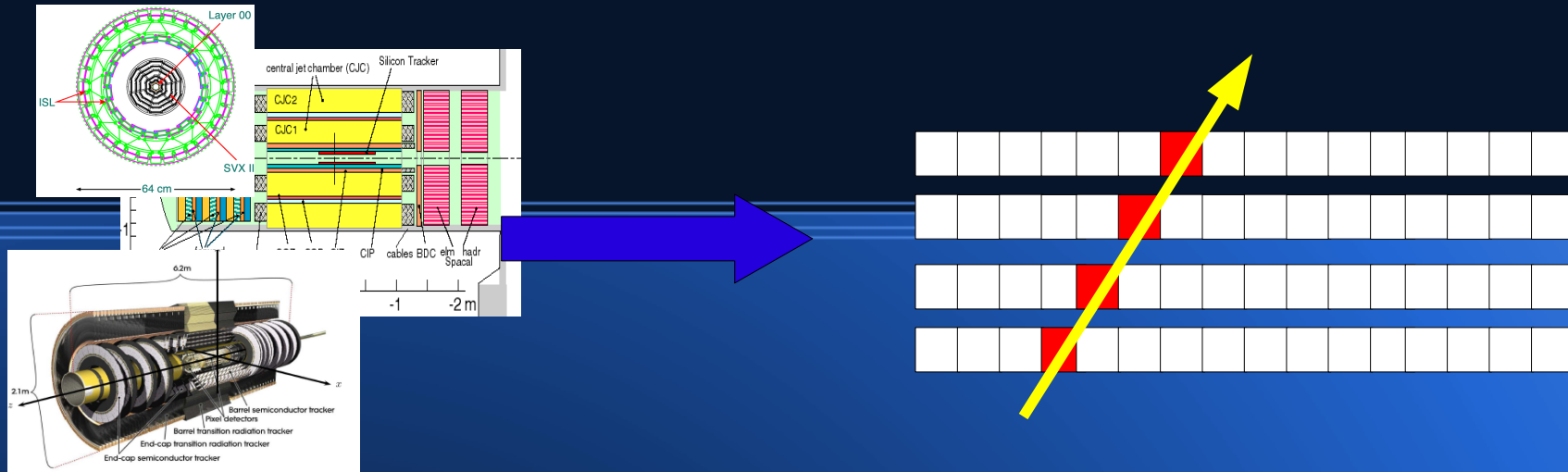
O(100) pp int/evt



Select tracks w/
 $P_t > 2 \text{ GeV}$

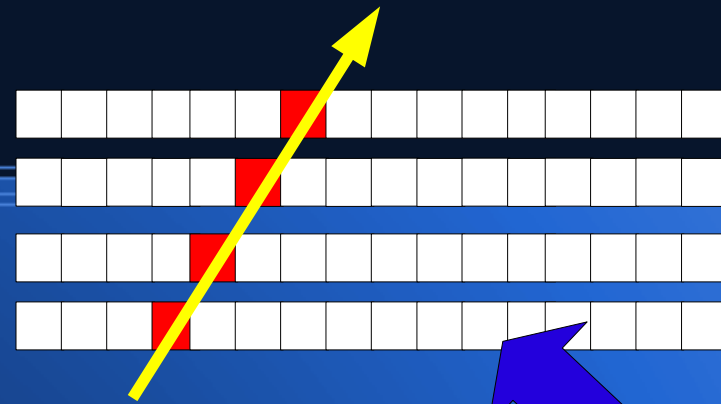
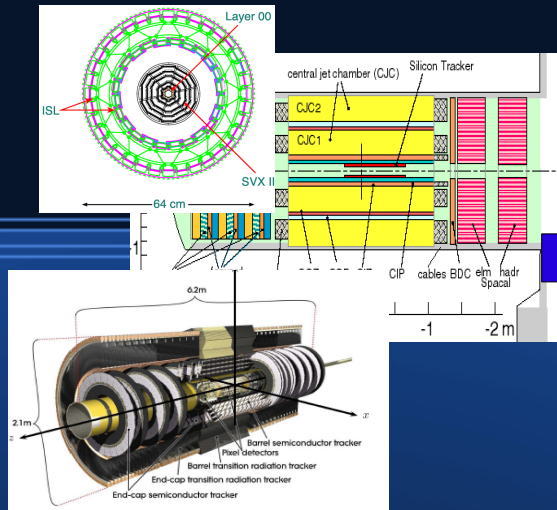


Track identification: Pattern Matching

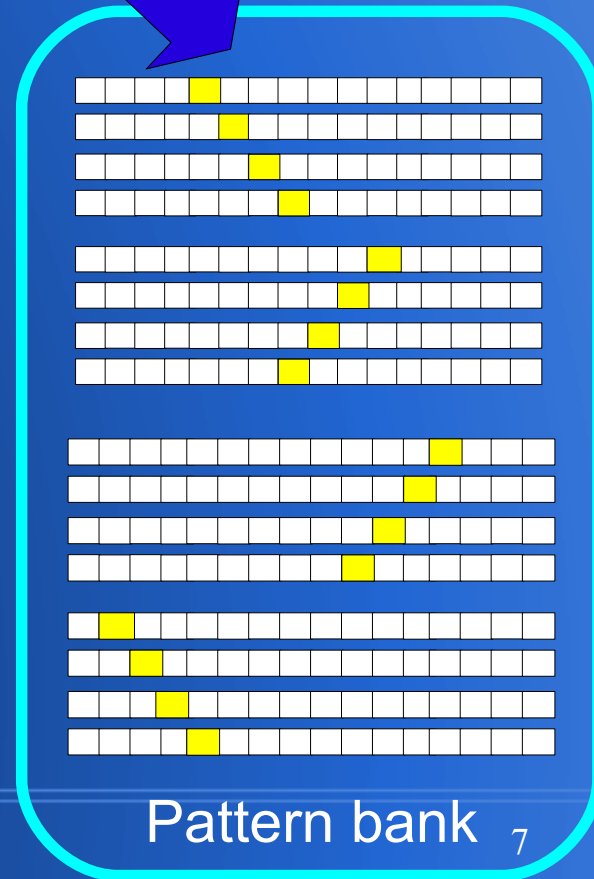


- Tracking detectors = **layers segmented into bins**
- Each charged particle generates a **hit pattern**

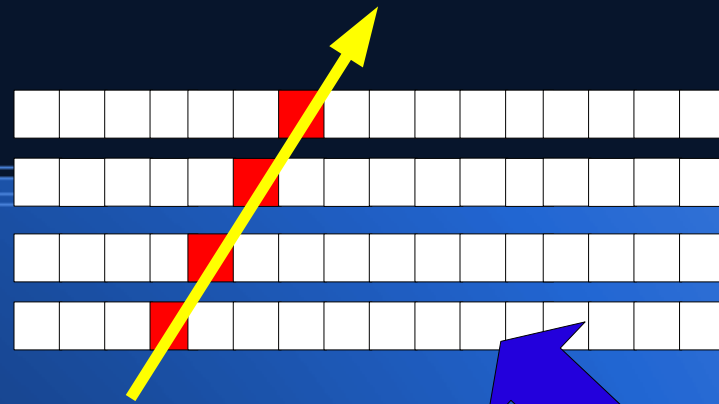
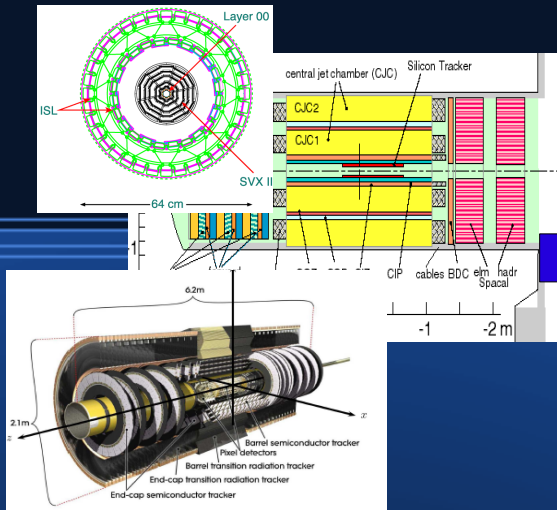
Track identification: Pattern Matching



- Tracking detectors = layers segmented into bins
- Each charged particle generates a hit pattern
- All possible hit patterns stored in memory (**pattern bank**)
- Hit pattern matching a precomputed pattern = **Candidate Track**



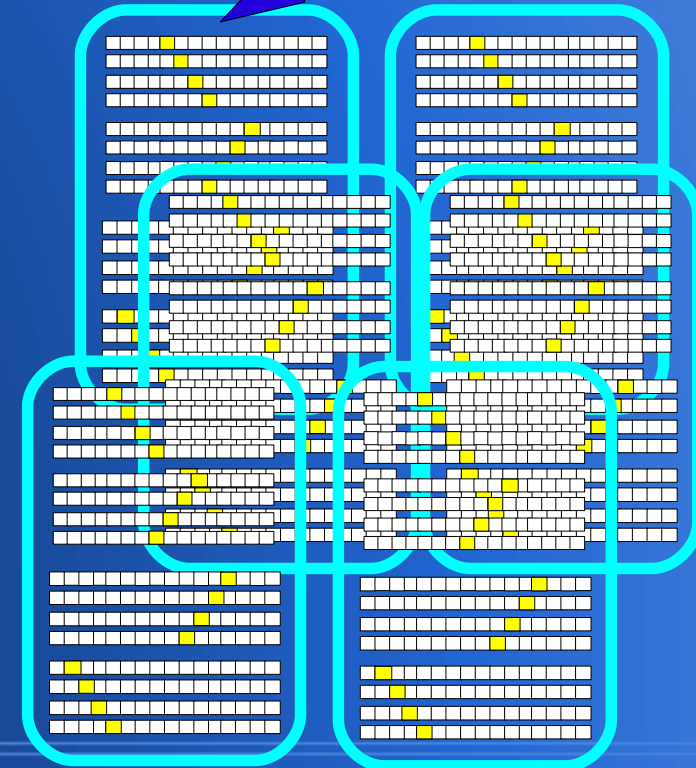
Track identification: Pattern Matching



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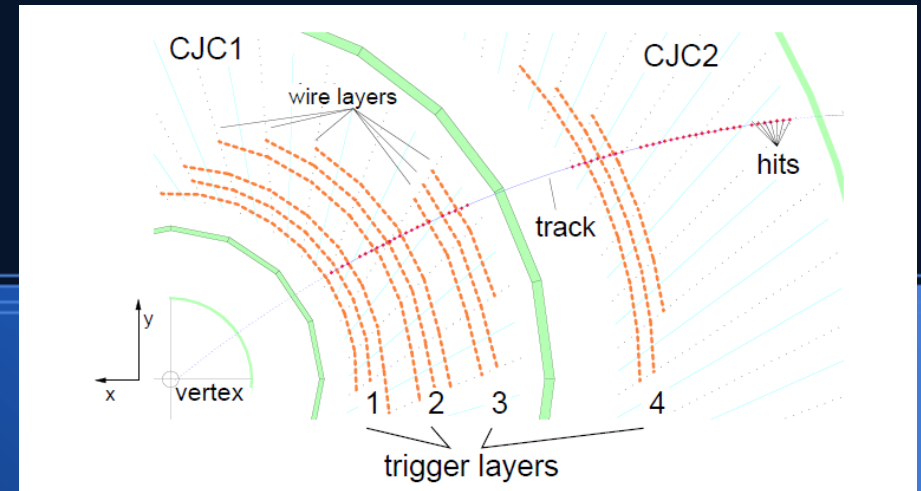
Candidate Track

High degree of parallelism (Associative Memory or commercial Content Addressable Memories) to increase speed.



The Fast Track Trigger @ H1

L1 bandwidth is limited \rightarrow use only a subsample (12/56) of the drift chamber layers



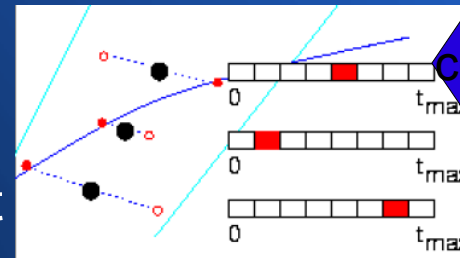
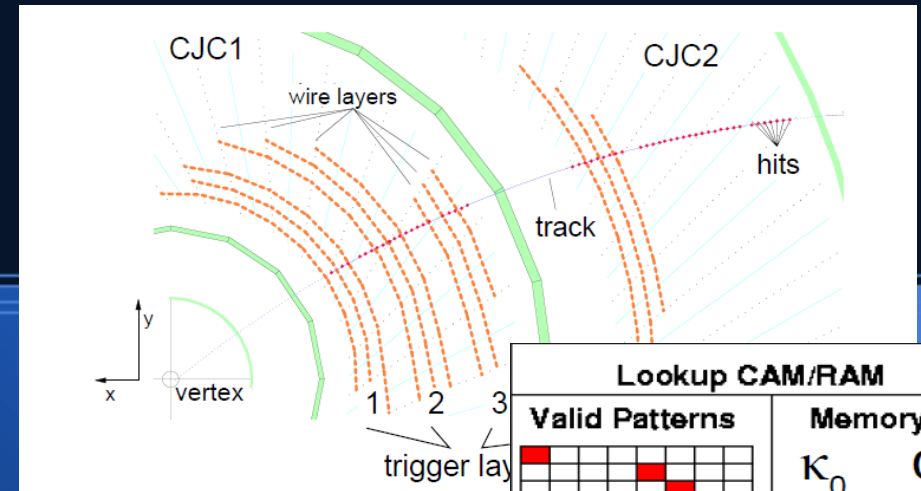
The Fast Track Trigger @ H1

L1 bandwidth is limited → use only a subsample (12/56) of the drift chamber layers

L1: Find track segments and link them into tracks.

