	Single p <sub>T</sub> Layer Performance	

# Simulating the performance of a $p_T$ tracking trigger for CMS

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Imperial College, London CMS Collaboration



Workshop on Intelligent Trackers, 2010

#### 1 Introduction

Why do we need a tracking trigger? What is stacked tracking?

- 2 Simulation
  - Detector Modelling

#### 3 Single p<sub>T</sub> Layer Performance

- Sensor Separation vs. Correlation Window
- Tilted vs. Untilted Modules
- Occupancy

#### 4 Two Layer Performance

- Track Reconstruction
- Efficiencies and Fake Rates
- Reconstruction Performance

#### 5 Summary

#### 1 Introduction

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Introduction ●○○	Single p <sub>T</sub> Layer Performance		
		Introdu	uction

A fair overview has been presented this morning...

By now you know,

- The CMS detector was designed for  $\sim 10$  years operation at a luminosity of  $10^{34} cm^{-2} s^{-1}$ .
- The majority of the detector will perform well at the sLHC upgrade luminosity (up to 10<sup>35</sup> cm<sup>-2</sup> s<sup>-1</sup>).

Outline	Introduction ●○○	Single p <sub>T</sub> Layer Performance		
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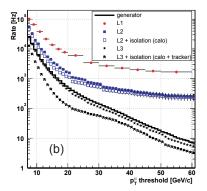
By now you know,

- The CMS detector was designed for ~10 years operation at a luminosity of 10<sup>34</sup> cm<sup>-2</sup>s<sup>-1</sup>.
- The majority of the detector will perform well at the sLHC upgrade luminosity (up to 10<sup>35</sup> cm<sup>-2</sup> s<sup>-1</sup>).
- Complete replacement of the tracking system will be required to survive the increased radiation environment and occupancies.
- Online trigger (L1) must continue to operate with a maximum 100 kHz rate.

Introduction	Single p <sub>T</sub> Layer Performance		
	Tria	noring at the	ର HC

L1 trigger must offer similar or better background rejection even with increased pileup, but

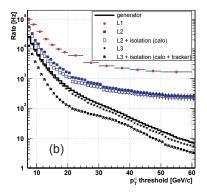
- Single µ rate cannot be constrained by increasing reconstructed track transverse momentum (p<sub>T</sub>) threshold.
- A transverse energy (E<sub>T</sub>) cut of at least 50 GeV is required to constrain the single isolated e/γ trigger.



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#### And physics performance must not be sacrificed...

Higher L1 thresholds will degrade sensitivity to LHC low mass discoveries.

Combined triggers risk biasing trigger strategy or important decay channels.

# Stacked Tracking Concept

#### Solution (of course!)...

000

Replacement tracker should provide basic hit information to the trigger.

#### But how?

Enormous power requirements and limited space for cabling and cooling.

Present tracker draws almost as much as the CMS superconducting solenoid ( $\sim$ 15 kA)!

Constrained by huge bandwidth requirements to read out hits at 40 MHz.

• Data rates  $\sim 10-20 \,\text{Gbcm}^{-2}\text{s}^{-1}$  to read out a layer at 10 cm.

# Stacked Tracking Concept

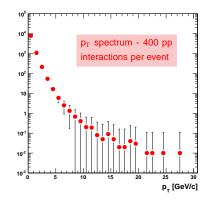
#### Solution (of course!)...

Introduction

Replacement tracker should provide basic hit information to the trigger.

Tracks with transverse momentum less than 1 GeV/c are considered 'uninteresting' for physics.

- Around 85% charged tracks reaching a layer of 25 cm have p<sub>T</sub><1 GeV/c.</li>
- An intelligent tracker could reduce the data bandwidth by a factor of ~10 by rejecting these hits.



# Stacked Tracking Concept

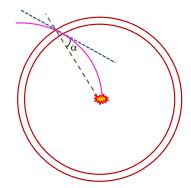
#### Solution (of course!)...

Introduction

Replacement tracker should provide basic hit information to the trigger.

Idea is to correlate hits between closely separated pixel sensors (stacks) using a simple matching algorithm

- Correlated hits can provide an effective geometrical cut on track p<sub>T</sub>.
- Multiple stacks of pixels sensors allows for track reconstruction if correlated hits can be combined.



