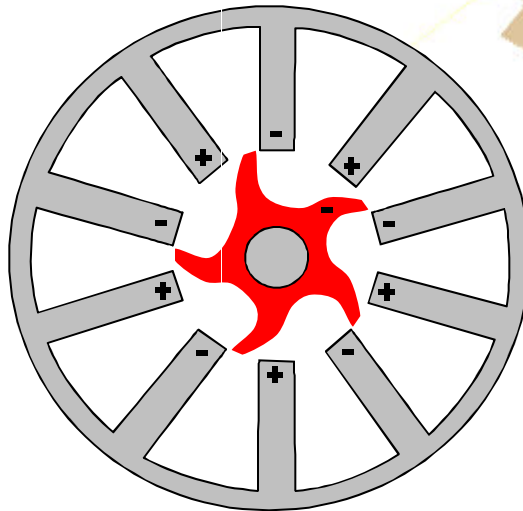
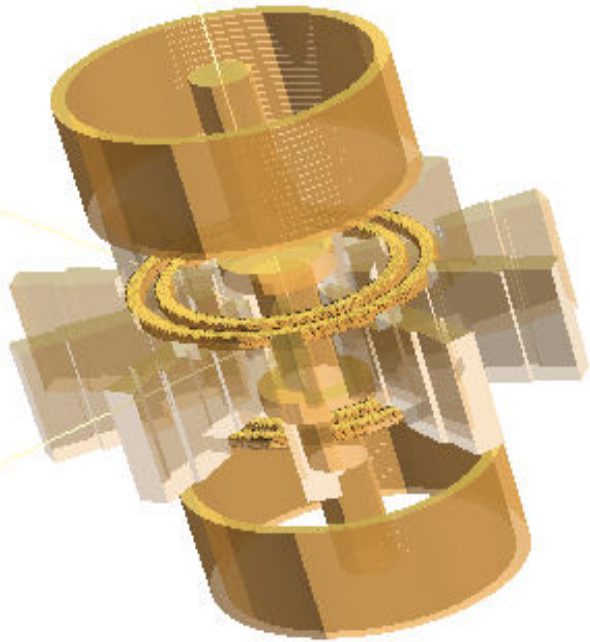
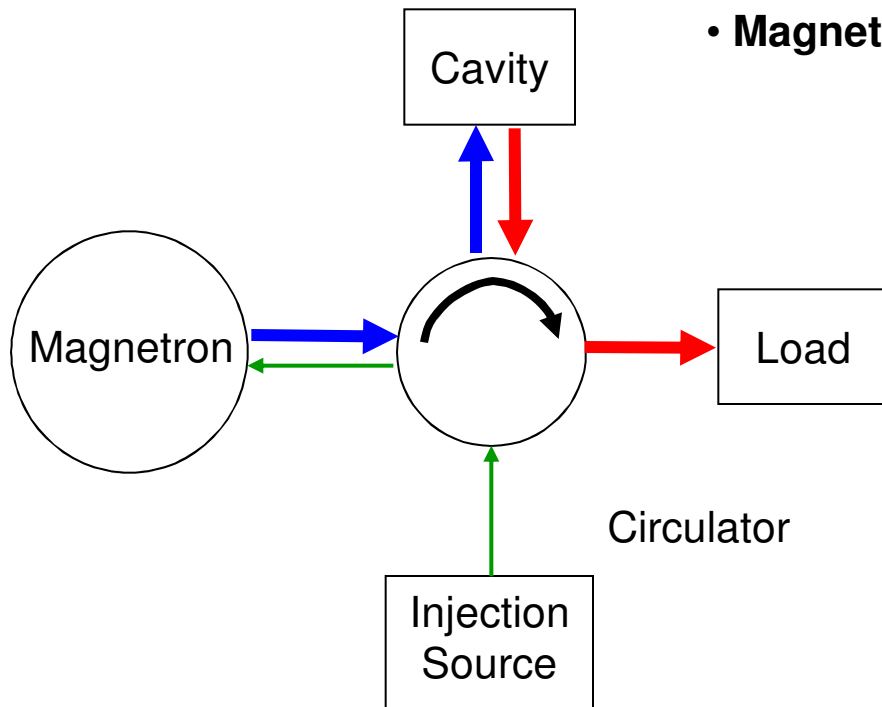


Amos Dexter, Imran Tahir, Bob Rimmer and Richard Carter



- Linacs require accurate phase control
- Phase control requires an amplifier
- Magnetrons can be operated as reflection amplifiers



Compared to Klystrons, in general Magnetrons

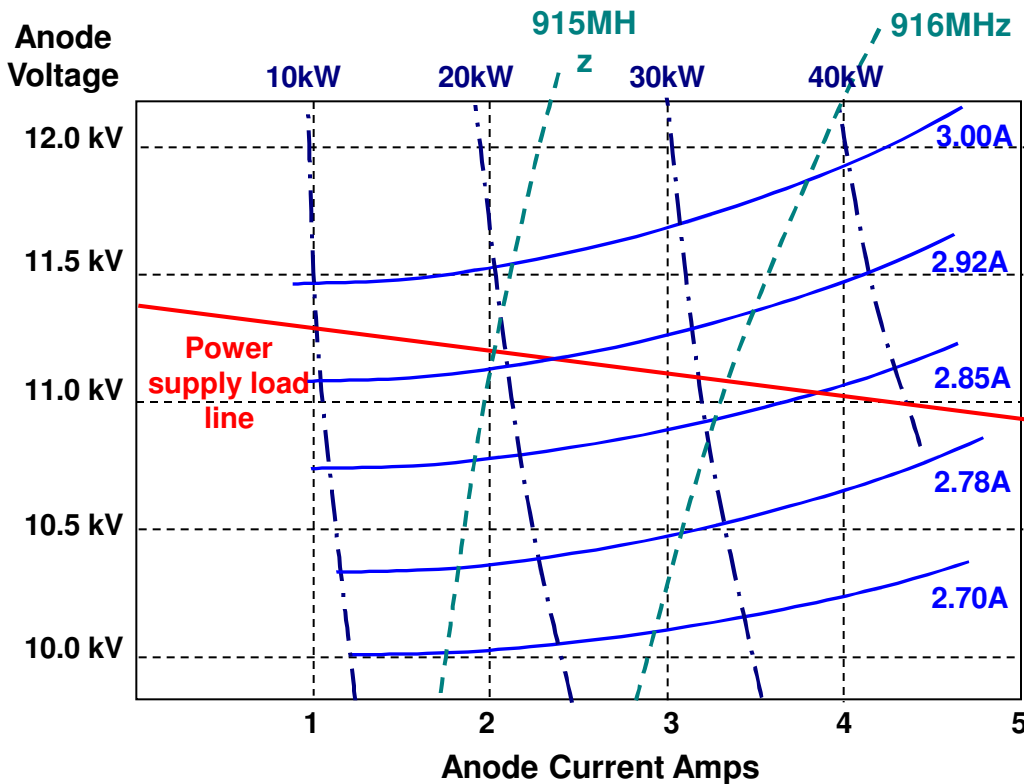
- are smaller
- more efficient
- can use permanent magnets (at 704 MHz)
- utilise lower d.c. voltage but higher current
- are easier to manufacture

