



DC-DC Conversion Powering Schemes for the CMS Tracker at Super-LHC

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- Higher detector granularity \rightarrow more readout channels
- More functionality: track trigger to preserve 100kHz trigger rate
- Lower operating voltages (250nm \rightarrow 130nm ...) \Rightarrow larger currents for same power
- Must cope with todays Tracker services, incl. power cables
- Decreasing material budget is the best/only way to improve performance

A novel powering scheme will be needed \Rightarrow Serial Powering or DC-DC conversion

In a review process, the CMS tracker has chosen **DC-DC conversion as baseline solution**, and maintains Serial Powering as back-up.

Reasons: simpler, closer to todays parallel powering scheme, less system issues



DC-DC Conversion



- Tracker needs kWs of power at a low voltage (1.2V) \rightarrow I = kAmps
- P = U x I = (rU) x (I/r) \Rightarrow supply power at higher voltage, but lower current \Rightarrow lower Ohmic losses P_{cable} = R_{cable} · (I/r)², and less copper in detector volume
- DC-DC step-down converters transform $V_{in} = rV_{out}$ to V_{out} , with **conversion ratio r**
- Based on inductors or switched capacitors ("charge pump")
- Focus here on **buck converter**: simplest inductor-based step-down converter few components, high r, efficiency ~80%, sev. Amps, regulated by feedback loop via PWM





Requirements for CMS Stacked Layers



Quantity	Requirement	Comments
Radiation level	Fast hadron fluence: ~9x10 ¹⁵ /cm ² ; Dose: ~1.3MGy	For R > 20cm, z < 3m, 5000fb ⁻¹ , safety factor of 2
Output voltage	$V_{ana} = 1.2V$ $V_{dig} = 0.9V$	Assuming 130 or 90nm (+ $V_{opto} = 2.5V, 1.5V$)
Output current	3-5A	\rightarrow 2 converters per double module
Conversion ratio	Up to 10:1, depends on proposal	Max. current in cable channels 15kA Assuming ~100kW & 80% efficiency
Efficiency	70-80%	Losses need to be cooled
Conductive noise (DM, ripple)	Depends on PSRR of the ROC (still to be studied); but f _s well below (or ideally above) system susceptibilty, i.e. ~ 1MHz	Can be filtered
Common mode noise	? As low as possible	Notoriously hard to control
Radiated noise (magnetic near field)	Ideally none	Minimize with distance, shielding, module design
Material budget	Critical since installed at low R	Expect 1-2g per converter
Real estate	No space on FE-hybrid	2-4cm ² per converter must be found

Only few <a> aspects really special for double layers. Go now through some of above points.



Radiation Hardness



F. Faccio,

CMS/ATLAS

Power WG, at TWEPP-09

St. Michelis, TWEPP-09

- Commercial converters are in general not radiation-hard \Rightarrow custom ASIC
- Systematic irradiations of candidate technologies by F. Faccio (CERN) Leakage current, R_{on} , $I_{DS} = f(V_{ds})$ vs. TID < 350Mrad & fluence < $10^{16}/cm^2$
 - → Best candidate: IHP SGB25V GOD 0.25µm SiGe BiCMOS (IHP, Germany)
 - → Back-up: AMIS I3T80 0.35µm (ON Semiconductor, US)

• ASIC development in candidate technologies by St. Michelis (CERN)

- IHP1 & IHP2: 2nd prototype submitted in January 2010
- AMIS1 & AMIS2 (May 2009); used by CMS for system tests etc.



AMIS2 ASIC

Aachen R&D: develop low mass, low noise converters with rad.-hard ASICs for CMS





Schematics in back-up slides.

m = 2.7g

PCB: 2 copper layers a 35μm FR4 1mm A = 18mm x 25mm for QFN32

Chip: AMIS2 by CERN $V_{IN} = 3 - 12V$ $I_{OUT} < 3A$ $V_{OUT} = 1.2V$, 2.5V or 3.3V $f_S \approx 1.3MHz$ (V1) or programmable (V2) betw. 600kHz...4MHz

Air-core toroid: Custom-made toroid, $\emptyset \approx 6$ mm, height = 7mm, L = 600nH, R_{DC} = 80m Ω