	Simulation	Single $p_{\mathrm{T}}$ Layer Performance	

#### Introduction

Why do we need a tracking trigger? What is stacked tracking?

2 Simulation

#### Detector Modelling

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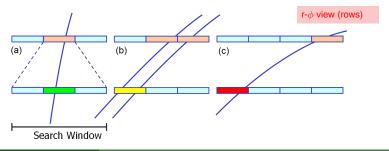
#### 5 Summary

		Simulation ●0000	Single p <sub>T</sub> Layer Performance		
				Corre	lation
Co	oncept				

#### Comparison between hit pixels on upper and lower sensors.

A successful correlation is identified as a stub.

- High  $p_T$  tracks can be identified if hits lie within a search window in r- $\phi$  (rows).
- Assumes binary readout.
- Stubs from two separate p<sub>T</sub> layers can be correlated to obtain tracklets.



	Simulation ●OOOO	Single p <sub>T</sub> Layer Performance		
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#### Concept

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#### Keep in mind

Correlation over a minimal number of rows (as well as columns) will permit a simpler and lower power correlation scheme.

Outline		Simulation 0●000	Single p <sub>T</sub> Layer Performance				
		Detector Geometry					
Im	portant to per	form realistic	simulations including	material effects			

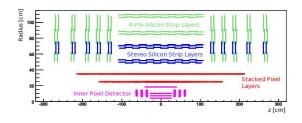
interactions etc. Modifications to the current CMS geometry software allows detailed simulations of events at SLHC based on **GEANT** (or a parametrised simplification of GEANT)

	Simulation O●OOO	Single p <sub>T</sub> Layer Performance		
			Detector Geo	metry

Important to perform **realistic simulations** including material effects, interactions etc. Modifications to the current CMS geometry software allows detailed simulations of events at SLHC based on **GEANT** (or a parametrised simplification of GEANT)

#### Concept geometry

Opting for the more conservative two stack layer geometry to help characterise the triggering performance of a  $p_T$  layer.



Full  $\eta$  coverage, layers as close as possible to IP without interfering with tracking.

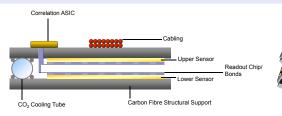
	Simulation 00●00	Single p <sub>T</sub> Layer Performance		
			р <sub>т</sub> М	odule

No definite design yet - more later this afternoon (G.Hall)

#### Concept design

A basic design for simulations including realistic estimates of material implemented.

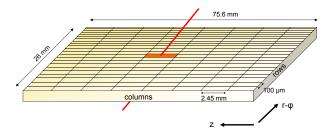
Includes provisions for cabling, cooling and structural support so that material interactions and impact on tracking performance is taken into account.





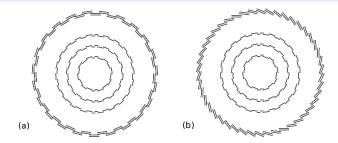
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- r- $\phi$  pitch of less than 100  $\mu m$  is unlikely while wider pixels reduce  $p_T$  discrimination ability.
- z pitch can be increased (macro-pixels) but lower limit is determined by luminous region; 2.45 mm for a sensor separation of 2 mm and layer radius of 25 cm. Occupancy remains less than 1%.



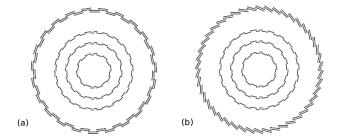
	Simulation 0000●	Single p <sub>T</sub> Layer Performance		
			р <sub>т</sub> М	odule

 Sensor Tilt - can reduce the effect of Lorentz drift hence smaller clusters...better correlation? lower data rates?



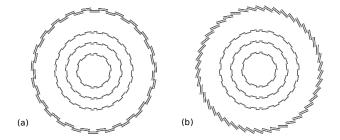
	Simulation 0000	Single p <sub>T</sub> Layer Performance		
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- Sensor Size wider sensors will complicate the correlation algorithm since offsets are needed near edges



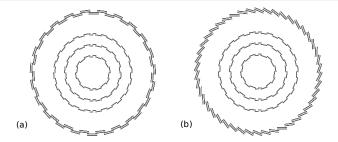
	Simulation 00000	Single p <sub>T</sub> Layer Performance		
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- Sensor Thickness thinner sensors could be also help reduce cluster size



Outline	Simulation 0000	Single p <sub>T</sub> Layer Performance	Two Layer Performance	
			р <sub>т</sub> М	odule
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Outline		Simulation 00000	Single p <sub>T</sub> Layer Performance	Iwo Layer Performance	
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Only a selection of the results of these simulations will be shown in the following slides...