L2: Repeat linking step at **full resolution**, 3D fit

L3: reconstruct complex objects (invariant masses, jets)



Lookup CAM/RAM	
Valid Patterns	Memory
	$\kappa_0 \quad \varphi_0$
	$\kappa_1 \quad \varphi_1$
...	track parameter
	$\kappa_{N-1} \quad \varphi_{N-1}$
	$\kappa_N \quad \varphi_N$

CAMs in high density FPGA (Altera)
Working frequency 100 MHz

The Fast Track Trigger @ H1

L1 bandwidth is limited → use only a subsample (12/56) of the drift chamber layers

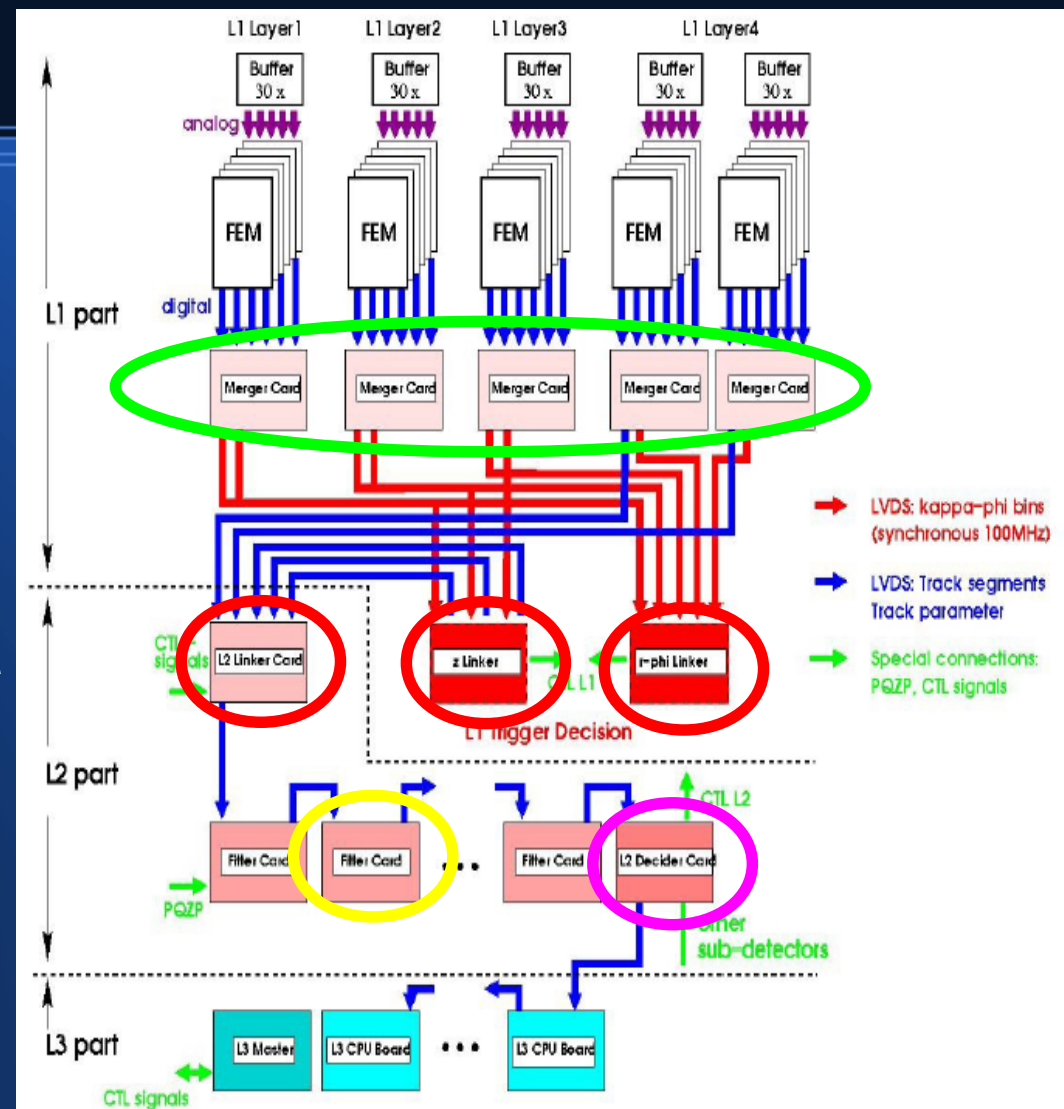
L1: Find track segments and link them into tracks.

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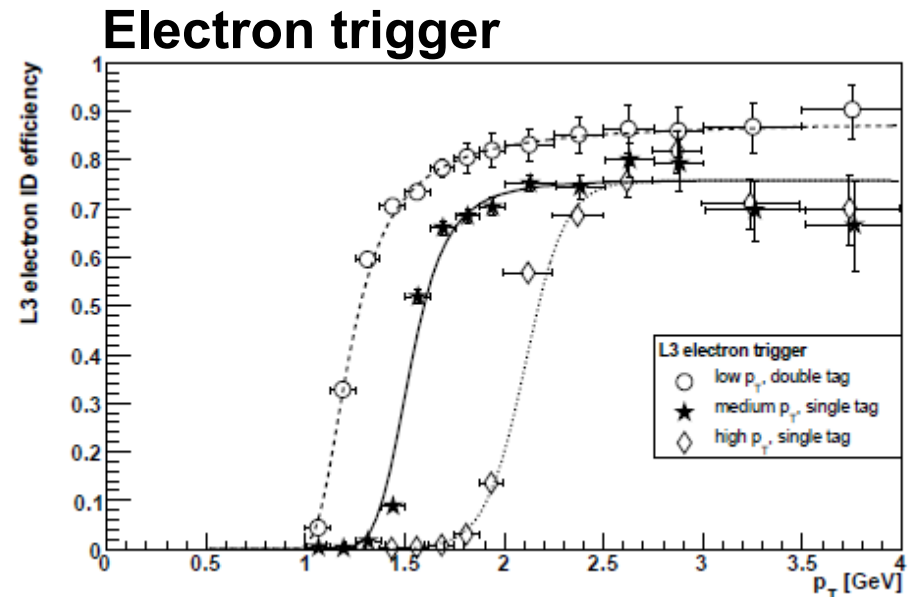
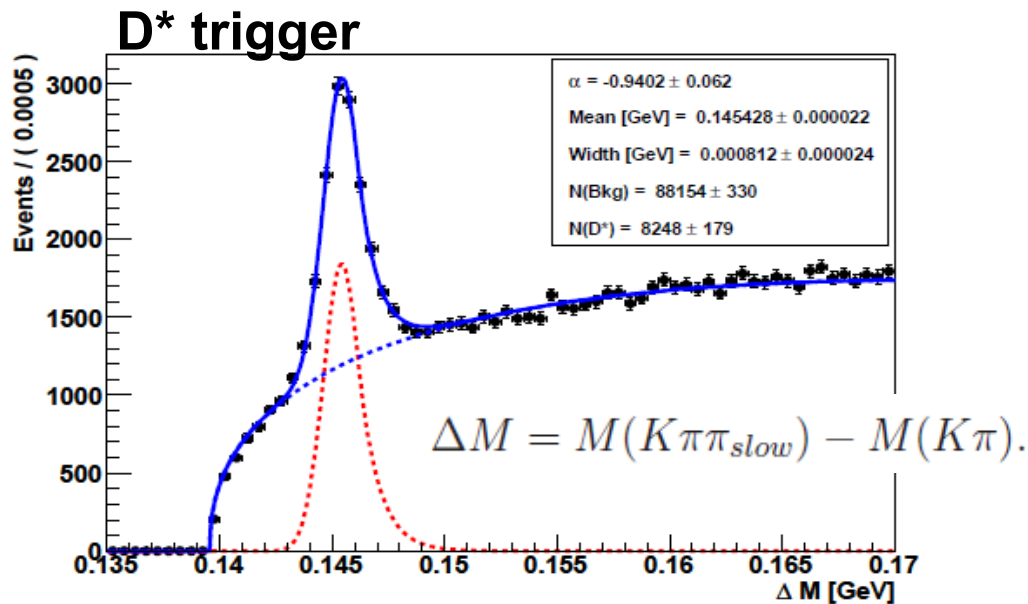
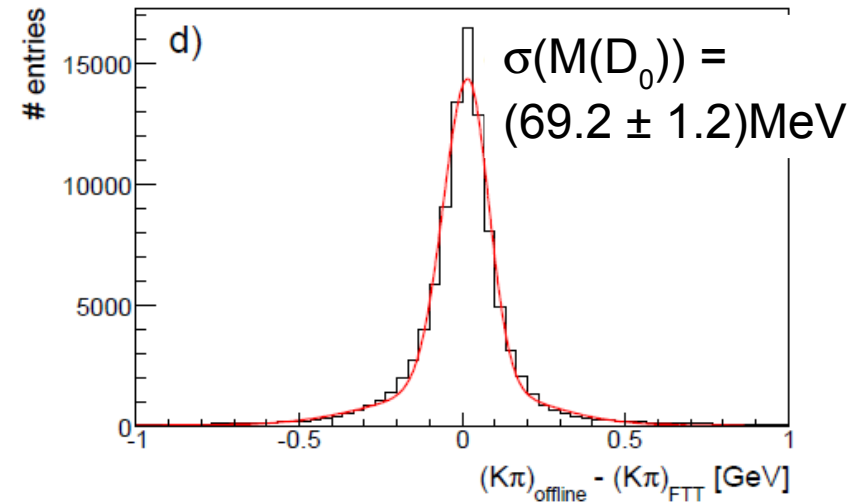
Based on a single flexible, multipurpose board (MultiFunctional Processing Board) that can

- Merge data streams
- Link track segments at L1 and L2
- Fit tracks at L2
- Make L2 decision



FTT performance

- Fit up to 48 tracks per event w/ $p_t > 100$ MeV
- Resolutions:
 - $1/p_t \rightarrow 2.2\%/GeV$
 - $\vartheta \rightarrow 50$ mrad
 - $\phi \rightarrow 2.5$ mrad

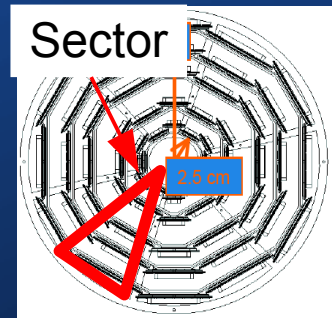


The Silicon Vertex Tracker @ CDF

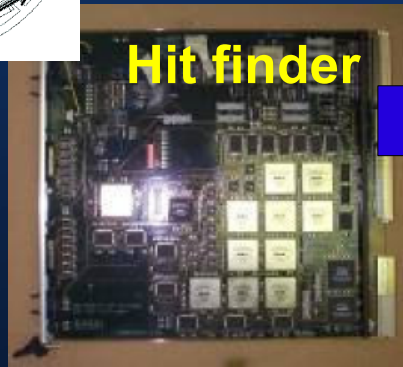
2) PATTERN RECOGNITION w/
custom VLSI Associative Memory
chip

1) HIGHLY PARALLEL

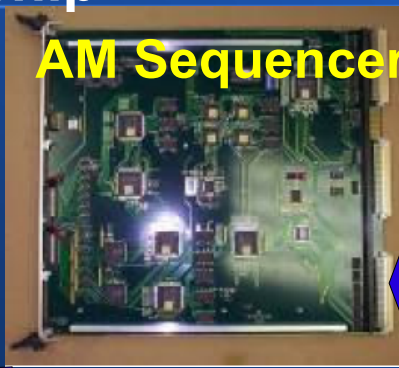
ARCHITECTURE



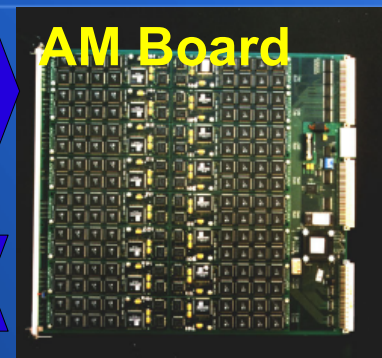
Detector Data



Hits



Matched patterns



Patterns + hits



3) LINEARIZED FIT in fast
FPGA

$$p_i = \vec{f}_i \cdot \vec{x} + q_i$$



L2

- Latency ~ 20 μ s
- eff ~ 80% ($p_T > 2$ GeV, $d_0 < 1$ mm)
- $\sigma_{d0} \sim 35$ μ m
- $\sigma_{pT} \sim 0.003$ pt²
- $\sigma_{\phi} \sim 1$ mrad

SVT (2006)

New AMS

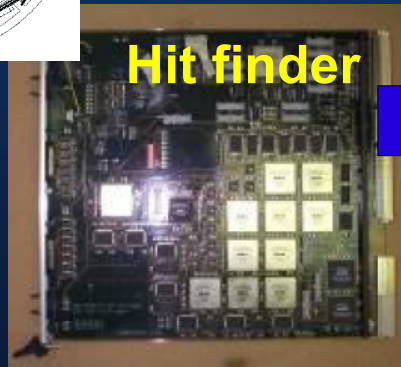
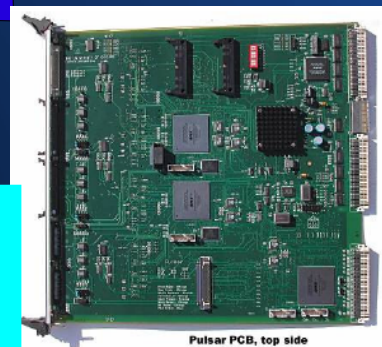
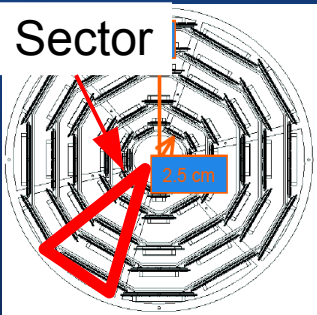
New AM

256 chips
128 patt/chip

128 chips
4k patt/chip

Larger pattern banks
(32k → 512k pattern per
silicon sector)

L2



Detector Data

Hits

Matching patterns

Patterns + hits

A single multipurpose and flexible board (**PULSAR**):