Consequently they are much cheaper to purchase and operate

J. Kline “The magnetron as a negative-resistance amplifier,”
IRE Transactions on Electron Devices, vol. ED-8, Nov 1961

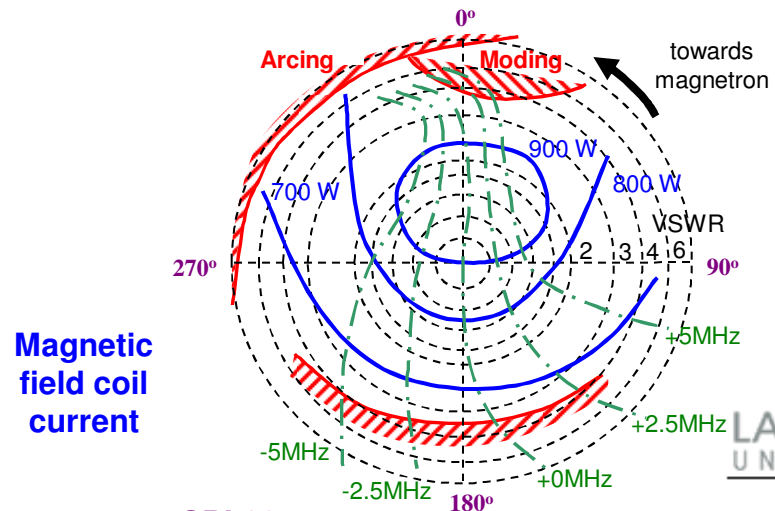
H.L. Thal and R.G. Lock, “Locking of magnetrons by an injected r.f. signal”,
IEEE Trans. MTT, vol. 13, 1965

1. Phase of output follows the phase of the input signal
2. Phase shift through magnetron depends on difference between input frequency and the magnetrons natural frequency
3. Output power has minimal dependence on input signal power
4. Phase shift through magnetron depends on input signal power
5. There is a time constant associated with the output phase following the input phase



Magnetron frequency and output vary together as a consequence of

1. Varying the magnetic field
2. Varying the anode current (pushing)
3. Varying the reflected power (pulling)



Single magnetrons 2.856 GHz, 5 MW, 3 μ s pulse, 200 Hz repetition are used to power linacs for medical and security applications.

Multiple magnetrons have been considered for high energy normal conducting linacs but the injection power needed for an unstabilised magnetron made it uncompetitive with a Klystron.

Overett, T.; Bowles, E.; Remsen, D. B.; Smith, R. E., III; Thomas, G. E. “Phase Locked Magnetrons as Accelerator RF Sources” *PAC* 1987

Benford J., Sze H., Woo W., Smith R., and Harteneck B., “Phase locking of relativistic magnetrons” *Phys. Rev.Lett.*, vol. 62, no. 4, pp. 969, 1989.

Treado T. A., Hansen T. A., and Jenkins D.J. “Power-combining and injection locking magnetrons for accelerator applications,” *Proc IEEE Particle Accelerator Conf.*, San Francisco, CA 1991.

Chen, S. C.; Bekefi, G.; Temkin, R. J. “Injection Locking of a Long-Pulse Relativistic Magnetron” *PAC* 1991

Treado, T. A.; Brown, P. D.; Hansen, T. A.; Aiguier, D. J. “Phase locking of two long-pulse, high-power magnetrons” , *IEEE Trans. Plasma Science*, vol 22, p616-625, 1994

Treado, Todd A.; Brown, Paul D., Aiguier, Darrell “New experimental results at long pulse and high repetition rate, from Varian's phase-locked magnetron array program” *Proceedings Intense Microwave Pulses*, SPIE vol. 1872, July 1993



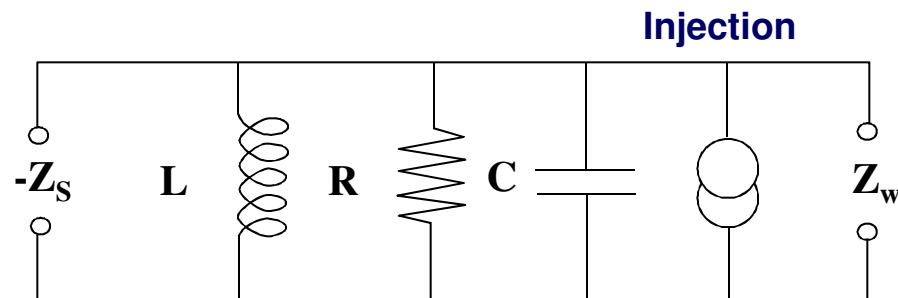
Courtesy of e2v

J.C. Slater "The Phasing of Magnetrons" MIT Technical Report 35, 1947

Shien Chi Chen "Growth and frequency Pushing effects in Relativistic Magnetron Phase – Locking", IEEE Trans. on Plasma Science Vol. 18 No 3. June 1990.

The basic circuit model for the phased locked magnetron is the same as for a cavity

Negative impedance to represent magnetron spokes excitation of the anode. Includes static pushing effects.



Load impedance includes pulling effects.

$$\ddot{V} - \frac{\omega_o}{Q_w} \left(\frac{Z_w}{Z_s} - \frac{Z_w}{R} - 1 \right) \dot{V} + \omega_o^2 V = -j \frac{\omega_o \omega_i}{Q_w} V_{inj} \exp(-j\omega_i t)$$

To get Adler's equation set $V(t) = A(t) \exp\{-j(\omega t + \psi(t))\}$

to give

$$\frac{d\psi}{dt} = -\frac{V_{inj}}{V_{RF}} \frac{\omega_o}{2Q_L} \sin \psi + \omega_o - \omega_i$$

$$\frac{d\psi}{dt} = -\frac{V_{inj}}{V_{RF}} \frac{\omega_o}{2Q_L} \sin \psi + \omega_o - \omega_i$$

ω_o magnetron ang. oscillation frequency without injection

ω_{inj} injection angular frequency

ψ phase shift between injection input and magnetron output

$V_{inj/RF}$ equivalent circuit voltage for injection signal / RF output

Adler's equation predicts that :-

if $\omega_o = \omega_i$ then $\psi \rightarrow 0$

if ω_o close to ω_i then $\psi \rightarrow$ a fixed value (i.e. when $\sin \psi < 1$ then locking occurs)

if ω_o far from ω_i then $\psi \rightarrow$ no locking unless V_{inj} is large

Steady state
$$\sin \psi = 2Q_L \sqrt{\frac{P_{RF}}{P_{inj}}} \frac{\omega_o - \omega_i}{\omega_o}$$

If the natural frequency of the magnetron is fluctuating then the phase ψ will be fluctuating.

High frequency phase jitter will be filtered by a superconducting the cavity

Advancing or retarding the injection signal allows low frequency jitter to be cancelled and the magnetron phase or the cavity phase to be maintained with respect to a reference signal.