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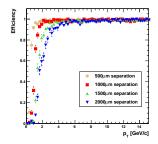
# Sensor Separation vs. Correlation Window

#### Single $\mu^{\pm}$ efficiencies

Sensor separation allows continuous selection of cut on track  $\ensuremath{p_{\mathrm{T}}}$  .

Increasing inter stack separation increases  $\ensuremath{p_{\mathrm{T}}}$  threshold.

- Also increases transition region where tracks may or may not pass.
- Region width depends on pixel charge sharing, pitch, sensor thickness, sensor separation and the track impact point.



# Sensor Separation vs. Correlation Window

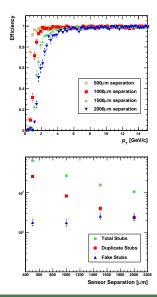
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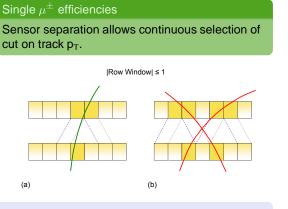
By increasing sensor separation, the  $p_T$  threshold is increased and fewer stubs are generated under SLHC pileup conditions.



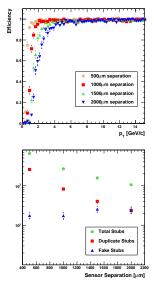
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### Sensor Separation vs. Correlation Window



Without clustering, stubs may be duplicated (a). Incorrectly matched hits give rise to fakes (b).



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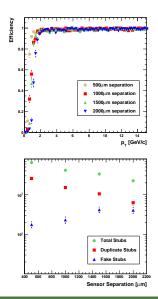
# Sensor Separation vs. Correlation Window

#### Single $\mu^{\pm}$ efficiencies

Size of correlation window can also be adjusted. Allows discrete selection of cut on track  $p_T$ .

Window size is increased with sensor separation

- Transition region width is minimised
- Efficiency is well defined above threshold.



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# Sensor Separation vs. Correlation Window

#### Single $\mu^{\pm}$ efficiencies

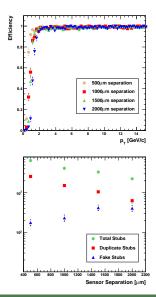
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#### But...

Increasing the correlation window size increases number of generated stubs and hence data rate under SLHC pileup conditions.



### Sensor Separation vs. Correlation Window

#### Single $\mu^{\pm}$ efficiencies

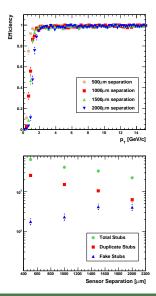
Size of correlation window can also be adjusted. Allows discrete selection of cut on track  $p_T$ .

Window size is increased with sensor separation

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- Efficiency is well defined above threshold.

#### Even so,

an adjustable correlation window would be useful to change  $p_T$  cut (and control trigger data rate) during operation.



# Sensor Separation vs. Correlation Window

#### Summary of a few results...

The table below highlights some of the important numbers from the simulations.

Sensor	Row	$\varepsilon_{ m muon}$	N <sub>Stubs</sub>	Fake	Duplicate	Rate
Separation	Window	p <sub>T</sub> >2 GeV/c				Reduction
(µm)	(pixels)	(%)		(%)	(%)	
1000	3	99.2	2670.5	6.6	30.9	22.0
1000	4	99.2	4150.9	5.6	36.6	14.2
2000	3	97.1	1054.1	23.3	22.4	54.4
2000	5	98.7	2248.3	18.1	28.0	25.5

 $\varepsilon_{muon}$  describes the efficiency of all muon tracks reaching the stacked layer with p\_T>2 GeV/c to generate a stub.

The **rate reduction** is the ratio of total number of hit pixels to number of generated stubs.