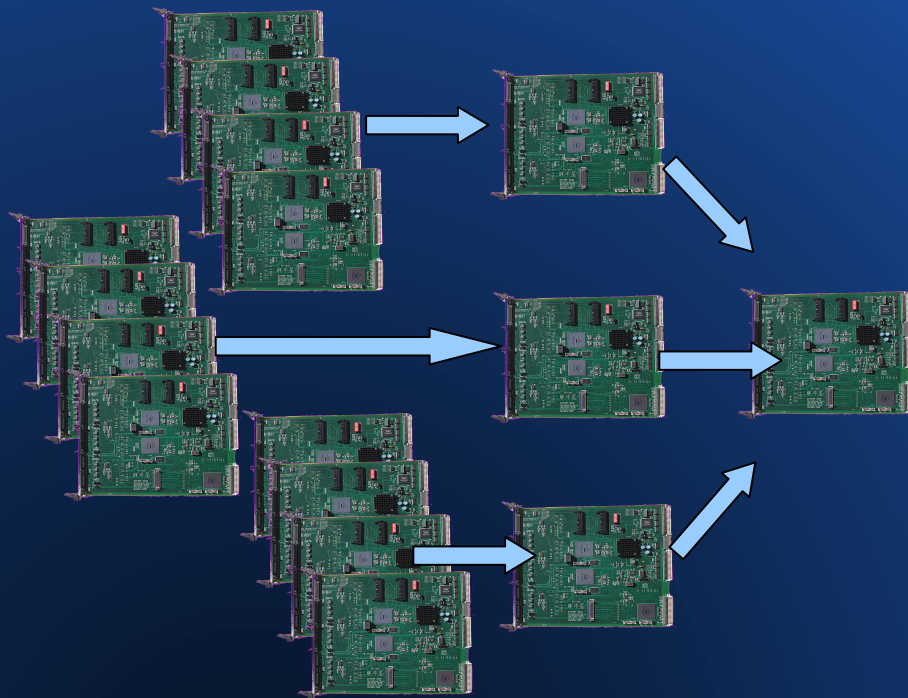
- 3 FPGAs
- Embedded RAM
- Interface w/ any user data through custom mezzanine cards

New Hit Buffer

New Track Fitter

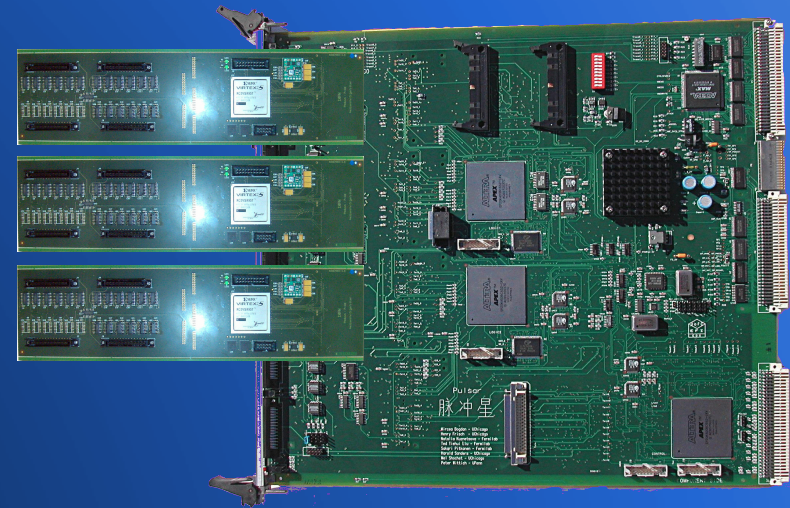
SVT (2010) : the Gigafitter upgrade

Old Track Fitter system



16 boards

New



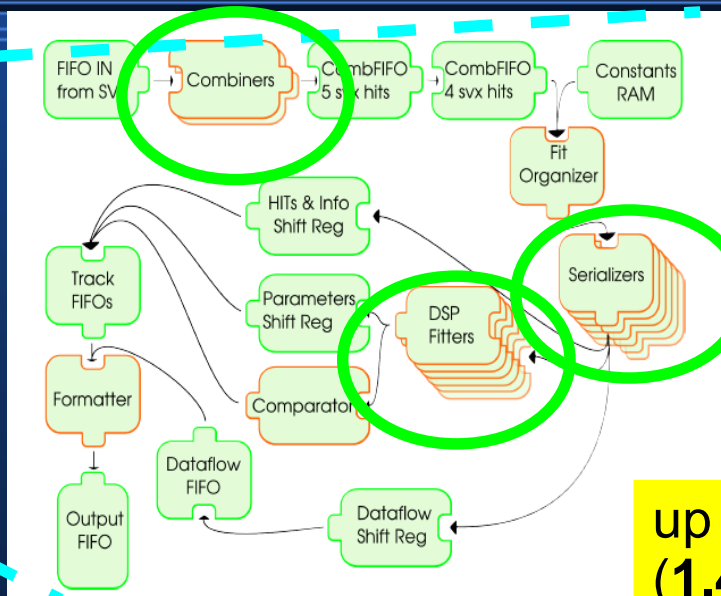
1 Pulsar board + 3 Mezzanine cards
equipped with

Xilinx Virtex-5 FPGA with

- **640 DSP** (25 x 18 bit multiplier + 48 bit adder)
- **8.2 Mb Ram**

The Gigafitter: advantages over the old system

Faster:



640 DSPs → many tasks in parallel

up to **12 fits / clock cycle**
(1.4 fits/ns at 120 MHz internal clock)

More available memory:

- **Extension of the SVT acceptance in track Pt and impact parameter d**

$d < 1.5 \text{ mm} \rightarrow d < 2-3 \text{ mm}$

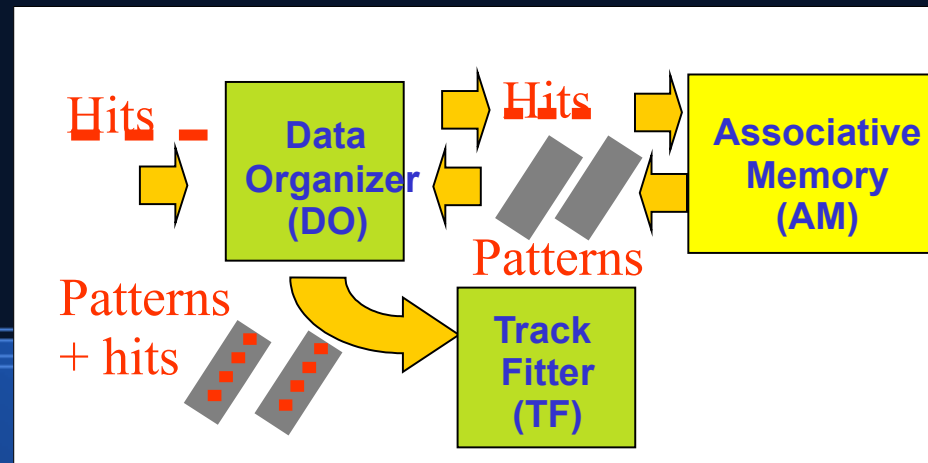
$P_t > 2 \text{ GeV} \rightarrow P_t > 1.5 \text{ GeV}$

Improvement in b-tagging capabilities and lifetime measurements

Fast Tracker (FTK) @ Atlas

Goal: reconstruct offline-like tracks in time for L2 decision @ 100 kHz (L1 rate).

How: adapt SVT (+GF) experience to Atlas

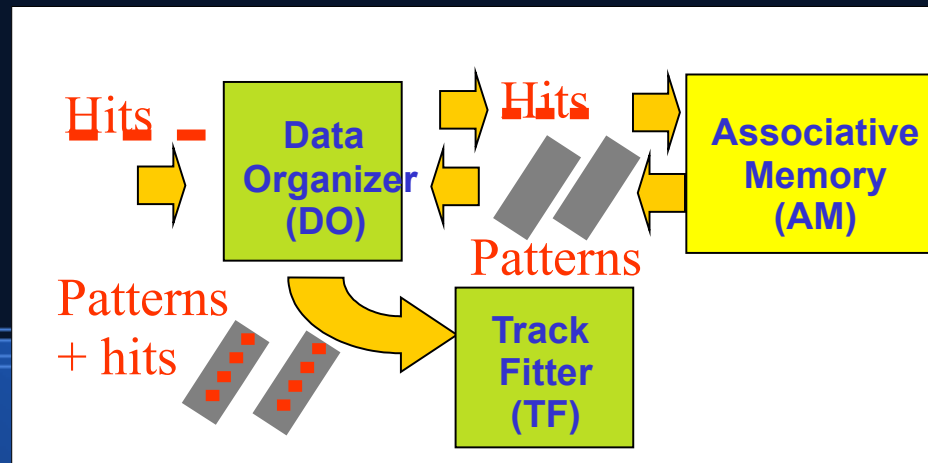


	SVT	FTK
L1 output rate	30 kHz	100 kHz
Detector layers	5	11 (3 pixel+8 SCT)
# patterns	6M	>800M

Fast Tracker (FTK) @ Atlas

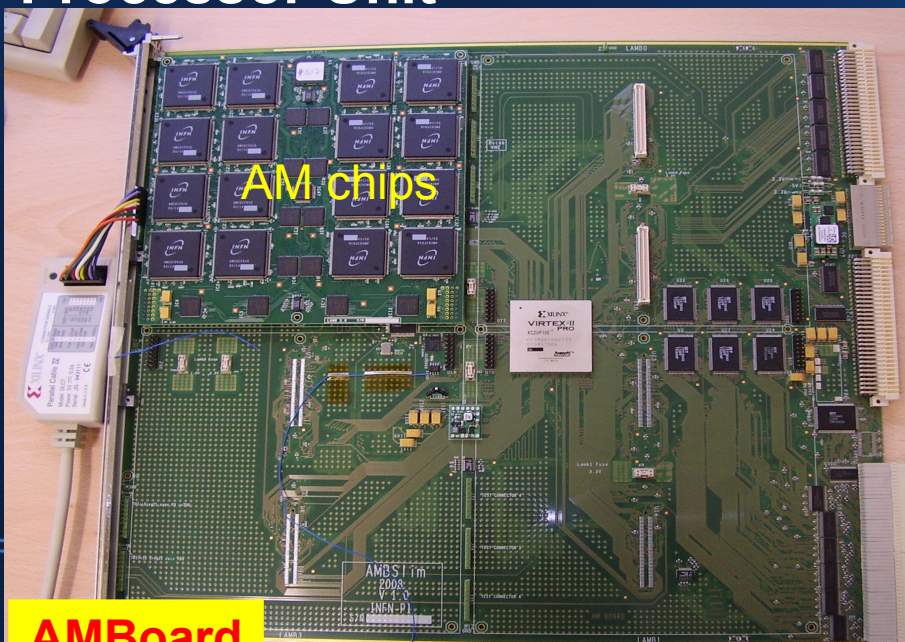
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L1 output rate	30 kHz	100 kHz
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Processor Unit



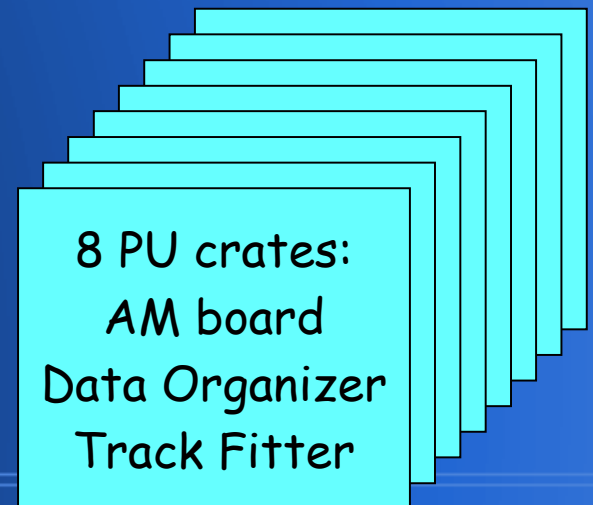
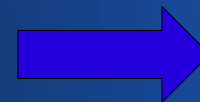
AM chips

AMBoard

AUX card



DO TF

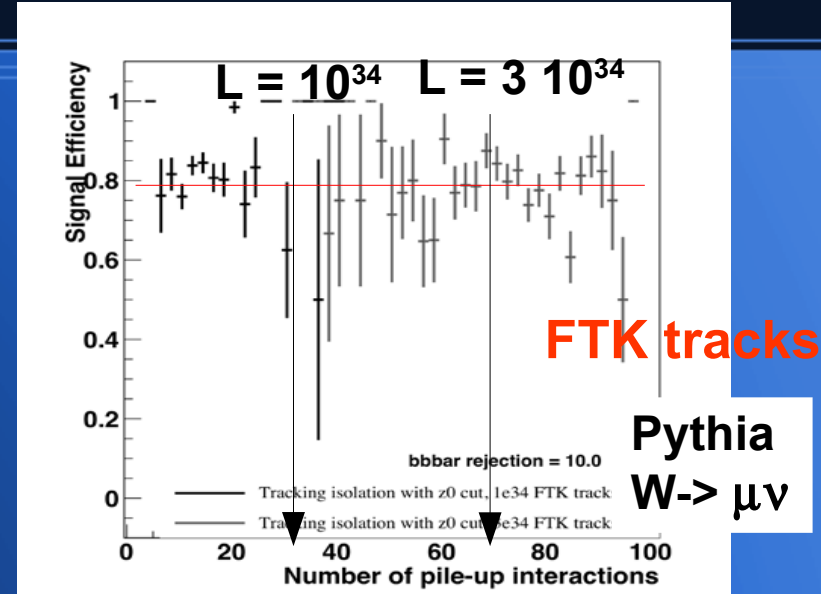
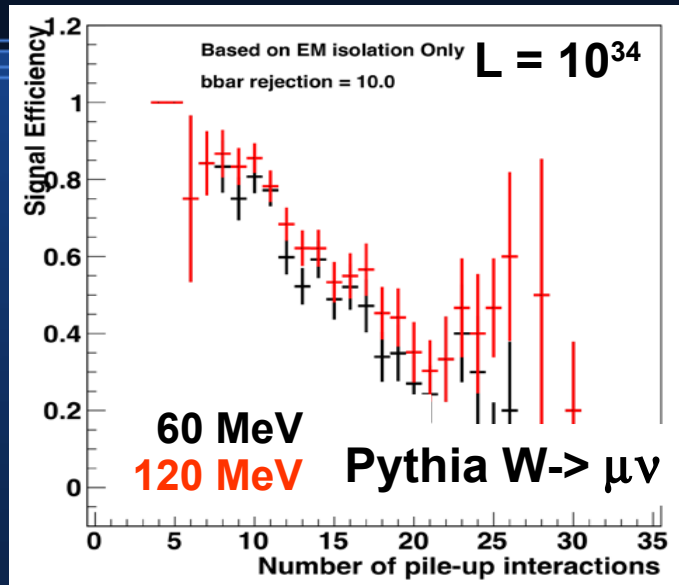