Like $\frac{d\psi}{dt} = -A\psi + \text{const}$
 for small ψ hence phase stabilises to a constant offset

The minimum locking power is given when $\sin \psi = 1$

P_{RF} is output power

Q_L refers to the loaded magnetron.

$$P_{inj} = 4 P_{RF} Q_L^2 \left(\frac{\omega_i - \omega_o}{\omega_o} \right)^2$$

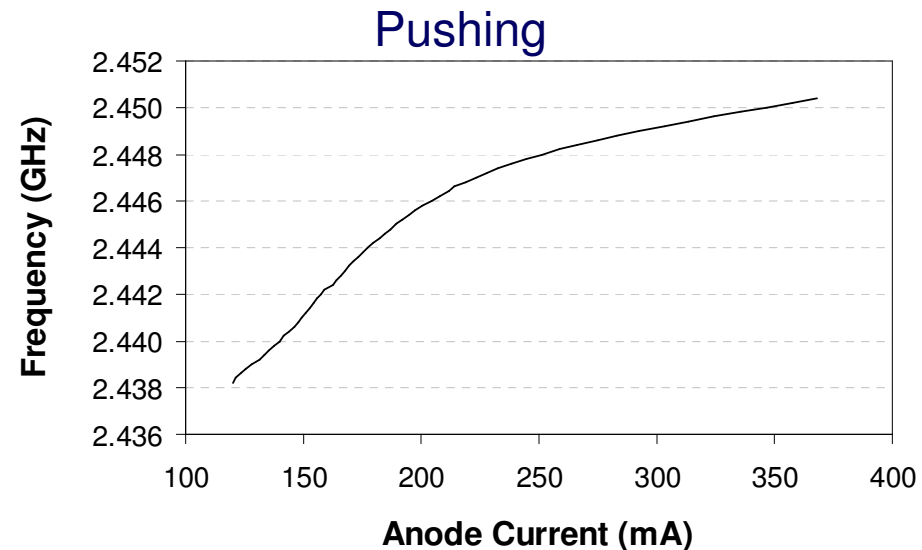
For our 2.45 GHz cooker magnetron

$(f_i - f_o)$ due to ripple ~ 2 MHz

$(f_i - f_o)$ due to temperature fluctuation > 5 MHz

$$\frac{P_{lock}}{P_{output}} = 4 Q^2 \left(\frac{f_i - f_o}{f_o} \right)^2 = 4 \times 100^2 \times \left(\frac{2.455 - 2.450}{2.450} \right)^2$$

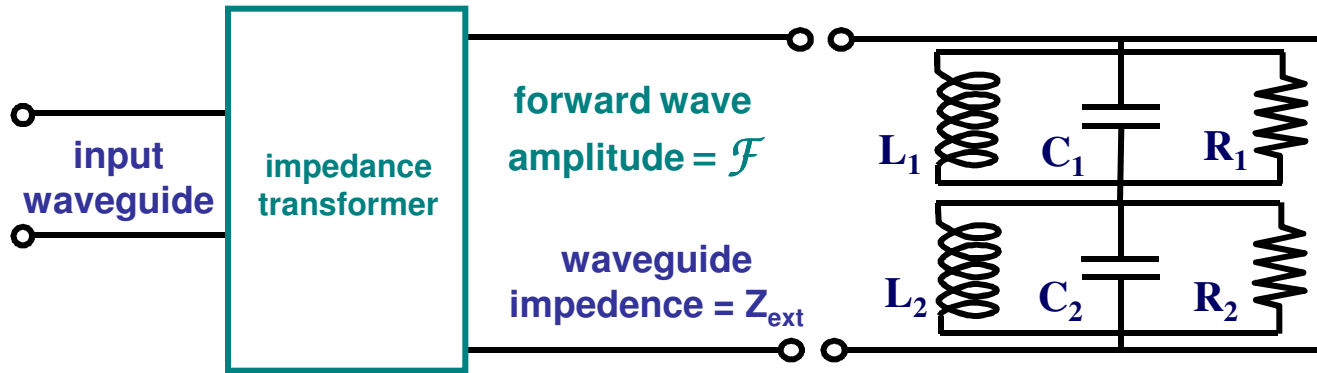
$$\frac{P_{lock}}{P_{output}} = 0.166$$



This is big hence must reduce $f_i - f_o$ (can do this dynamically using the pushing curve)

Time response $\sim \frac{2Q_w}{\omega_o} \sqrt{\frac{P_{RF}}{P_{inj}}} \sim \frac{200}{2\pi \times 2.45 \times 10^9} \sqrt{\frac{1000}{1}} \sim 400 \text{ ns} \sim 1000 \text{ RF cycles}$

A full system model assists in understanding amplifier requirement



equivalent electrical circuit for excitation of two cavity modes

$$\frac{1}{L_i} \int V_i dt + C_i \frac{dV_i}{dt} + \frac{V_i}{R_i} + \frac{1}{Z_{wg}} \sum_{j=1}^N V_j = \frac{2\mathcal{F}}{Z_{wg}} \exp(-j\omega t)$$

resulting differential equation for N modes (Numerically solve envelope equations)

$$Q_i = \omega_i R_i C_i \quad \omega_i = \frac{1}{\sqrt{L_i C_i}} \quad \frac{Q_{ie}}{Q_i} = \frac{Z_{wgi}}{R_i}$$

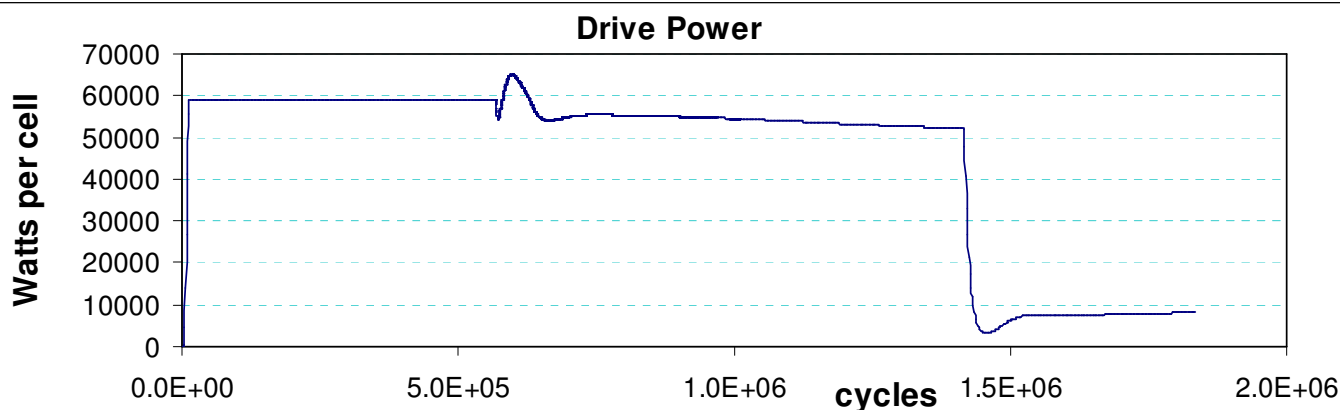
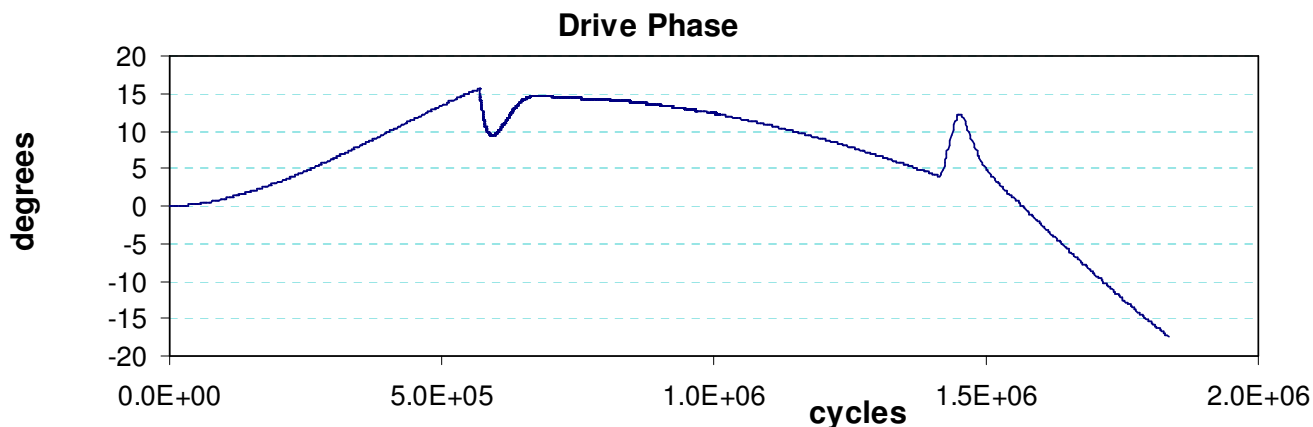
conversion from circuit parameters to cavity parameters