Input and output π -filters L = 12.1nH, C = 22 μ F

"AC2" Buck Converter with Enpirion Chip

The "work horse": buck converter with non-radiation-hard commercial chip

 \rightarrow useful for comparison, and at pre-AMIS2 times



PCB:

2 copper layers a 35μ m FR4, 200 μ m V = 2.3cm² x 10mm m = 1.0g

$$\label{eq:chip:EnpirionEQ5382D} \begin{split} \textbf{Chip:EnpirionEQ5382D} \\ \textbf{V}_{in} &= 2.4\text{-}5.5 \text{V}(\text{rec.}) \text{/}7.0 \text{V}(\text{max.}) \\ \textbf{I}_{out} &\leq 0.8 \text{A} \\ \textbf{f}_s &\approx \textbf{4MHz} \end{split}$$

Air-core inductor: Custom-made toroid, $\varnothing \approx 6$ mm L = 200nH or 600nH

Input/output filters

Snubber to reduce ringing





Estimates for stacked layers FE power consumption from CMS:

- Power/channel: 0.1mW for 100µm x ~2mm pixel (cf. tracking: 0.5mW for 5pF)
- Power per unit area: ~100mW/cm² (cf. tracking: 10/20 mW/cm² for 5.0/2.5 cm strips)
- Power per double module: 2 x 1.0 ... 4.5W (cf. tracking: 1.5W per module)

More relevant: supply currents

- 130nm or 90nm technology: 1.2V (analogue) or 0.9V (digital)
- Total current at 1.2V: 1.6 ... 8A. Note: buck supply current 3-4A.
- Digital power consumption ~ 50-75% of total; lowering V_{dig} to 0.9V halfes P_{dig}
- \rightarrow Need up to 2 x 2A at 1.2V and 2 x 2A at 0.9V per double module

\Rightarrow Two buck converters (1 x 1.2V, 1 x 0.9V) per double module

- Currents at 0.9V too large for switched capacitors
- Linear regulator for 0.9V: efficiency = 0.75%

Link Power

- Power per GBT link: ≈ 2W
- Power per pixel (50% usage of bandwidth): **150µW**
- 1 GBT per double module for trigger data: 2W
- Separate GBT links for readout
- GBTIA, GB Laser Driver: ≈ 280mA at 2.5V
- GBTX: ≈ 1.0A at 1.5V

Various options:

- One buck (1.5V) plus one step-up switched capacitor conv. (2.5V) per GBT 1)
- 2) As 1), but 1.5V buck converter delivers in addition V_{ana} to module (25% more P)
- 3) Two buck converters (1.5V, 2.5V) per 1-3 GBT(s)



P. Moreira, GBTX

SPECIFICATIONS V1.2





Power Efficiency Pout/Pin



- AMIS2, V_{out} = 1.2V, fs = 1.3MHz Efficiency [%] 80 Output Current [A] 75 2.5 70 65 60 1.5 55 1-50 0.5 45 40 5 6 7 8 9 10 11 Input Voltage [V] **AMIS2**, Vin = 10V, Vout = 1.2V, Iout = 1A 70 Efficiency [%] 65 60 55 50
- Efficiency drops with conversion ratio & current
- In practise, efficiencies above 80% hardly reached for any conversion ratio of interest
- Ohmic losses in transistor, wire bonds, PCB, coil; dynamic losses in coil etc.
- Often: higher efficiency \leftrightarrow more material

Frequency [MHz]

2,5

0,0

0,5

1,0

1,5

2.0

3,0

Conductive "Switching" Noise





DC-DC Conversion for CMS Tracker Upgrade

10 Frequency [MHz]



The System Test



SLHC prototype modules not yet available \Rightarrow existing strip hardware must be used



APV25 readout chip:

- 0.25 µm CMOS
- -128 channels
- analogue readout
- per channel: pre-amp., CR-RC shaper, pipeline
- $-\tau = 50$ ns
- 1.25V & 2.50V supply
- $-I_{250} = 0.12A, I_{125} = 0.06A$

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Silicon Strip Module Noise



- Conductive Differential Mode noise indeed increases module noise, visible mainly on edge strips due to on-chip common mode subtraction in APV25 (details in back-up slides)
- Magnetic radiation from inductor creates "wings"
- Some aspects are special to todays CMS modules (e.g. transistor of pre-amp referenced to 1.25V → high sensitivity to ripple on 1.25V)