FTK expected performances

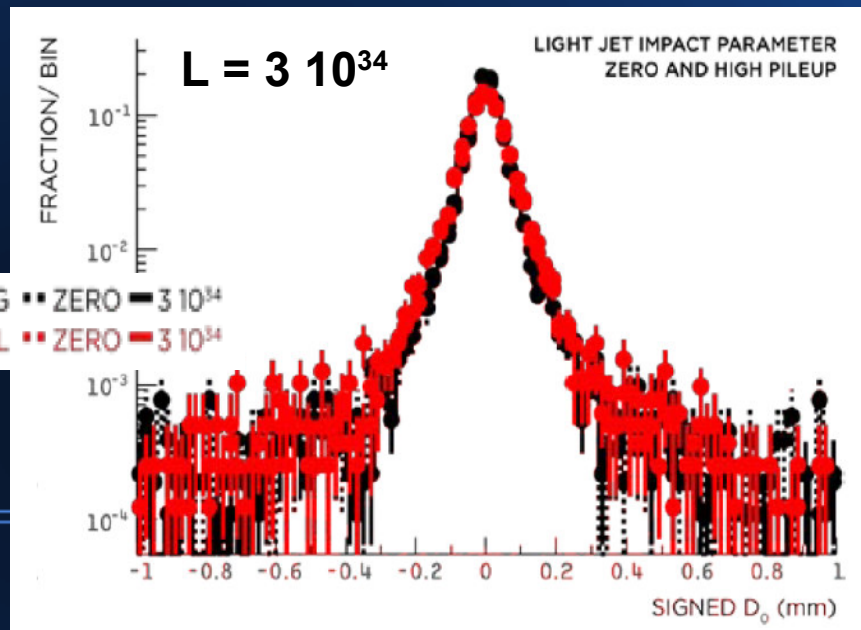
EM calorimeter isolation only

Track isolation (w/ z_0 cut)

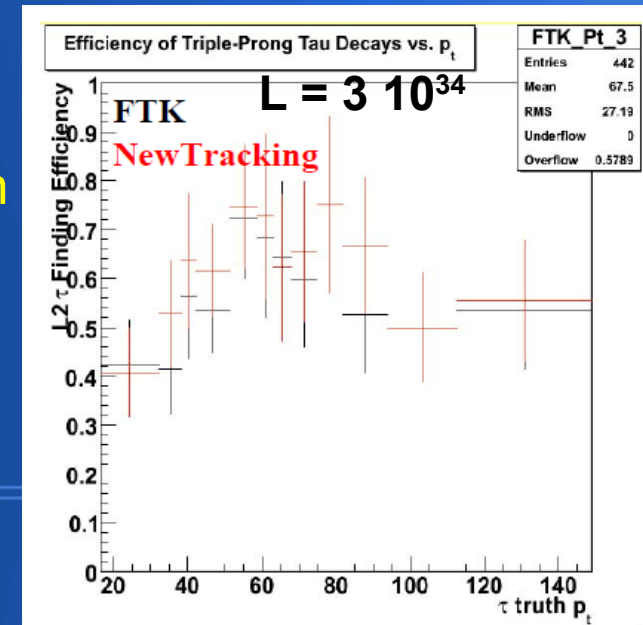
Isolated
muon
triggers



Online
b-tagging

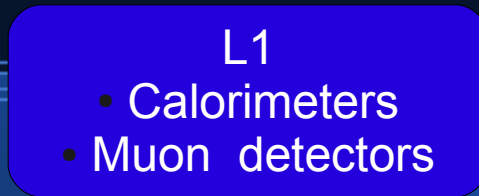


Online tau
reconstruction

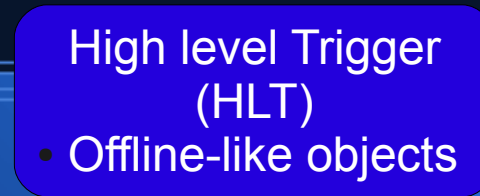


CMS tracking @ L1

LHC



100 MHz, 4 μ s



100 Hz, 40 ms

SLHC

new tracker & new L1 track trigger

Main challenge is data volume: data rates $\sim 10\text{-}20\text{Gb cm}^{-2}\text{s}^{-1}$ to read out a silicon detector layer at 10 cm! *On-detector data reduction is needed.*

CMS tracking @ L1

LHC

- L1
- Calorimeters
 - Muon detectors

100 MHz, 4 μ s

- High level Trigger (HLT)
- Offline-like objects

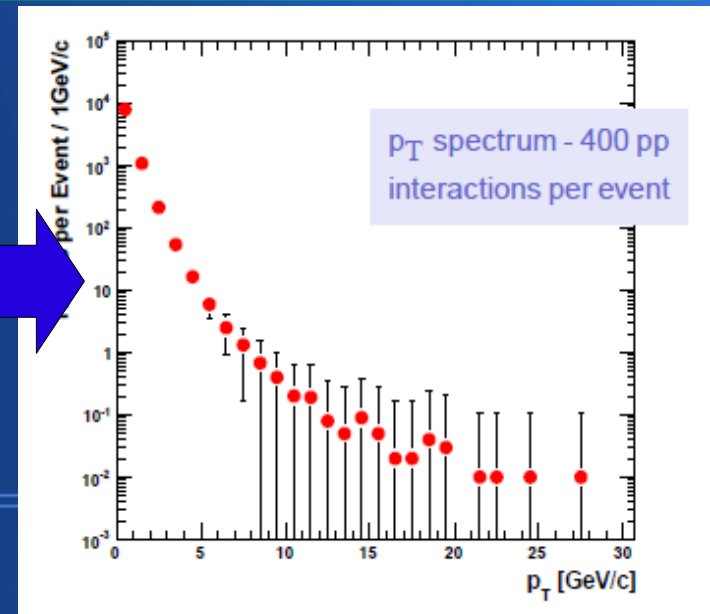
100 Hz, 40 ms

SLHC

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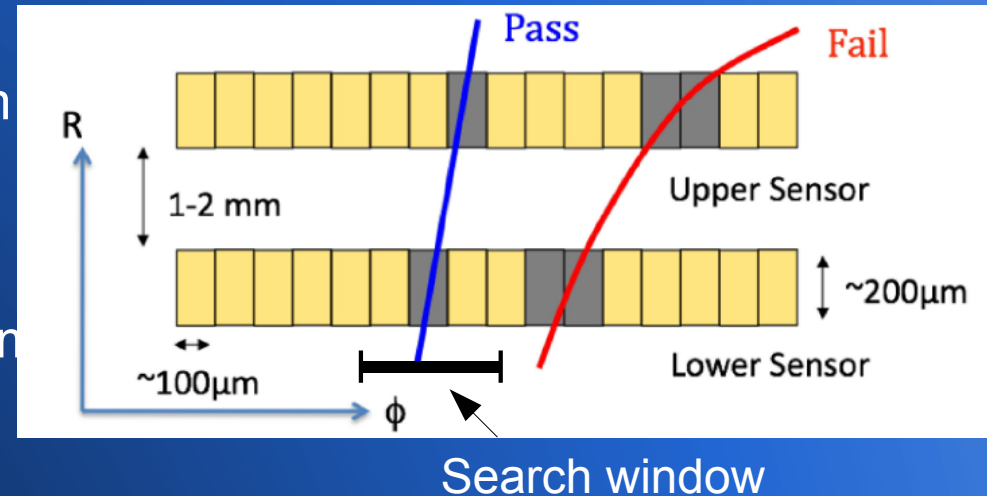
Possible solution: use for L1 decision only tracks with $P_t > 1\text{ GeV}/c$, reject low momentum ones.



CMS tracking @ L1: possible solutions

STACKED TRACKING

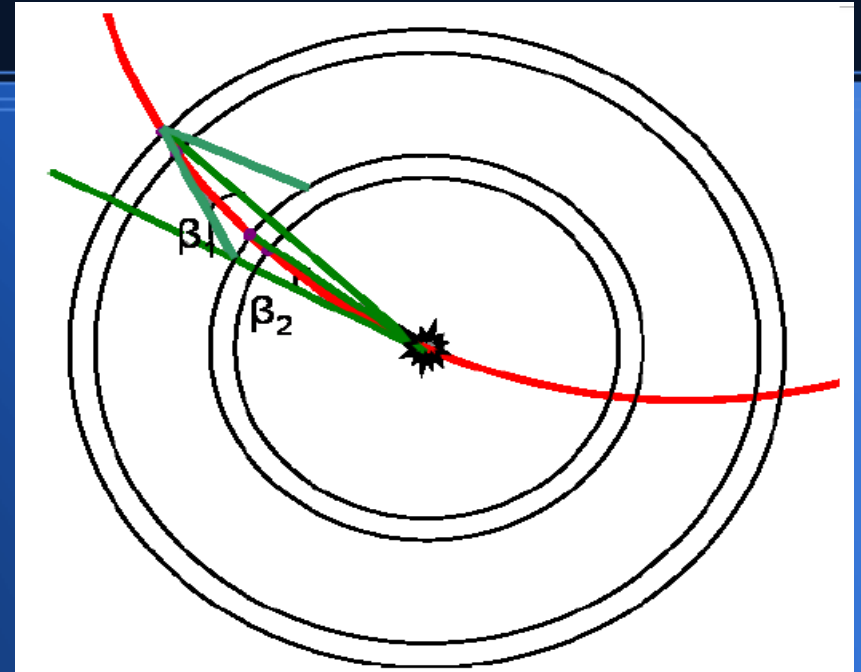
- Correlate hits between closely separated sensors using a simple matching algorithm
- High Pt tracks = hits within a specific search window.
- With multiple sensors pairs, matched hits from different pairs can be correlated to form raw tracks.



CMS tracking @ L1: possible solutions

STACKED TRACKING

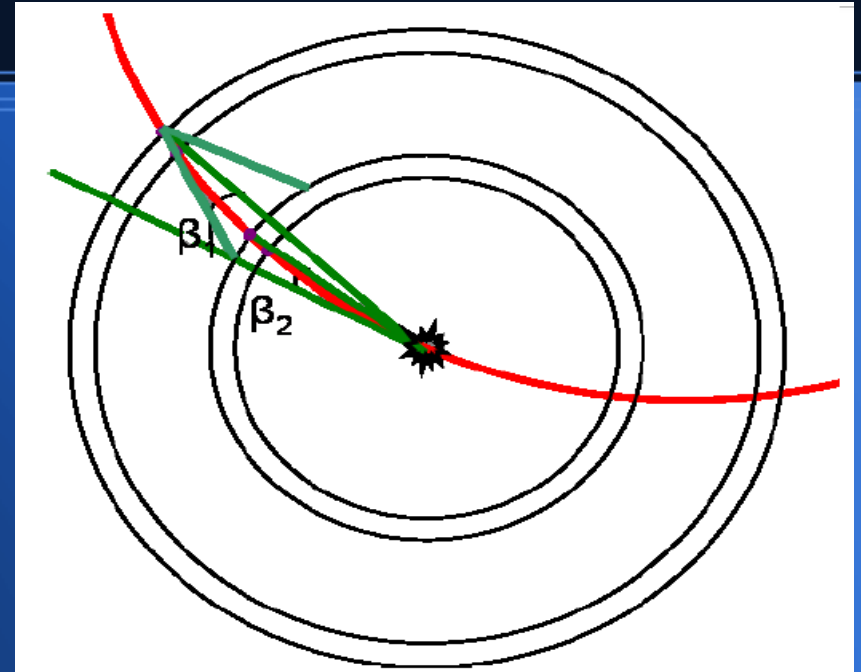
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CMS tracking @ L1: possible solutions

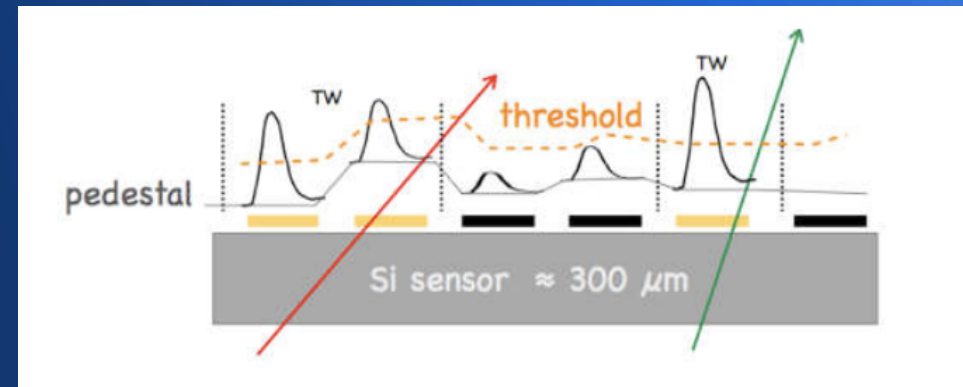
STACKED TRACKING

- Correlate hits between closely separated sensors using a simple matching algorithm
- High Pt tracks = hits within a specific search window.
- With multiple sensors pairs, matched hits from different pairs can be correlated to form raw tracks.



CLUSTER WIDTH DISCRIMINATION

- Four strip sensor layers at radii 25-50 cm.
- Cut on cluster width to reduce data rate.
- Correlate clusters from 3 out of 4 layers using CAM or FPGAs



Conclusions

A good online tracking system is important to increase the physics reach of experiments at hadron colliders.

What do we learn from the past (H1) and the present (CDF)?

The online tracking system has to be

- FAST and EFFICIENT → *data reduction, pattern recognition, parallelism, high density FPGAs*
- FLEXIBLE, to be easily adapted to different luminosity conditions → *multipurpose boards.*

Both CMS and ATLAS are facing the challenge: R&D activity ongoing for SLHC.