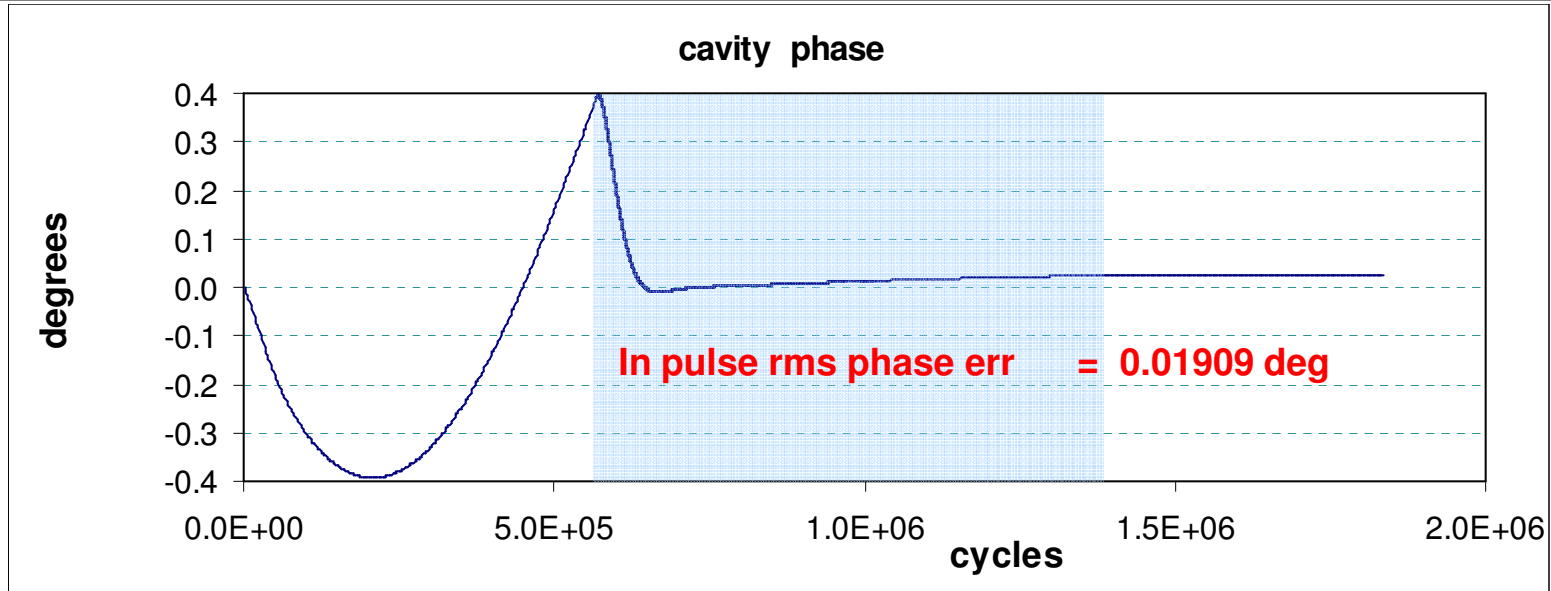
- Microphonics cause ω_i to vary with time
- Beamloading causes V to jump when a bunch passes through
- The amplitude and phase of \mathcal{F} depend on the controller, the amplifier characteristics and the coupler temperature

- Fill at almost full power
- PI control plus simple feed forward when pulse arrives
- Drive power and drive phase depends on cavity frequency offset caused by microphonics and Lorentz detuning

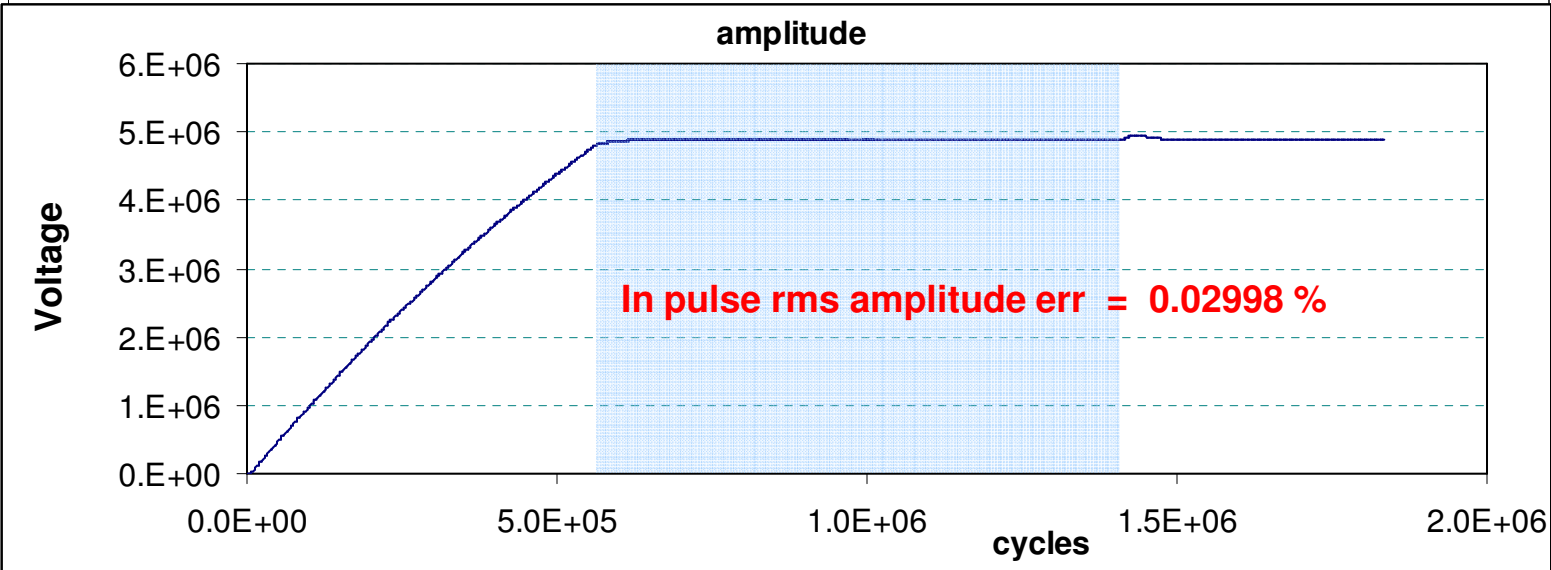
Plausible parameters

Drive frequency in GHz	=	0.704 GHz
Centre cavity frequency in GHz	=	0.704 GHz
Number of cavity modes included	=	1
Cavity Q factor	=	1.0 E+09
External Q factor	=	4.0 E+06
Cavity R over Q	=	100 ohms
Energy set point	=	21.8 J
Amplitude set point	=	4.8792 MV
Max Amplifier Power per cell	=	59 kW
Max voltage set point (no beam)	=	13.740 MV
Target fill time	=	9.0E-04 s
Cycle number for beam arrival	=	568000
Maximum bunch phase jitter	=	0.000 deg
Bunch charge (ILC=3.2 nC)	=	0.057 nC
RF cycles between bunches	=	2.0
Bunch train length	=	1.2 ms
Cavity frequency shift from microphonics	=	60 Hz
Cavity vibration frequency	=	200 Hz
Phase measurement error(degrees)	=	0.000 deg
Fractional err in amplitude measurement	=	0.0000
Time delay (latency) for control system	=	1.0E-06 s
Control update interval	=	1.0E-06 s
Gain constant for controller	=	0.55
Beam arrival real feedforward term	=	0.50E+10
Beam arrival imag feedforward term	=	0.13E+10
Amplifier bandwidth	=	1.0E+06
Measurement filter bandwidth	=	5.0E+05
In pulse rms phase err	=	0.01909 deg
In pulse rms amplitude err	=	0.02998 %