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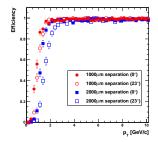
# Tilted vs. Untilted Modules

#### Effect of sensor tilt

Sensors can be tilted to reduce Lorentz drift and minimise cluster size.

Tilting sensors also increases transition width

- Correlation induces small track charge bias.
- Effect can be reduced by adjusting correlation window.



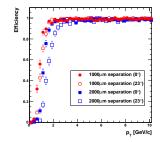
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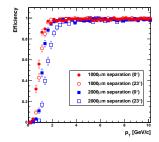
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#### Effect of sensor tilt

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#### Untilted sensors probably better...

Unless lowest possible rate is of extreme importance, an untilted layout should be easier to implement.

- Less complex mechanics, correlation over fewer pixels.
- Offers better hit position resolution for higher level track reconstruction.
- Basic clustering on trigger data to eliminate duplicates could be possible.

	Single p <sub>T</sub> Layer Performance ○○○○●○○	
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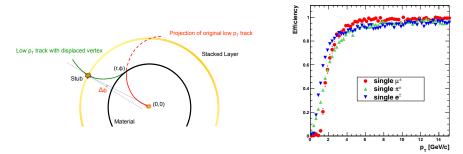
#### Pions, Electrons...

#### Single $\pi^{\pm}$ , $e^{\pm}$ efficiencies

p<sub>T</sub> resolution worsens for interacting particles

Inner tracker material contributes to mis-measurement of transverse momentum.

- Low p<sub>T</sub> tracks come from secondary interactions with displaced vertex.
- High p<sub>T</sub> electrons can radiate in material so p<sub>T</sub> at the stack is lower.



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Single p<sub>T</sub> Layer Performance

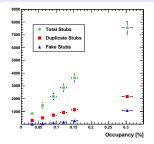
## **Minimum Bias Pileup**

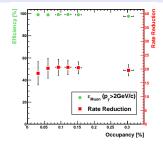
#### Effect of occupancy

Important to ensure correlation algorithm is robust to the range of occupancies possible at SLHC.

Simulations so far indicate that a stacked layer could operate,

- Efficiently up to an occupancy of at least 0.3%.
- With a fairly consistent rate reduction.





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Single p<sub>T</sub> Layer Performance

## **Minimum Bias Pileup**

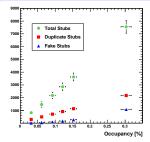
#### Effect of occupancy

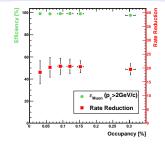
Important to ensure correlation algorithm is robust to the range of occupancies possible at SLHC.

Simulations so far indicate that a stacked layer could operate,

- Efficiently up to an occupancy of at least 0.3%.
- With a fairly consistent rate reduction.

#### Requires further simulations for occupancies up to worst case.





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Single p<sub>T</sub> Layer Performance

Two Layer Performance

Summary

## Single Layer Summary

## Simulations show that a stacked layer could discriminate against low $\ensuremath{p_{\mathrm{T}}}$ tracks

- Efficiently (better than 90%) up to an occupancy of at least 0.3%.
- With an adequate data rate reduction of  $\sim$ 20.

#### For better operation,

- Sensors should be untilted and would benefit from simple clustering (preferably on detector).
- Material before the stacked layers should be minimised.



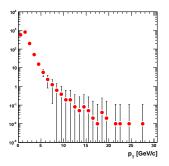
## Single Layer Summary

## Simulations show that a stacked layer could discriminate against low $p_{\rm T}$ tracks

- Efficiently (better than 90%) up to an occupancy of at least 0.3%.
- With an adequate data rate reduction of  $\sim$ 20.

#### For better operation,

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- Material before the stacked layers should be minimised.



#### However,

A single stacked pixel layer with such a rate reduction would not be useful for a L1 trigger. With over 1000 stubs per event, every trigger tower would be matched to a tracker stub due to poor stub vector resolution. Stub  $p_T$  spectrum indicates why.

	Single $p_{T}$ Layer Performance	Two Layer Performance	

#### Introduction

Why do we need a tracking trigger? What is stacked tracking?