References

FTT

- A. Baird et al, *A Fast High Resolution Track Trigger for the H1 Experiment*, arXiv:hep-ex/0104010v1
- D. Meer et al, *A Multifunctional Processing Board for the Fast Track Trigger of the H1 experiment*, arXiv:hep-ex/0107010v1
- A.W.Jung et al, *First Results from the Third Level of the H1 Fast Track Trigger*, Proceedings of 15th IEEE-NPSS Real Time Conference (2007)

SVT

- M.Dell'Orso, L.Ristori, *VLSI Structures for Track Finding*, NIM A278 (1998) 436-440
- J.Adelman et al., *The Silicon Vertex Trigger Upgrade at CDF*, NIM A572 (2007) 361
- S.Amerio et al., *The Gigafitter: Performance at CDF and Perspectives for Future Applications*, 2010 J.Phys.: Conf.Ser. 219 022001

FTK

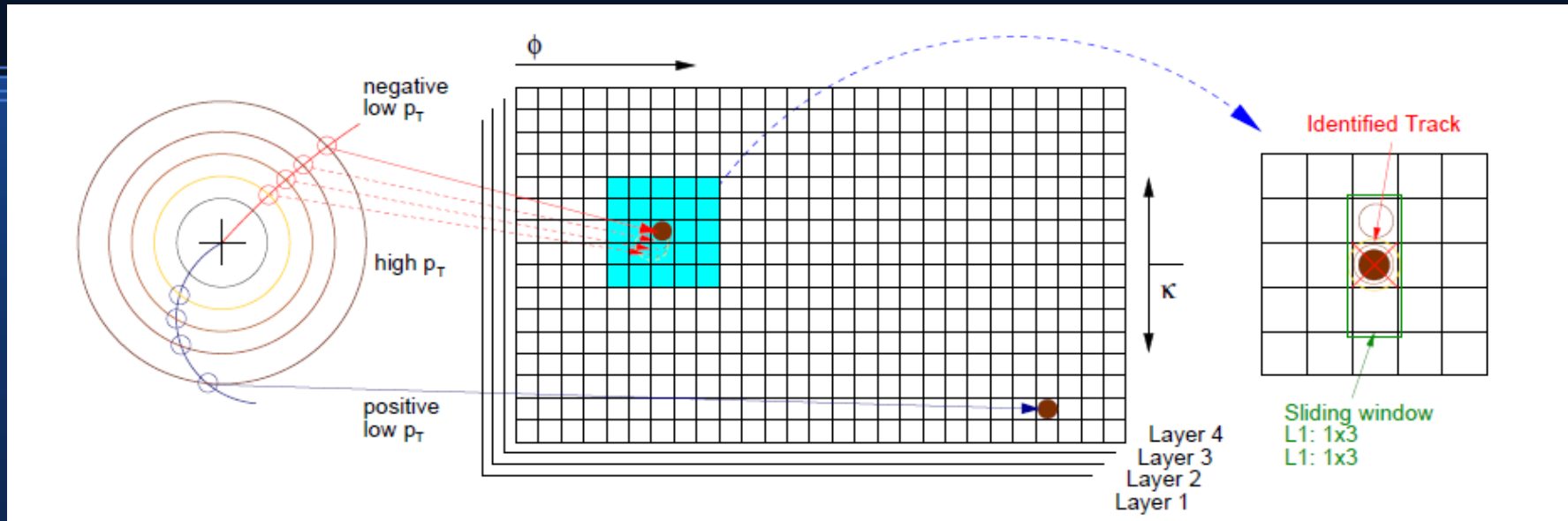
- A.Annovi et al., *Associative memory design for the Fast Track Processor (FTK) at Atlas*
- A.Andreani et al., *The FastTrack Real Time Processor and Its Impact on Muon Isolation, Tau and b-jet Online Selections at ATLAS*, both in Proceedings of 17th IEEE NPSS Real Time Conference, Lisbon, Portugal, 24-28 May 2010

CMS

- G.Hall, *Design of a trigger module for the CMS tracker at SLHC*, Proceedings of TWEPP-09
- F. Palla, *Proposal for a First Level Trigger using Pixel Detector for CMS at Super-LHC*, 2007 JINST 2 P02002
- J. Jones et al, *A Pixel Detector for Level-1 Triggering at SLHC*, arXiv:physics/0510228 ²⁶

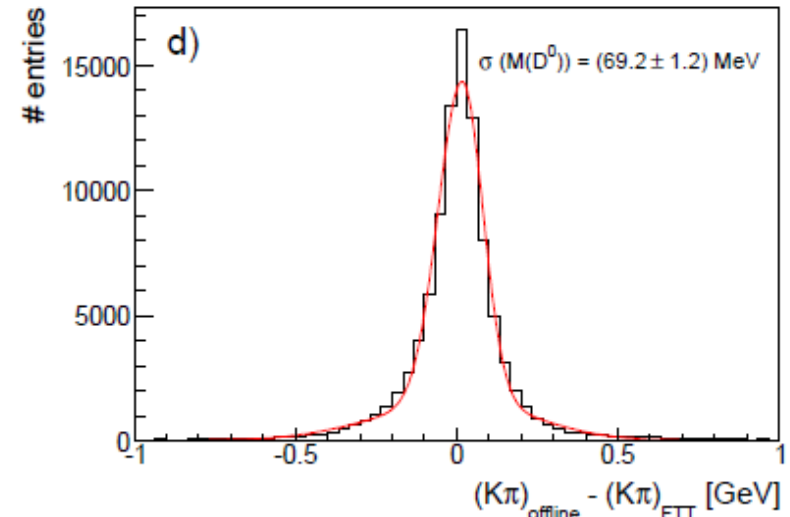
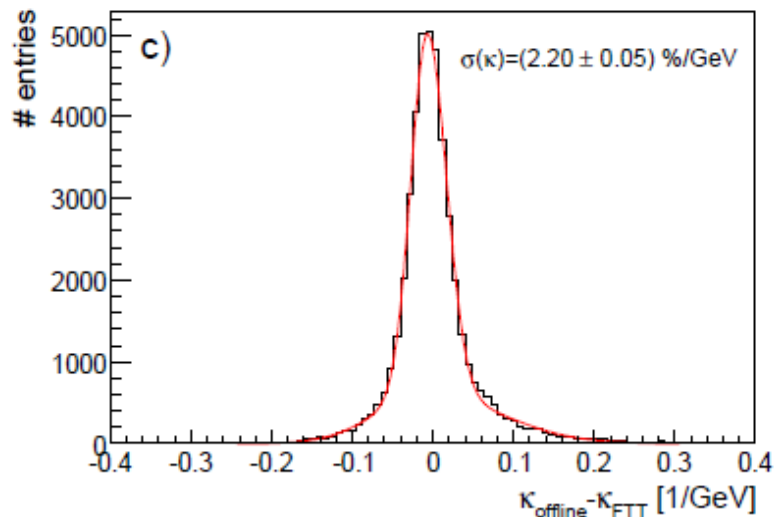
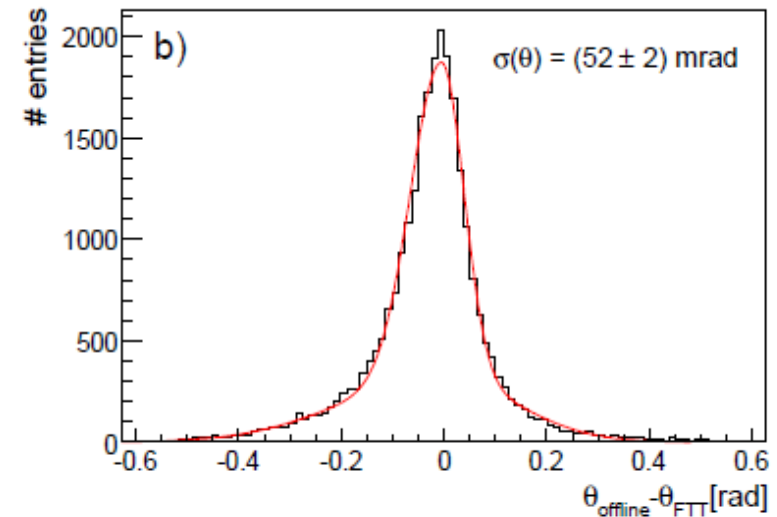
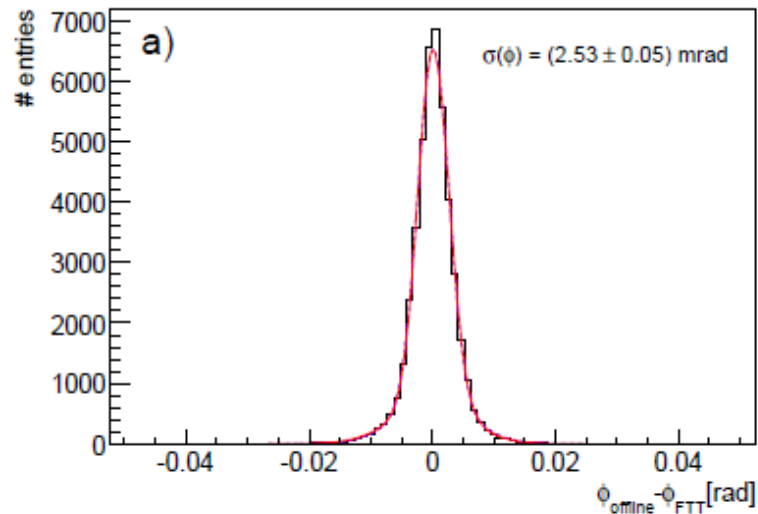
BACKUP

FTT track linking and fit

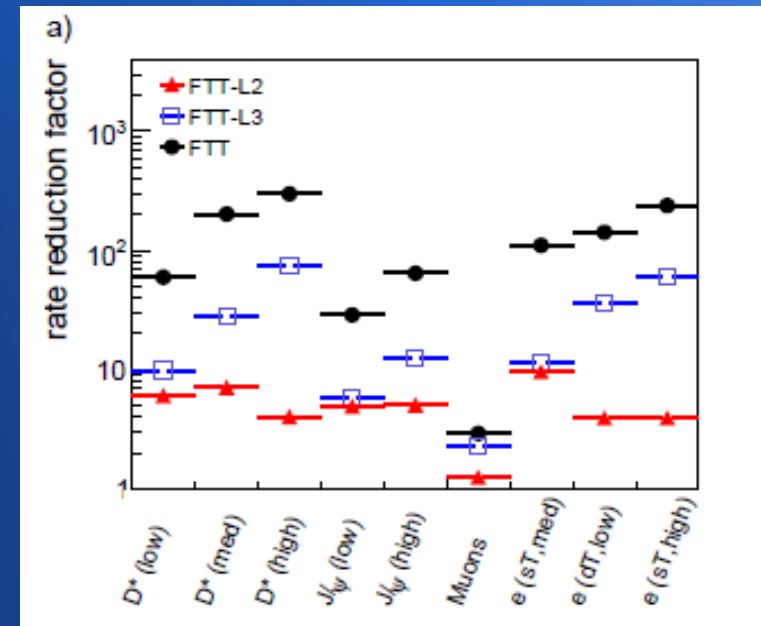
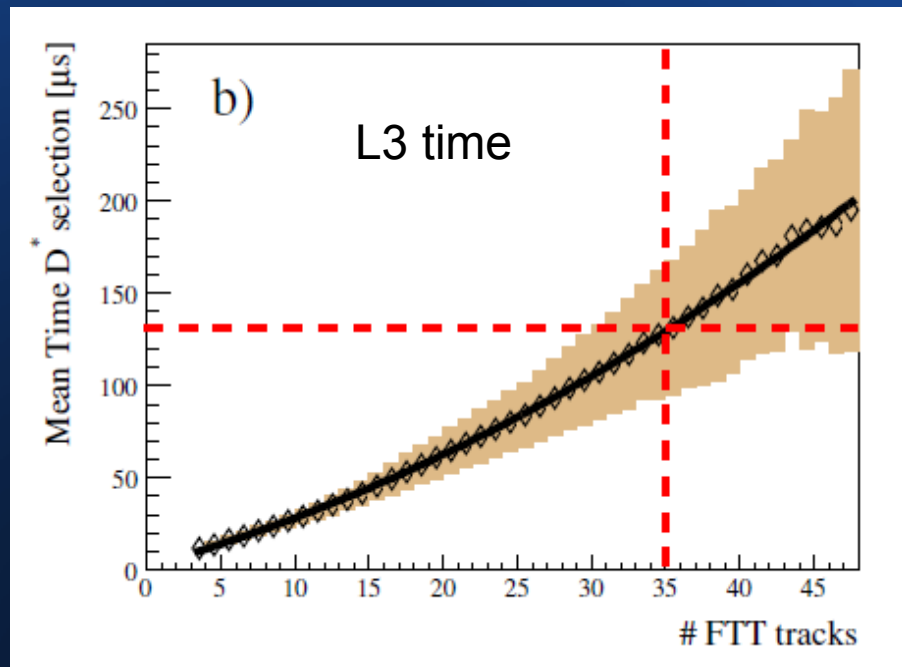


- Track segments from the 4 trigger layers are filled into four corresponding k - ϕ histograms (size 16 x 60 @ L1, 60 x 640 @ L2).
- A sliding window technique is used to link track segments to tracks: coincidence of at least 2 out of 4 trigger layers.
- @ L2 the track is fitted. A primary vertex constraint is applied. Each DSP performs up to 2 track fits.