Filling at almost full power may give poor phase accuracy at start of bunch train

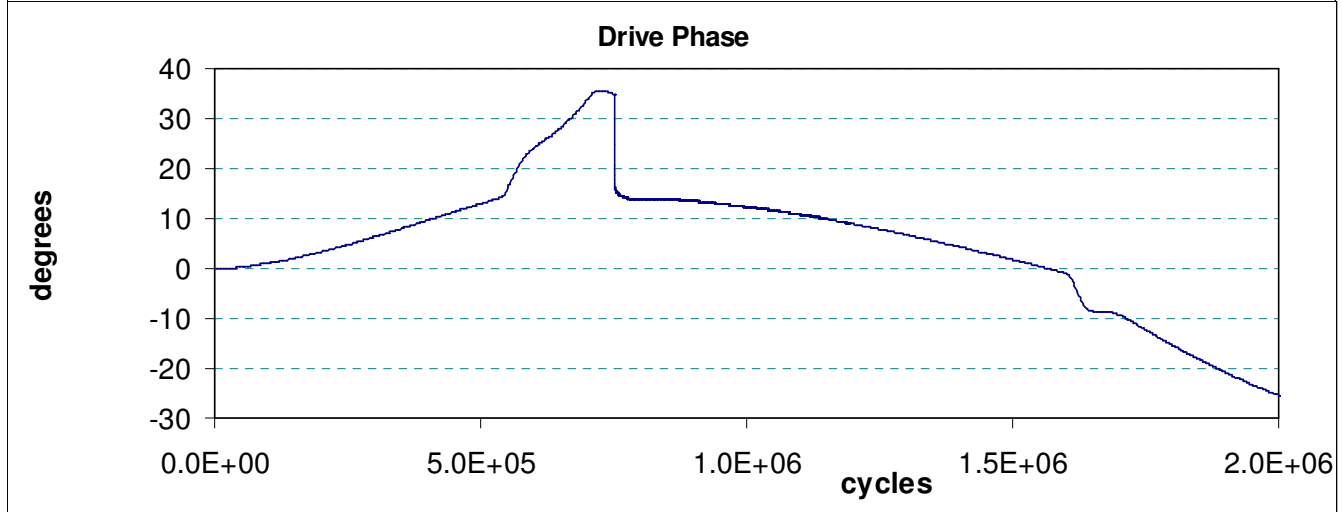
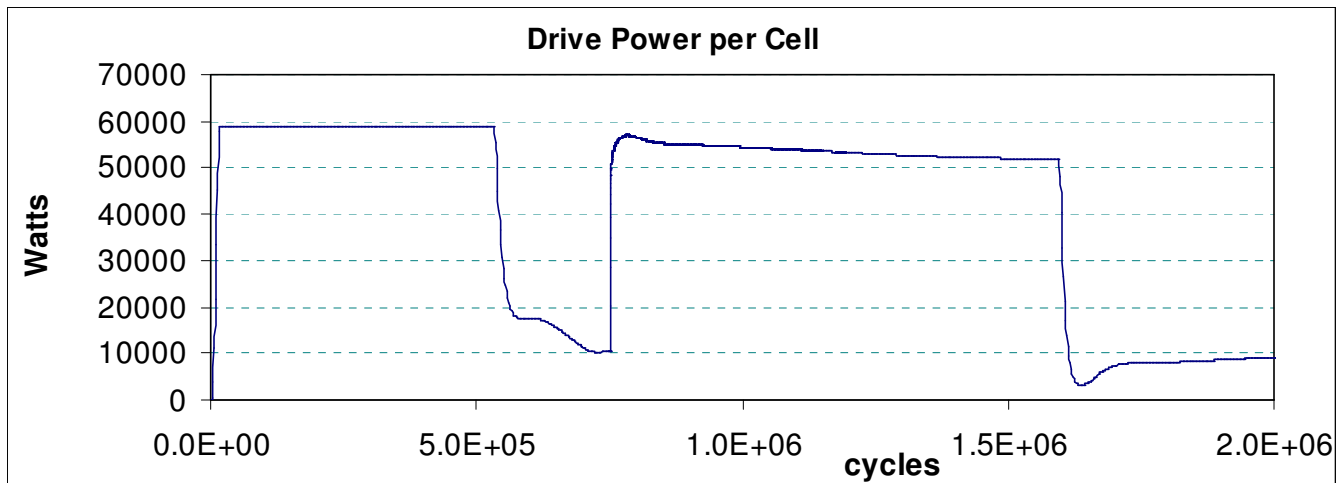