#### 2 Simulation

Detector Modelling

#### 3 Single p<sub>T</sub> Layer Performance

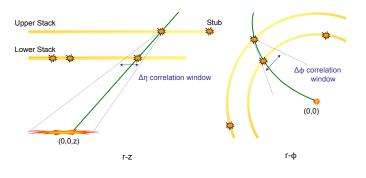
- Sensor Separation vs. Correlation Window
- Tilted vs. Untilted Modules
- Occupancy

#### 4 Two Layer Performance

- Track Reconstruction
- Efficiencies and Fake Rates
- Reconstruction Performance

#### 5 Summary

			Single p <sub>T</sub> Layer Performance	Two Layer Performance ●○○○○○	
				Corre	lation
Us	sing two stack	ed layers			
	orrelate stubs i f-detector.	in upper layer	with stubs in lower laye	er to form tracklets	



Outline	Introduction	Simulation 00000	Single p <sub>T</sub> Layer Performance	Two Layer Performance ●○○○○○	Summary
				Corre	ation
Us	ing two stack	ed layers			
	rrelate stubs -detector.	in upper layer	r with stubs in lower la	yer to form tracklets	
	Upper Stack		Stub		
	Lower Stack		correlation window	Δφ correlation window	

 $_{(0,0,z)}^{(0,0,z)}$ r-z Apply a cut in  $\Delta\eta$  large enough to account

Apply a cut in  $\Delta \phi$  large enough to allow for low  $p_T$  tracks and multiple scattering.

r-φ

(0,0)

for vertex smearing.

	Two Layer Performance ●○○○○○	Single p <sub>T</sub> Layer Performance		
elation	Corr			

#### Using two stacked layers

Correlate stubs in upper layer with stubs in lower layer to form tracklets off-detector.

#### then...

Track transverse momentum can be measured - assuming(x,y) interaction vertex is (0,0).

$$p_{\rm T} = \frac{0.6\sqrt{r_1^2 + r_2^2 - 2r_1r_2\cos(\Delta\phi)}}{\sin(\Delta\phi)}$$
(1)

where  $r_1$  and  $r_2$  are the radii in metres of the inner stack layer and outer stack layer respectively and  $\Delta \phi$  is the angular separation in  $\phi$  between the two stubs.  $p_T$  is in GeV/c.

			Single p <sub>T</sub> Layer Performance	Two Layer Performance ○●O○○○	
				Effic	ciency
Si	nale $\mu^{\pm}$ $\pi^{\pm}$ e	e <sup>±</sup> efficiencie:	8		

# After calculating track transverse momentum, a secondary $\ensuremath{p_{\mathrm{T}}}$ cut can be applied.

#### Flexibility in choice of p<sub>T</sub> threshold in L1 firmware

 Can be trigger algorithm specific when matching to other subdetectors, e.g. electrons

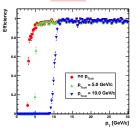
			Single p <sub>T</sub> Layer Performance	Two Layer Performance ○●○○○○	
				Effic	ciency
Sir	ngle $\mu^\pm$ , $\pi^\pm$ , $\epsilon$	$e^{\pm}$ efficiencies	S		

After calculating track transverse momentum, a secondary  $p_{\rm T}$  cut can be applied.

Flexibility in choice of p<sub>T</sub> threshold in L1 firmware

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#### Muons



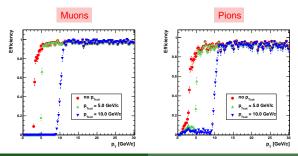
Mark Pesaresi (IC-CMS)

			Single p <sub>T</sub> Layer Performance	Two Layer Performance ○●○○○○	
				Effic	ciency
Sin	ngle $\mu^\pm,\pi^\pm,\epsilon$	$e^{\pm}$ efficiencies			

After calculating track transverse momentum, a secondary  $p_T$  cut can be applied.