FTT L2 track resolution

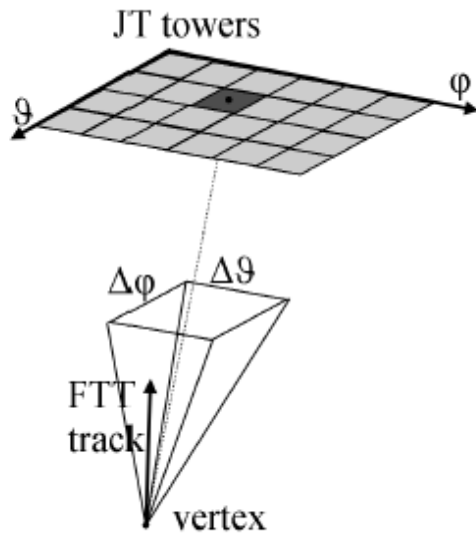


FTT timing and reduction rate

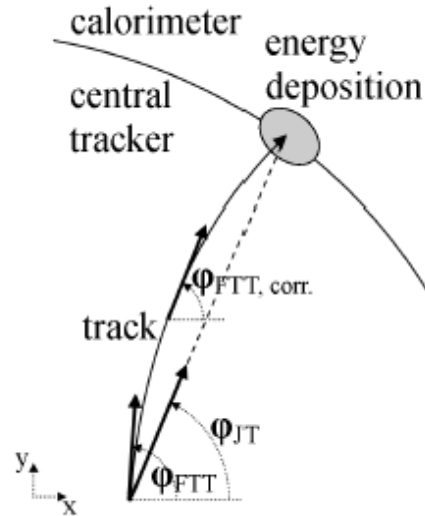


Rate reduction factors

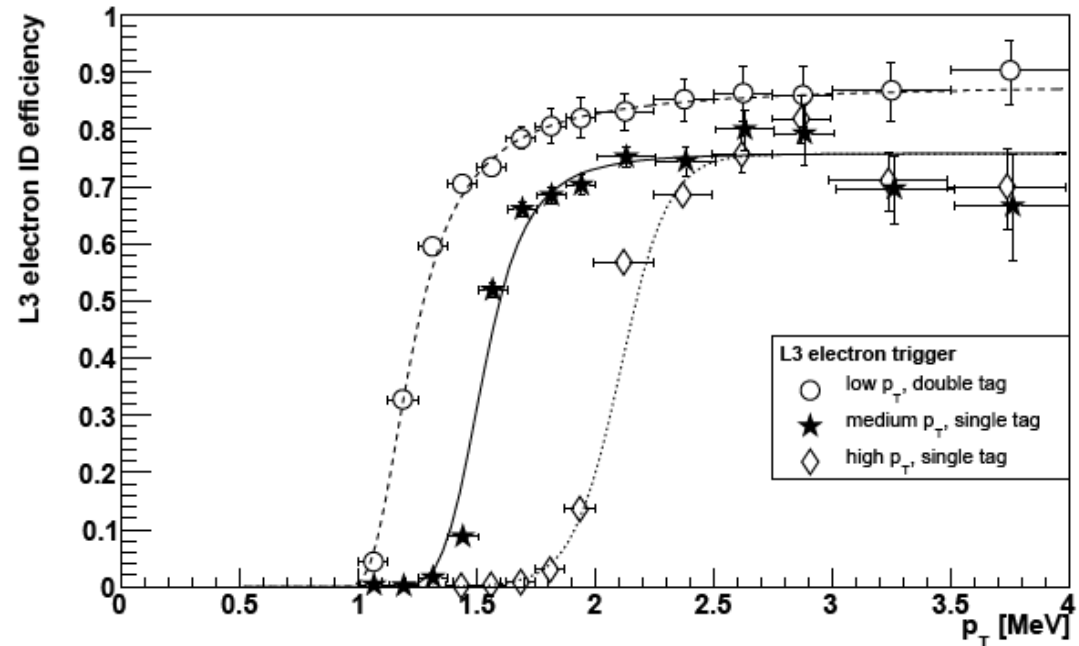
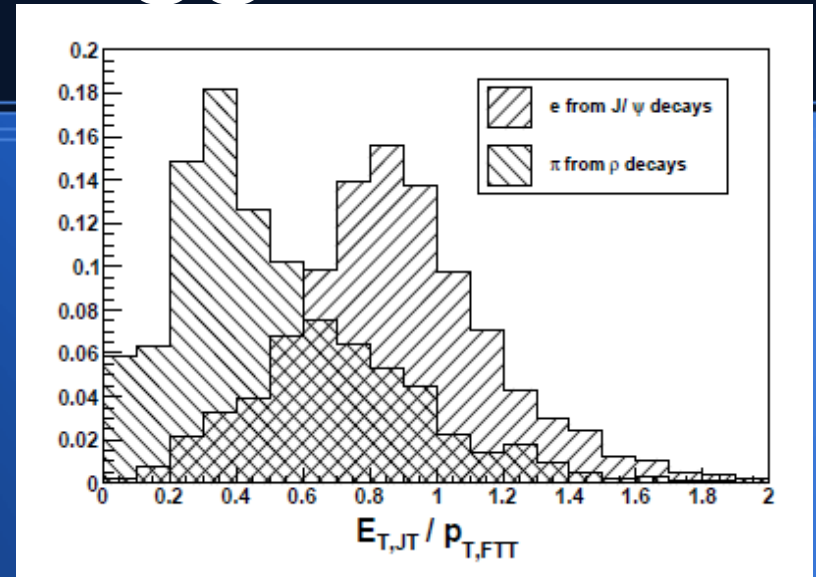
FTT electron trigger



(a)



(b)



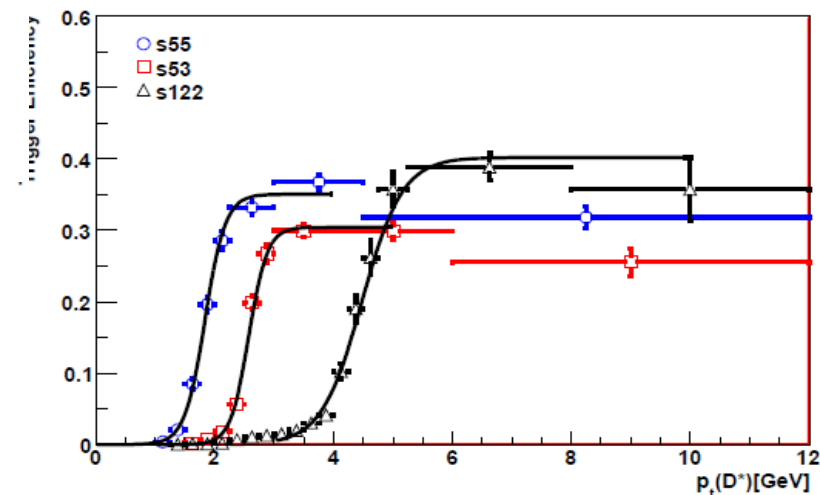
D* reconstruction @ H1

Subtrigger	triggerelement	definition
	level 1	
s55, s53, s122	cipmul>4 & cipsig>2 & FTT_mul_Ta>5 & FTT_mul_Tc>2 & FTT_mul_Td>1 & FTT_mul_Te>0	$N(ctr) + N(bwd) + N(fwd) > 10$ $N(ctr) > 2 \cdot (N(bwd) + N(fwd))$ #tracks > 5, with $p_t > 100\text{MeV}$ #tracks > 2, with $p_t > 400\text{MeV}$ #tracks > 1, with $p_t > 900\text{MeV}$ #tracks > 0, with $p_t > 1.8\text{GeV}$
	level 2	
s55	& FTT_Et_1 & FTT_mul_Te>1 & FTT_zVtx>2	total transverse energy > 5.0GeV #tracks > 1, with $p_t > 900\text{MeV}$
s53	& FTT_Et_2 & FTT_mul_Te>1 & FTT_zVtx>2	total transverse energy > 6.5GeV #tracks > 1, with $p_t > 900\text{MeV}$
s122	& FTT_mul_Te>1 & FTT_zVtx>2	#tracks > 1, with $p_t > 900\text{MeV}$
	level 3	
s55	& low_pt_D*_untagged	$p_t(D^*) > 1.5\text{ GeV}$ with $\Delta M \leq 180\text{ MeV}$
s53	& medium_pt_D*_untagged	$p_t(D^*) > 2.5\text{ GeV}$ with $\Delta M \leq 180\text{ MeV}$
s122	& high_pt_D*_untagged	$p_t(D^*) > 4.5\text{ GeV}$ with $\Delta M \leq 280\text{ MeV}$

- Trigger efficiency vs D* pt for 3 different triggers (low, medium and high transverse momenta)

@L3:

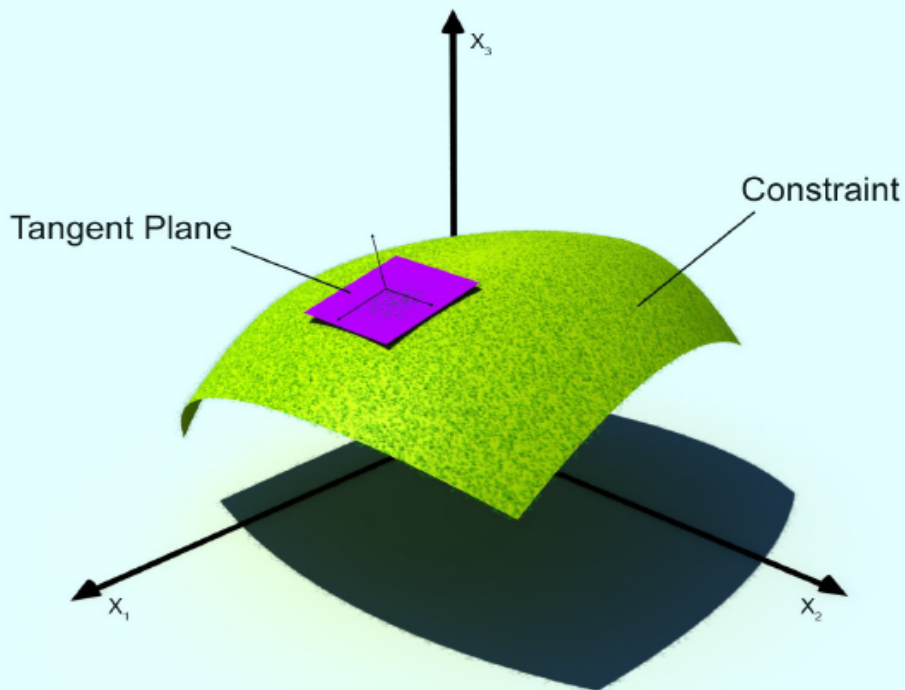
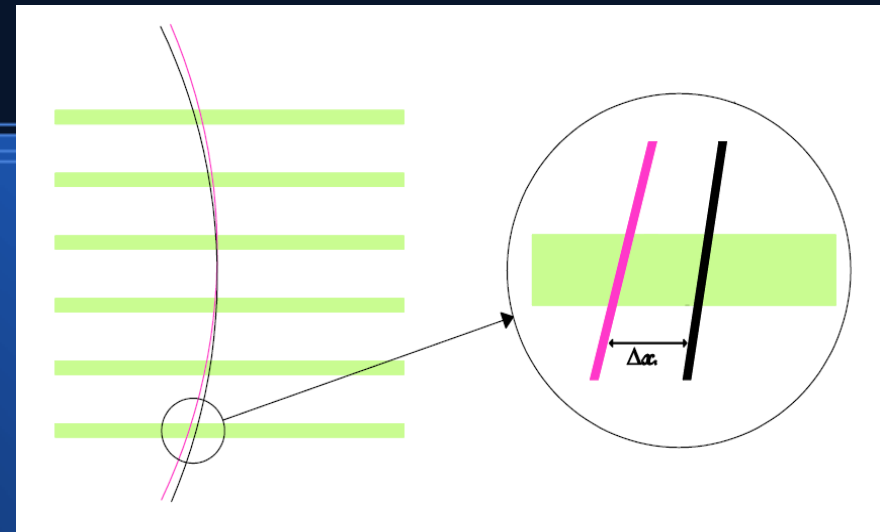
- 2 tracks with mass consistent with D0 meson mass
- 3rd track corresponding to π^+ mass
- Mass difference (around 145 MeV)



SVT – Track Fitter

Non linear geometrical constraint for a circle $\rightarrow F(x_1, x_2, \dots) = 0$

For small displacements $\rightarrow F(x_1, x_2, \dots) \sim a_0 + a_1 \Delta x_1 + a_2 \Delta x_2 \dots$
($a_i = \text{constant}$)



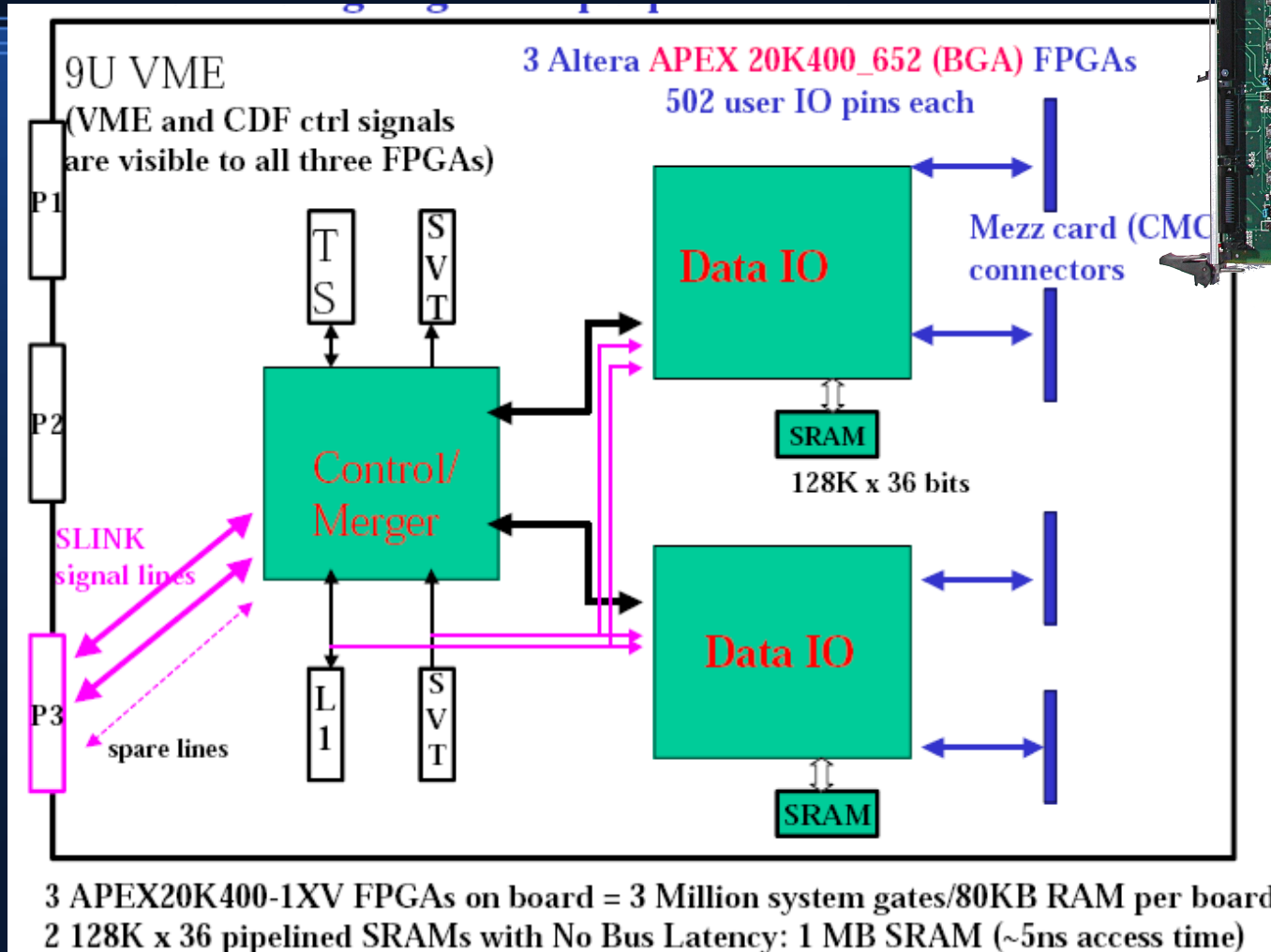
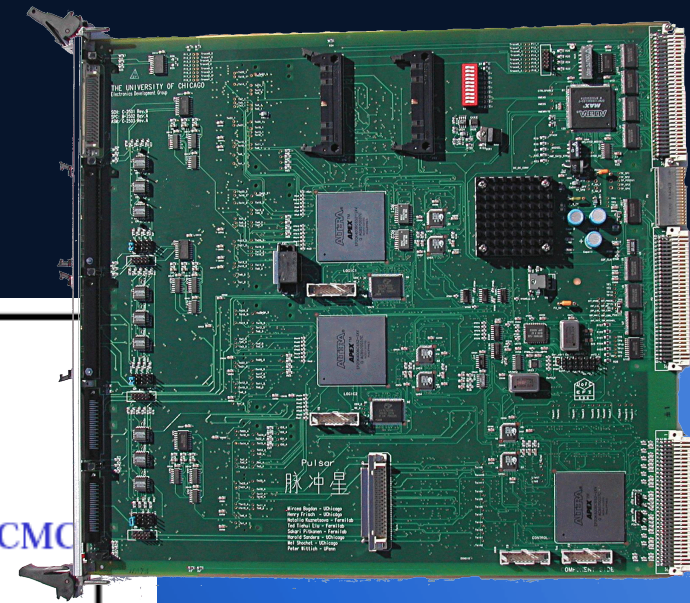
6 coordinates (4 SVX hits + Pt and Phi from XFT) – 3 parameters to fit \rightarrow 3 constraints that can be locally linearized