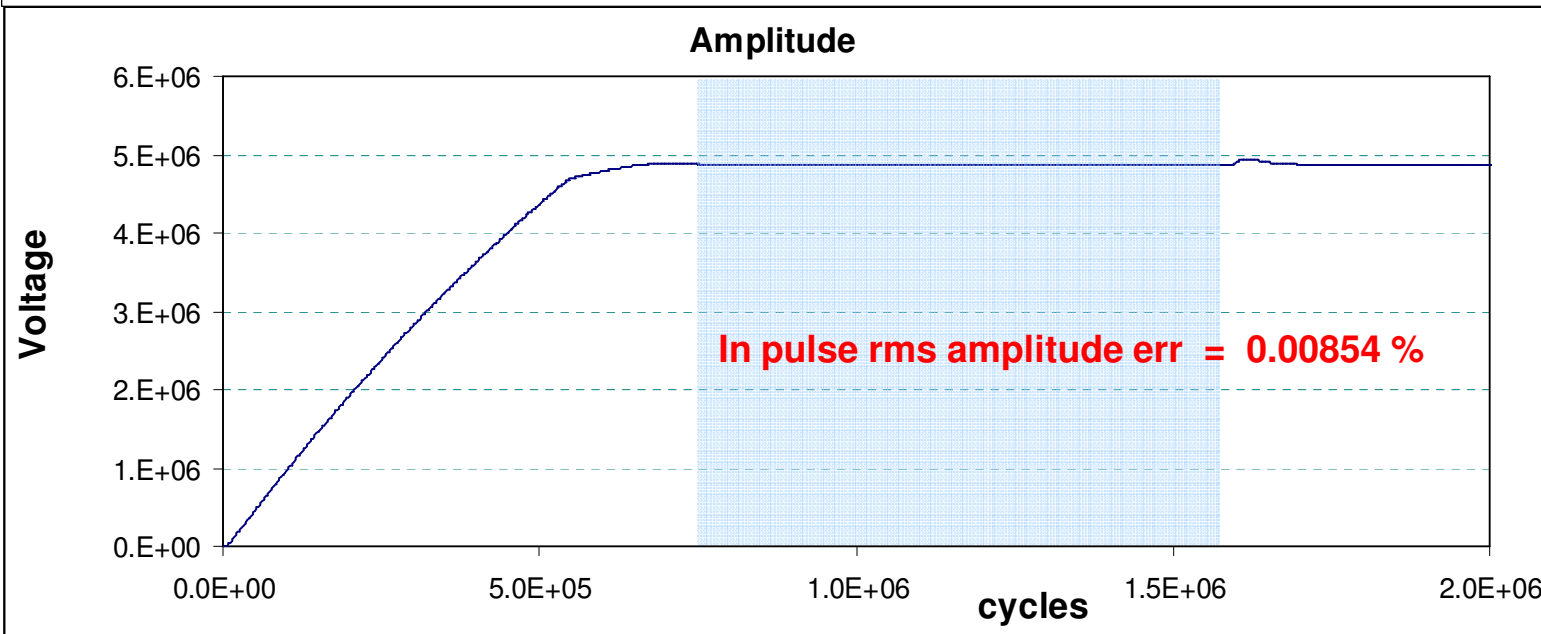
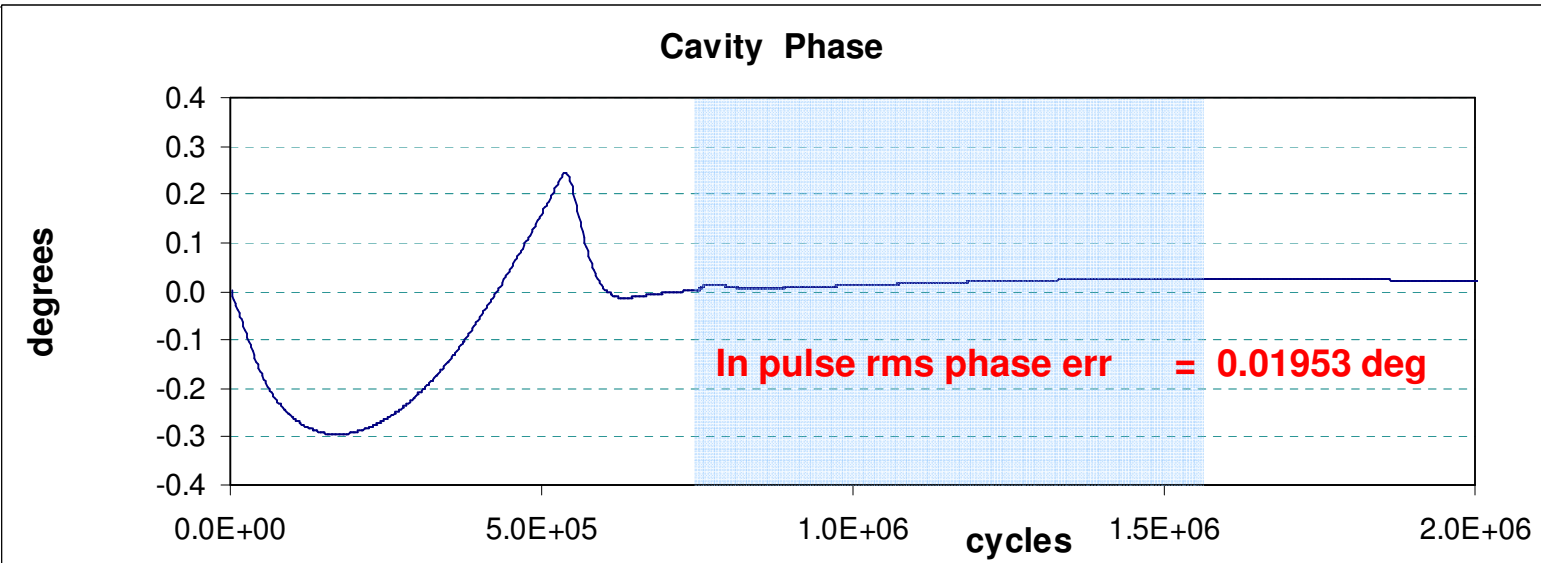
Plausible parameters

- Reduce fill rate as cavity approaches set point, the control system can then fix the phase error.
- PI control plus simple feed forward when pulse arrives

Drive frequency in GHz	=	0.704 GHz
Centre cavity frequency in GHz	=	0.704 GHz
Number of cavity modes included	=	1
Cavity Q factor	=	1.0 E+09
External Q factor	=	4.0 E+06
Cavity R over Q	=	100 ohms
Energy set point	=	21.8 J
Amplitude set point	=	4.8792 MV
Max Amplifier Power per cell	=	59 kW
Max voltage set point (no beam)	=	13.740 MV
Target fill time	=	10.0E-04 s
Cycle number for beam arrival	=	750000
Maximum bunch phase jitter	=	0.000 deg
Bunch charge (ILC=3.2 nC)	=	0.057 nC
RF cycles between bunches	=	2.0
Bunch train length	=	1.2 ms
Cavity frequency shift from microphonics	=	60 Hz
Cavity vibration frequency	=	200 Hz
Phase measurement error(degrees)	=	0.000 deg
Fractional err in amplitude measurement	=	0.0000
Time delay (latency) for control system	=	1.0E-06 s
Control update interval	=	1.0E-06 s
Gain constant for controller	=	0.55
Beam arrival real feedforward term	=	0.50E+10
Beam arrival imag feedforward term	=	0.13E+10
Amplifier bandwidth	=	1.0E+06
Measurement filter bandwidth	=	5.0E+05