Flexibility in choice of  $p_T$  threshold in L1 firmware

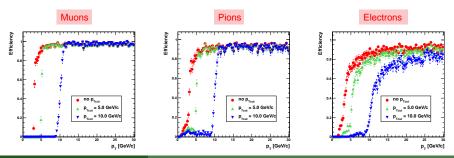
 Can be trigger algorithm specific when matching to other subdetectors, e.g. electrons



			Single p <sub>T</sub> Layer Performance	Two Layer Performance ○●○○○○	
				Effic	ciency
Si	ngle $\mu^{\pm},\pi^{\pm},\epsilon$	$e^{\pm}$ efficiencies	S		
	ter calculating plied.	track transve	rse momentum, a secor	ndary $p_T$ cut can be	

#### Flexibility in choice of p<sub>T</sub> threshold in L1 firmware

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Outline		Single p <sub>T</sub> Layer Performance	Two Layer Performance ○O●○○○	
			Fake	Rate

#### **Combinatorial fakes**

Matching uncorrelated stubs in each layer to form tracklets with random  $p_{\rm T}$ .

Dependent on occupancy, layer correlation windows and inter-stack correlation window.

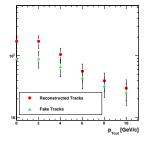
• ~25 fake tracks per event after a 10 GeV/c  $p_T$  cut.

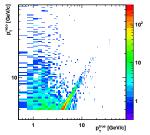
#### Mis-reconstructed fakes

Measurement of p<sub>T</sub> is over-estimated due to secondary displaced vertices.

Irreducible without a third point in the reconstruction.

• ~2 fake tracks per event after a 10 GeV/c  $p_T$  cut.





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Summary

### Track Reconstruction

#### p<sub>T</sub> resolution

Track  $p_T$  resolution using two stack plus assumed beam spot worsens with  $p_T$ .

#### Performance is reasonable,

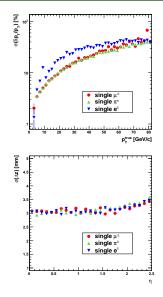
- $\sim$  20% for pions and muons up to 50 GeV/c.
- Slightly worse for electrons.

#### z vertex resolution

Track z vertex resolution is constant with  $\eta$ .

#### Primary vertex hard to identify,

- A 3 mm resolution would include over 3 vertices every crossing.
- Determined by the pixel pitch in z.



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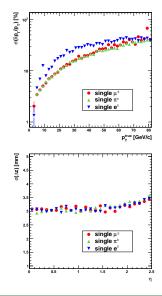
### Track Reconstruction

#### p<sub>T</sub> resolution

Transverse momentum measurement could be used for  $E_T/p_T$  cut. Increasing distance between layers would improve  $p_T$  resolution.

#### z vertex resolution

Can be improved by bringing the layers closer to the IP. May be enough to identify a region of interest for combined trigger vertex cuts.



Outline

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Single p<sub>T</sub> Layer Performance

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Summary

### **Track Reconstruction**

#### $\Delta \phi$ resolution at ECAL

At the Electromagnetic Calorimeter surface, phi track resolution is better than a trigger tower.

Important so that matching of track candidates is similar to that of calorimeter trigger objects.

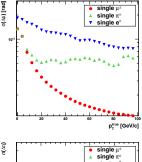
- ~0.02 compared to the L1 ECAL trigger tower of  $\Delta\phi{=}0.087$
- Worse for electrons and pions than muons.

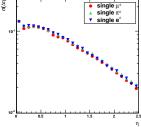
#### $\Delta\eta$ resolution at ECAL

At the ECAL surface, eta track resolution is worse than that of a trigger tower.

But resolution is still less than two trigger towers,

- Improves with increasing  $\eta$
- Similar performance for all particles.





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Outline	Introduction	Simulation 00000	Single p <sub>T</sub> Layer Performance	Two Layer Performance	Summary
				Sum	nmary
	software package On detector h Effects such when defining	e. The layer i hit correlation is as Lorentz drif g the layer, e.g	een implemented within s also configurable. It h s a non trivial process. t, multiple scattering etc. a . tilting the sensors to redu ithm complexity.	as demonstrated tha	ions
	• • •	•	ood and demonstrates t probably not viable for a	•	
	• •	-	timate of the track $p_T$ , than 20% for $p_T < 20 \text{ GeV}$	/c.	

- Track  $\Delta \phi$  and  $\Delta \eta$  resolutions for matching to ECAL trigger objects is sufficient.
- Fake background appears to be under control.

Matching with other subdetector primitives for viable L1 triggers remains to be demonstrated.

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