Noise of edge strips [ADC counts]

50 b

40

30

20

10

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AC2-StandardC

Conductive Noise

L = 200 n H

L = 600 nH

"Mini Toroid"



Noise increases for

- larger conversion ratio: $\delta U_{out}/U_{out} \sim [1 - 1/r] \cdot 1/f_s^2 \cdot 1/LC$
- **lower frequency** preferred for efficiency; (depends also on module susceptibility)

AC2-ReverseC

4mg

mn

AC2-IDC

lower inductance: $\delta I_L = V_L \cdot t_{on} / L$

Enpirion converter



Switching frequency [MHz]



Conductive Noise Filters

Passive π -filters



e.g. L1 = 2.55nH ($R_{DC} \le 5m\Omega$) C = 2.2 μ F \Rightarrow f_{cut} \approx 3MHz

Efficiency loss < 1%







On-board pi-filters of AMIS2 not equally effective \Rightarrow to be understood

Radiative Noise from Air-Core Inductor

- Large fast changing currents through inductor \rightarrow magn. near field can induce noise
- Air-core toroid field has a multi-polar shape: superposition of toroid + single wire loop
- Confirmed by simulation (COMSOL) and system tests by rotating converter





Work in progress!



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DC-DC Conversion for CMS Tracker Upgrade



Shielding



- Amount of radiative noise depends on distance, orientation and other parameters
- A robust solution must be found, cannot rely on "fine-tuning"
- Ungrounded shields (30µm Aluminium) help (eddy currents)
- Shielding only the inductor less effective than shielding PCB







Motivation for new powering schemes is to save material inside the tracker

- Detailed study of Enpirion-converter, 1 per Tracker End Cap module, located on FE-hybrid
- Assumptions: 80% efficiency, r = 8, lout = 2A per module, Uout = 1.2V
- Simulation of current tracker layout with CMS software based on GEANT4

⇒ Converter adds 10% of strip module, but still saves 30% in electronics & cables





Space Requirements



- AMIS2 (QFN32) with input & output pi-filter: 25mm x 18mm ... but LDO for 3.3V and some passives will vanish
- Enpirion converter: 19mm x 12mm
 - ... but pi-filter at output desirable
- Height ~ 10mm, dominated by inductor (to be optimized)
- Plane ar an ar an

25mm

- \Rightarrow Final size will be inbetween
- \Rightarrow Will be hard to squeeze below 2cm² without compromising performance
- \Rightarrow Trade-off between redundancy and size (e.g. input pi-filter)

If two converters (1.2V/0.9V) needed per double module:

- can of course be installed on one PCB
- size increases by a factor of ≤ 1.5



Space Requirements





Converters could be integrated into support structure:

- \checkmark no space on hybrid required
- ✓ height/shape of coil no issue
- \checkmark larger distance \rightarrow less magnetic field
- \checkmark easier shielding (e.g. by existing Carbon Fibre structures)
- ✓ much easier cooling
- \checkmark Kapton bus between converter and modules $\,$ needed anyway: GBT, by-pass caps
- \checkmark decoupling of module & converter R&D, QA etc.
- ✓ straight-forward in double-stack proposal (less obvious in others)





Summary



- The CMS tracker upgrade will be powered using DC-DC conversion
- Rad.-had buck converters in two technologies are being developed at CERN
- R&D on noise understanding & mitigation at Aachen, CERN and other places
- Stacked modules require high currents at a high conversion ratio (efficiency!)
- Need to find space and to minimize material
- Converter R&D is still focused on generic aspects
- Once concrete layouts and reliable power estimates are available, DC-DC R&D will become more specific

Back-up Slides



AC_AMIS2 Schematics







- 128 APV inverter stages powered from 2.5V via common resistor (historical reasons)
 ⇒ mean common mode (CM) of all 128 channels is effectively subtracted on-chip
- Works fine for regular channels which see mean CM
- CM appears on open channels which see less CM than regular channels
- CM imperfectly subtracted for channels with increased noise, i.e. edge channels





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Module Edge Strips



- Edge strips are capacitively coupled to bias ring
- Bias ring is AC coupled to ground
- Pre-amplifier is referenced to 1.25V
- If V125 is noisy, pre-amp reference voltage fluctuates against input
- This leads to increased noise on edge channels