In pulse rms phase err = 0.01953 deg
In pulse rms amplitude err = 0.00854 %



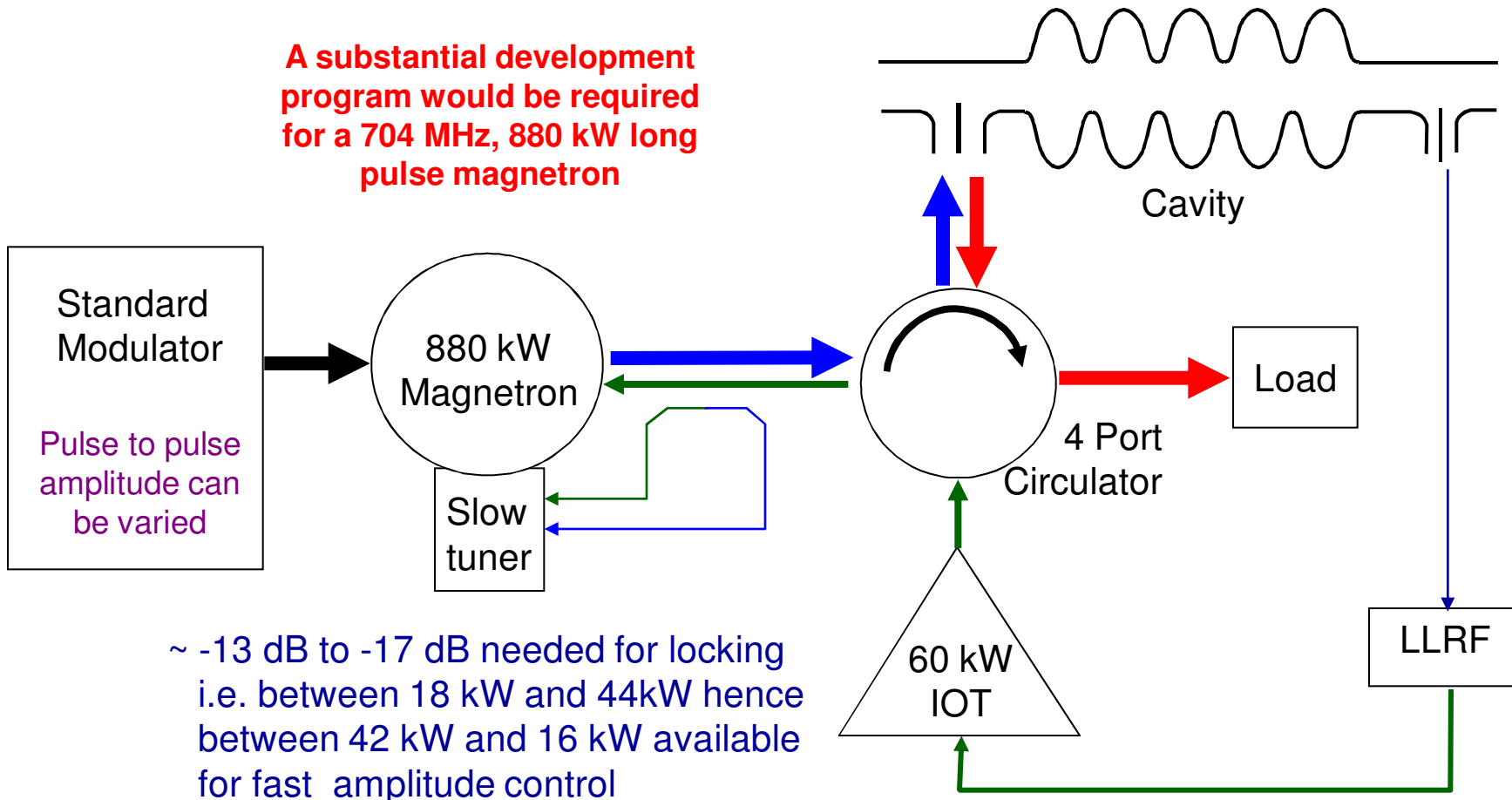


**Phase correct
at start of
bunch train**

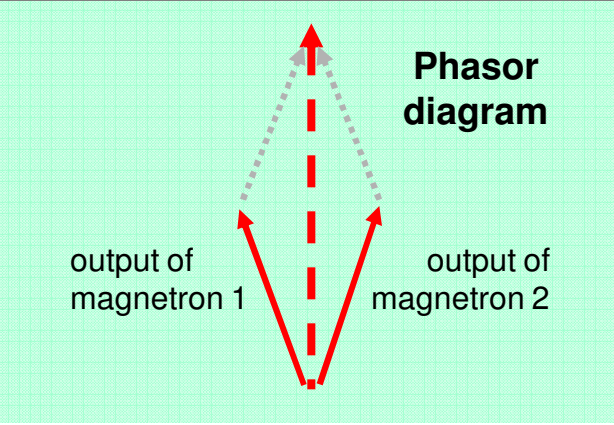
**Note that
microphonics start
with same phase as
before but as the
bunch arrives later
the cavity frequency
offset is greater and
the resultant phase
error is greater
despite the better
start.**

Permits fast phase control but only slow, full range amplitude control

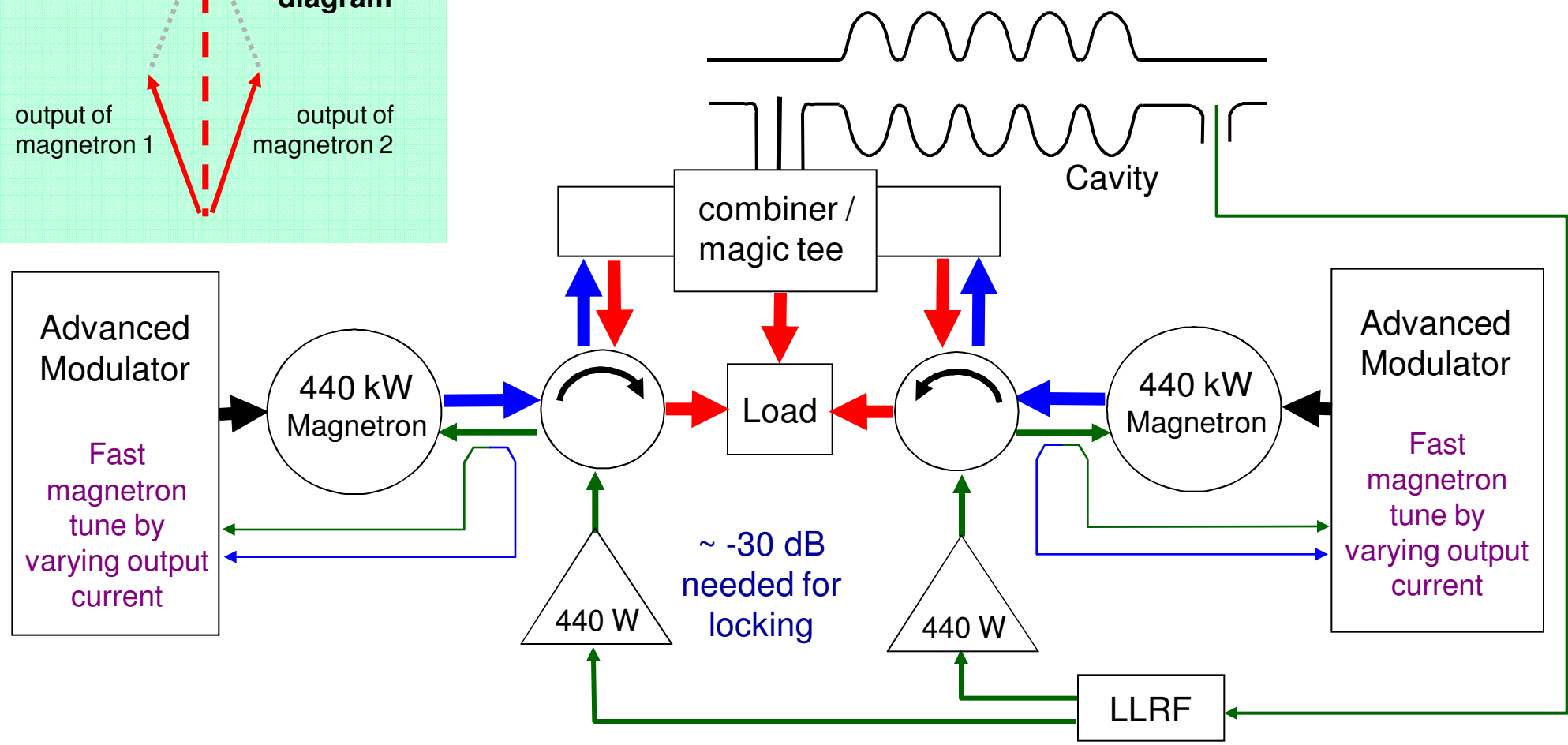
A substantial development program would be required for a 704 MHz, 880 kW long pulse magnetron