Track parameters \rightarrow

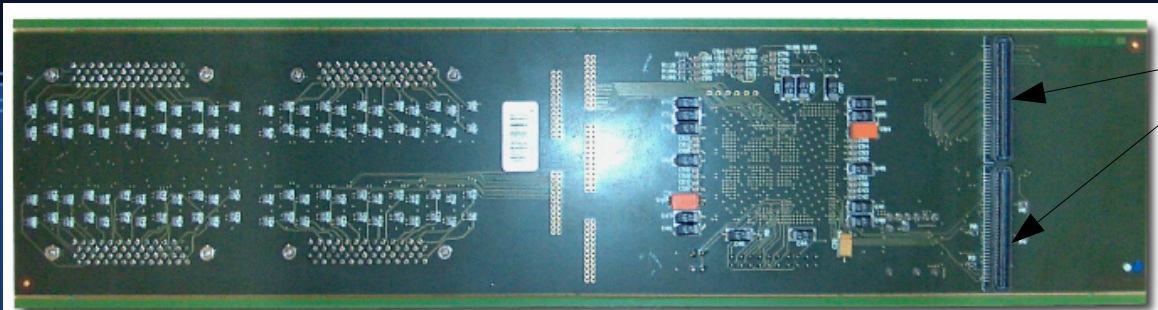
$$p \sim c_0 + \sum_{i=1,6} c_i x_i$$

A single set on constants c_i is good for a whole detector wedge (30° in ϕ)

The Pulsar board

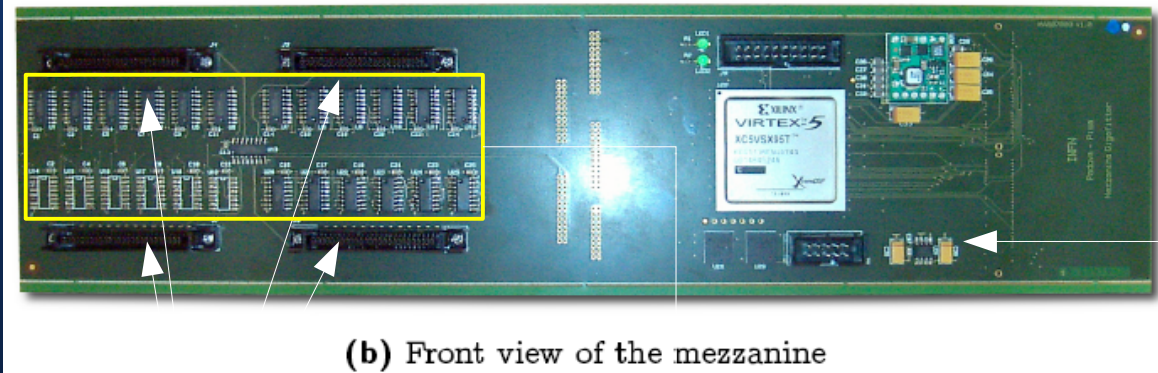


The GF mezzanine



(a) Back view of the mezzanine

Interface with the Pulsar based on 2 64 pins PMC IEEE 1386 connectors



(b) Front view of the mezzanine

EEPROM to program the FPGA at every startup

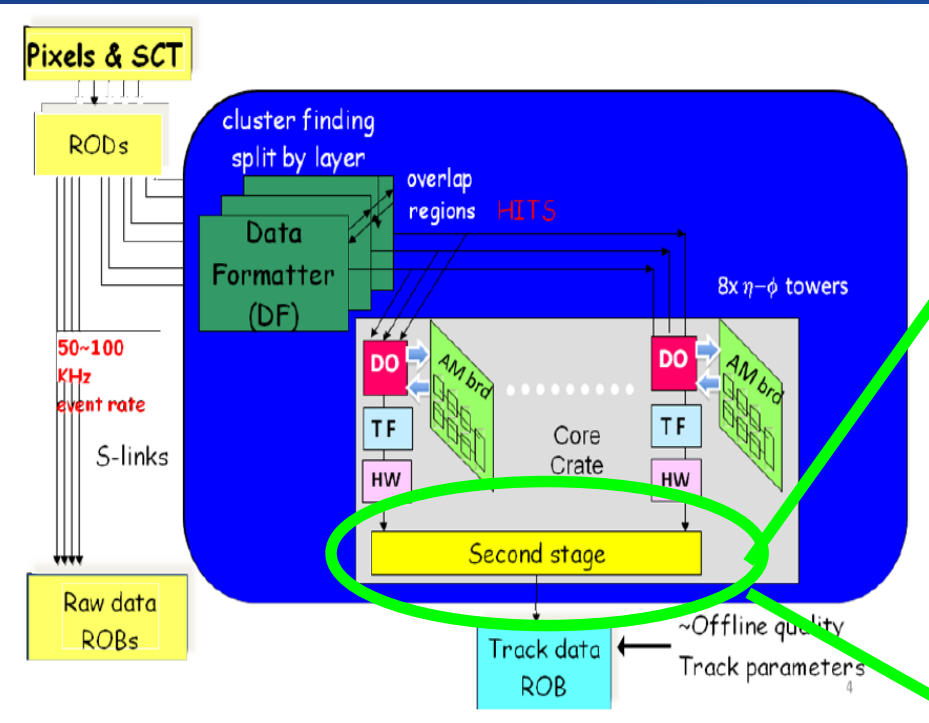
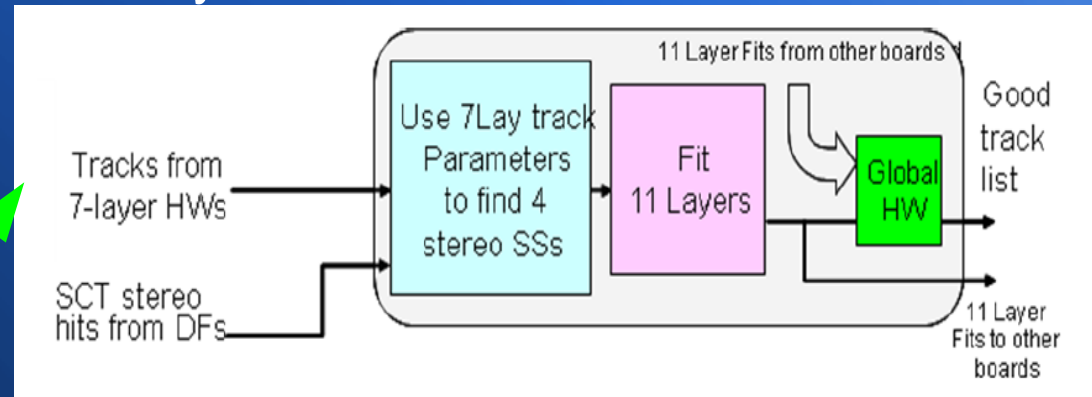
Connectors (52 pins KEL_8830E-052-170S) to receive the SVX+ XFT inputs

24 receivers and 1 driver to allow the translation from LVDS to TTL signals

FTK architecture

Option A:

- Pattern matching w/ 3 pixel + 4 SCT axial layers.
- Chi2 cut --> extrapolation into the SCT stereo layers
- 11-layers fit



Option B:

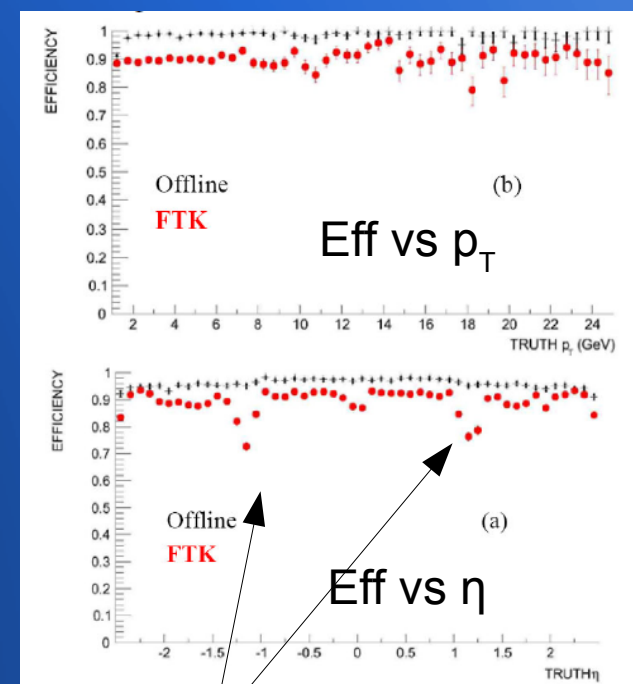
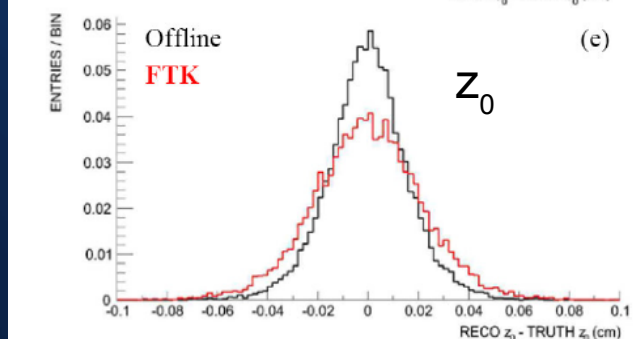
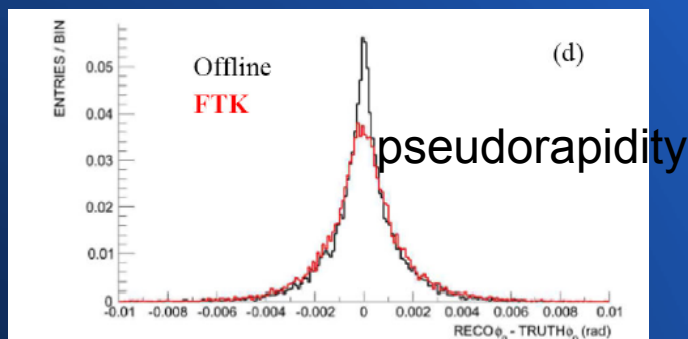
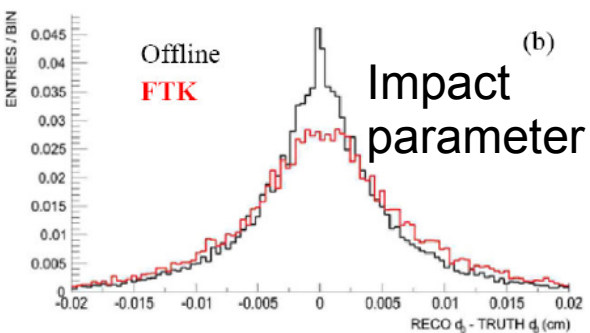
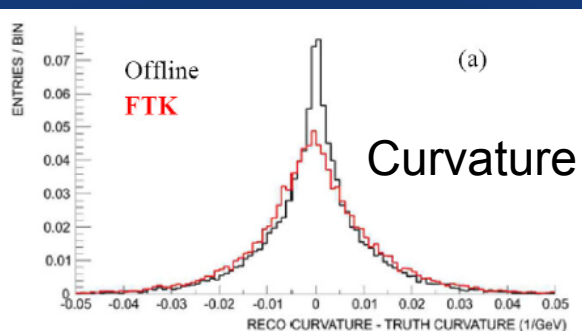
- Pattern matching w/ 8 SCT layers
- Chi2 cut --> track = "pseudohit"
- 4 layers AM (pseudohit + 3 pixel layers)
- 11-layers fit

Pattern matching and track fitting with 11 layers not feasible at high lumi ($3 \times 10^{34} \text{cm}^{-2}\text{s}^{-1}$): AM size and # of fits increase rapidly with the number of layers.

Need to divide the track reconstruction in 2 stages.

FTK expected performances (I)

Single track efficiency and resolution

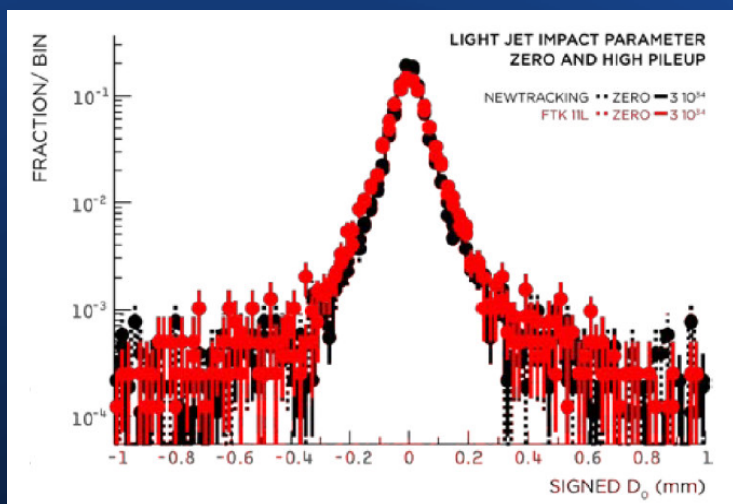


Single muon events, no pile-up
FTK settings to be used at high lumi.

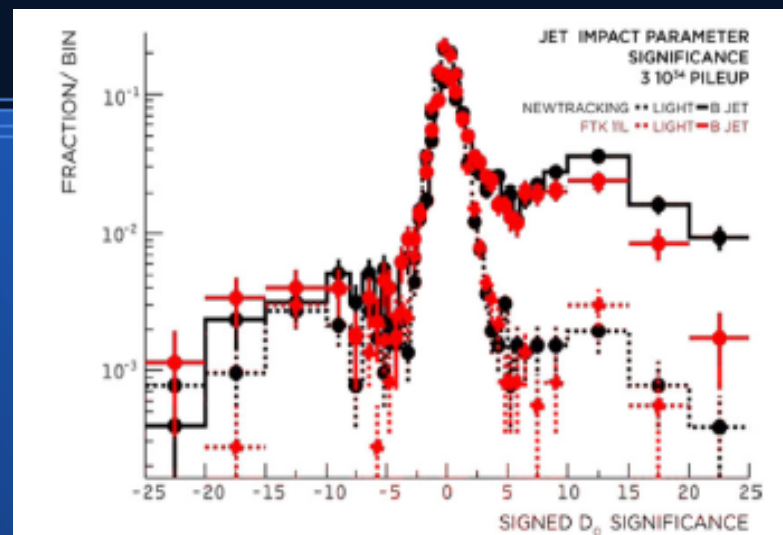
Drop in efficiency
between barrel and
forward regions

FTK expected performances (II)

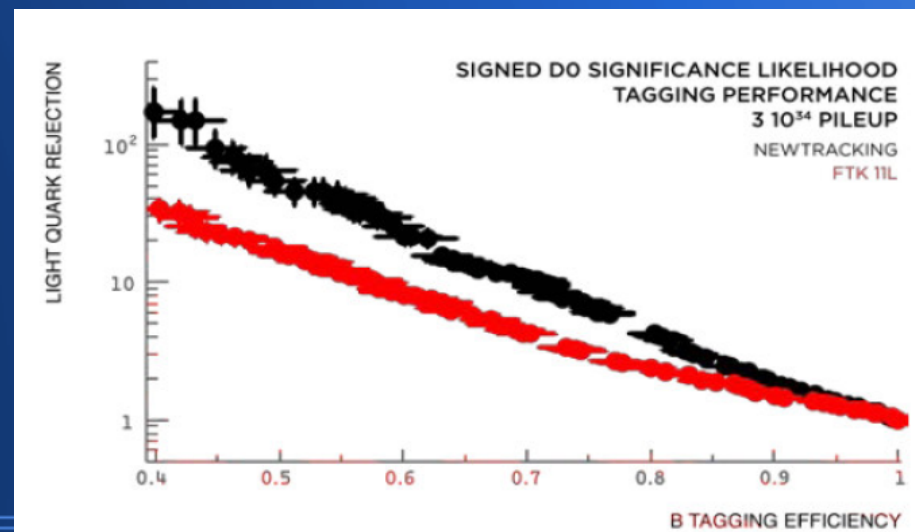
B-tagging



Impact parameter for tracks in light quark jets.



Impact parameter significance for b- and light jets.

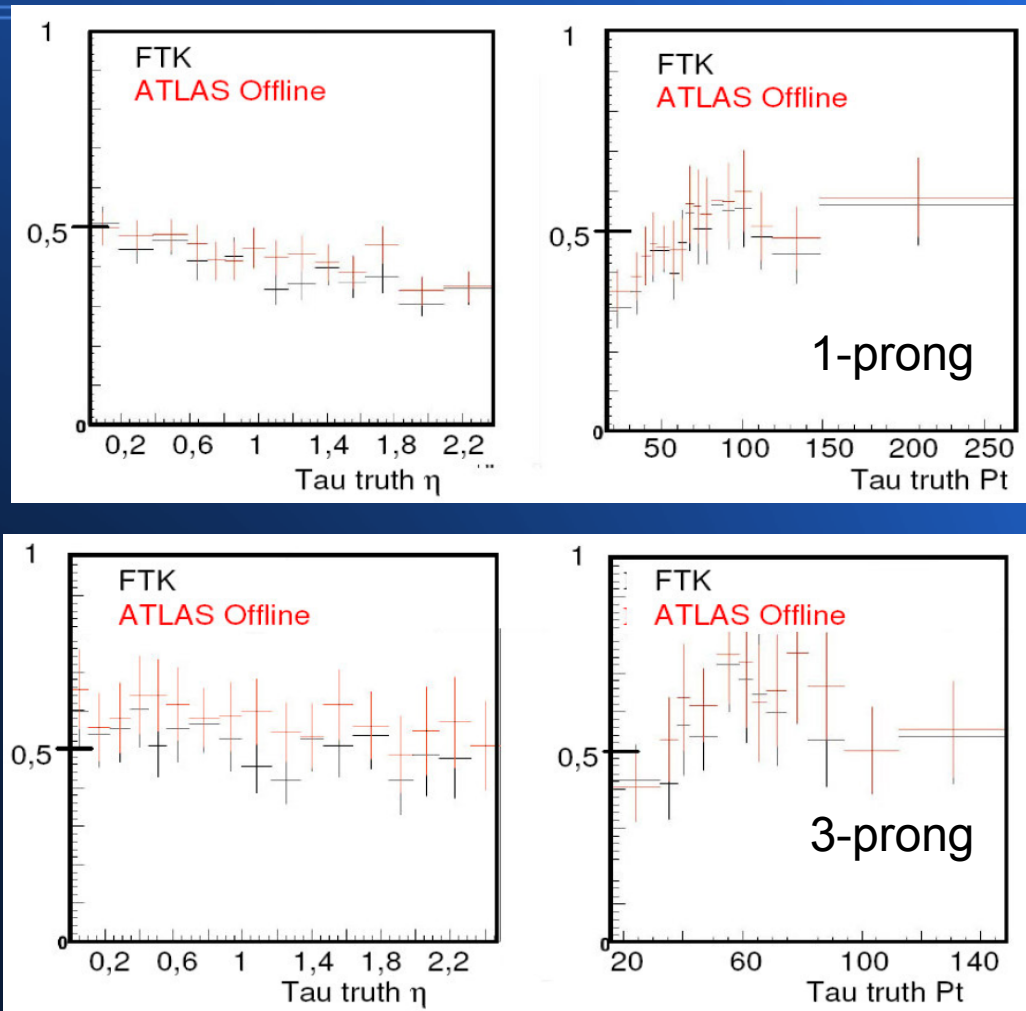


Light quark rejection vs b-tagging efficiency

WH sample ($M_H = 120$ GeV, $H \rightarrow bb/uu$)
 Offline cuts for very high lum: $N_{\text{hits}} \geq 9$,
 $N_{\text{pixel holes}} = 0$, $N_{\text{SCT holes}} \leq 2$, $|d_0| < 1$
 mm, $|z_0| < 15$ cm)

FTK expected performances (III)

Tau reconstruction



Vector-boson-fusion Higgs \rightarrow $\tau_{\text{had}} \tau_{\text{had}}$

CMS stacked tracker module

Pixel size = $100\ \mu\text{m} \times 2.5\ \text{mm}$
1 module = 256 rows \times 32 columns
Active sensor size = $25.6\ \text{mm} \times 80\ \text{mm} = 8192$ pixels

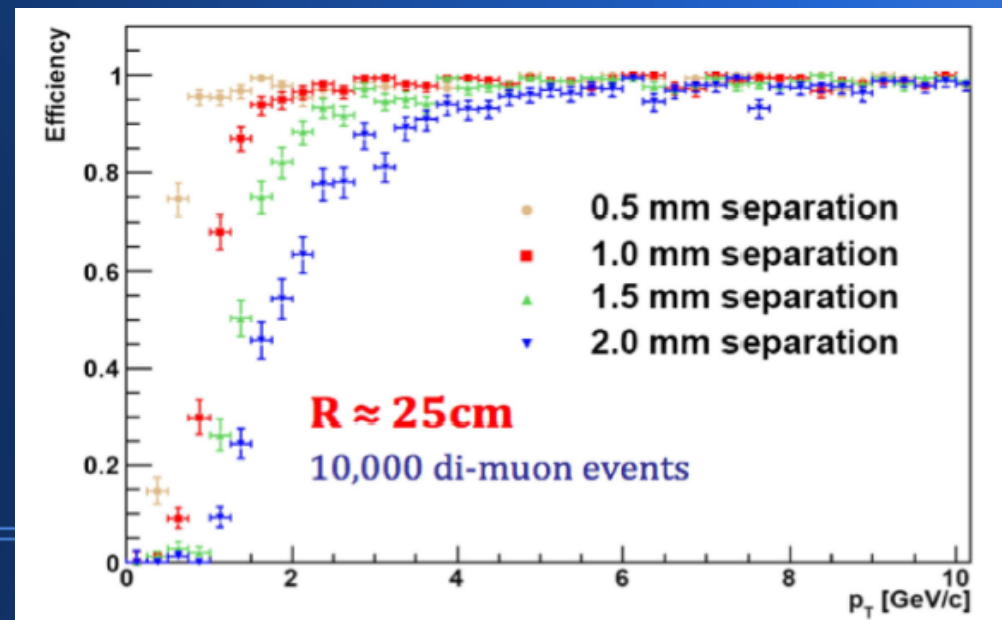
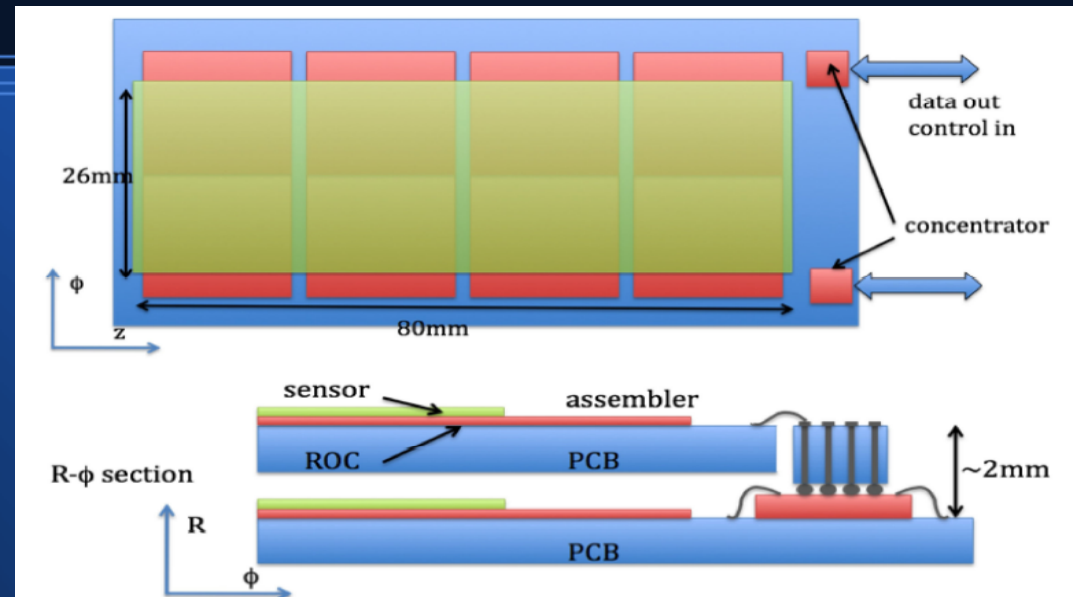
Sensors thickness = $200\ \mu\text{m}$

Read out from a column of 128 pixels

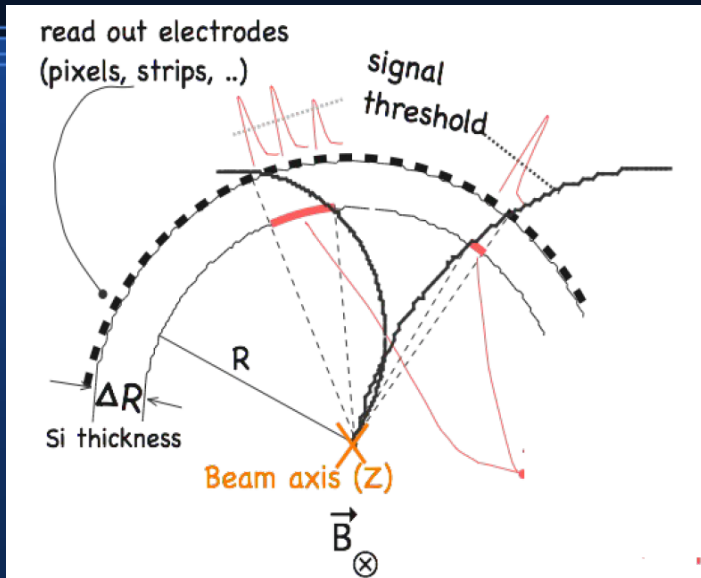
Readout Asic = 128 channel front-end element + assembler where comparison of patterns between the two layers are made.

High speed radiation hard bidirectional optical links

Power consumption: $250\ \mu\text{W}/\text{channel}$,
 $10\ \text{kW}$ for 40M pixels at 25 cm radius



CMS L1 tracker based on cluster width discrimination



4 layers between $R = 25$ cm and $R = 50$ cm

Hybrid pixel modules equipped with radiation hard fibers

Independent engines working on different azimuthal sectors

Each engine receives hits from each layer and produces track candidates using Associative Memory.

25kpatterns per engine for tracks with $P_t > 5$ GeV/c

To sustain data flux from the detector, 40 AM chips per engine working in parallel on 40 events at the same time.

160 boards with 40 AM chips (new generation) each.