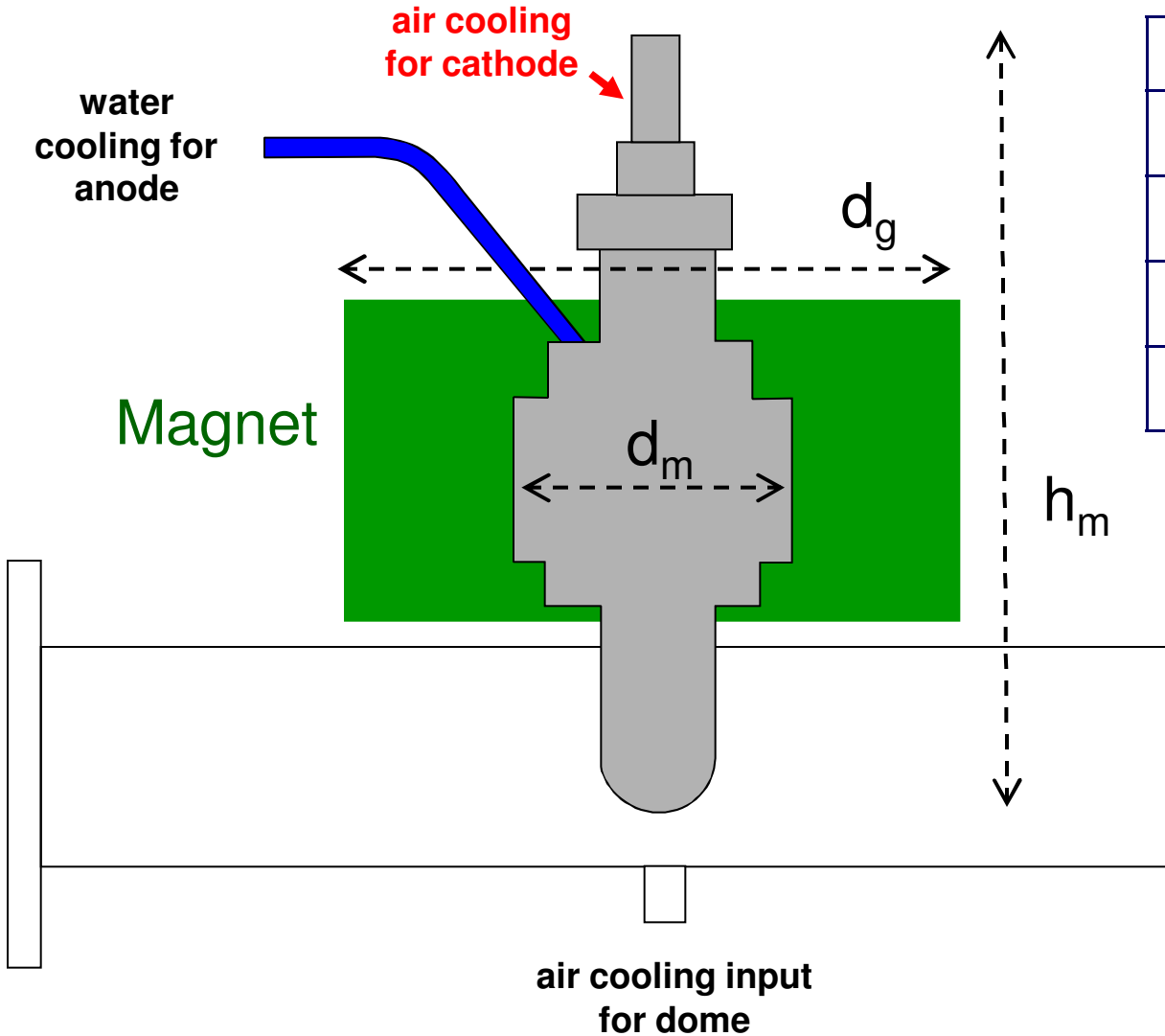
Could fill cavity with IOT then pulse magnetron when beam arrives



Permits fast full range phase and amplitude control



440 kW Magnetron design is less demanding than 880 kW design reducing cost per kW, and increasing lifetime and reliability.



	915 MHz	704 MHz
d_g	325 mm	~ 425 mm
d_m	125 mm	~ 165 mm
h_m	500 mm	~ 650 mm
€ tube	€ 8000	?

If magnetron design is similar to industrial design with similar tolerances and can be made on same production line then cost may not be much more

Cost Calculation 20 mA beam

20 mA beam		Two magnetrons per cavity	One Klystron per cavity	One Klystron four cavities	Notes
Tube Power	kW	220	440	1760	[1]
Duty cycle		0.05	0.05	0.05	[2]
Tube unit cost	k£	8	140 ?	260	[3]
Magnets, supplies and heater	k£	4 ?	20 ?	40 ?	
number of tubes		484	242	62	[4]
Tube total cost	k£	5,808 ?	38,720 ?	18,600	
Circulator unit cost	k£	9 ?	16 ?	30 ?	
Circulator cost	k£	4,356	3,872	1,860	[5]
HP phase shifter unit cost	k£	0	0	10 ?	[6]
Total phase shifter cost	k£	0	0	2,420	
Power of drive amplifier	W	300	30	120	[7]
Drive amplifier unit cost	k£	3.00 ?	0.60 ?	1.20 ?	
Number of drive amplifiers		484	242	62	[8]
Drive amplifier cost	k£	1,452	145	74	
Tube + drive + circulator cost	k£	11,616	42,737	22,954	
Modulator unit cost	k£	50 ?	100 ?	400 ?	[9]
Total modulator cost (Guess!)	k£	24,200 ?	24,200 ?	24,800 ?	[10]
Tube life	yrs	2 ?	20 ?	10 ?	[11]
Annual tube replacement cost		2904	1936	1860	[12]
Efficiency		0.88 ?	0.67 ?	0.67 ?	
Intalled RF power	kW	106480	106480	109120	
Power consumption	kW	6050	7946	8143	
Hours per year		4800	4800	4800	[13]
kWh cost	k£	0.00005	0.00005	0.00005	
Annual electricity cost	k£	1,452	1,907	1,954	
Cost after installation	k£	35,816	66,937	47,754	
Cost after 10 years	k£	79,376	105,368	85,898	

Status [14] [15] [16]

- [1] Amplitude control needs two magnetrons with phase difference
- [2] 50 Hz operation 1 ms pulse
- [4] beta 0.92 cavities =200, beta 0.65 cavities =42, use same power source for all
- [5] One circulator per tube - magnetron needs 4 port device
- [6] One High Power Phase Shifter per cavity
- [7] Use -28.5 dB magnetron drive and -42 dB Klystron drive
- [8] One per tube
- [9] One modulator per tube (Magnetron ~ 8 amps at 32 kV)
- [10] Flat cost per kW assumed but magnetron uses half voltage hence maybe cheaper
- [11] The 440 kW Klystron is assumed to be underated hence the good life
- [12] Magnetron refurbishment would save much of this cost
- [13] 200 days
- [14] Unproven
- [15] Available
- [16] Needs development of high power phase shifter for 50Hz operation

Cost Calculation for 40 mA beam

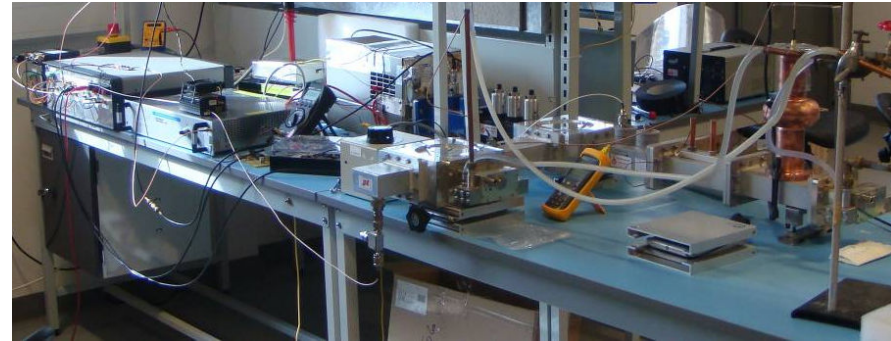
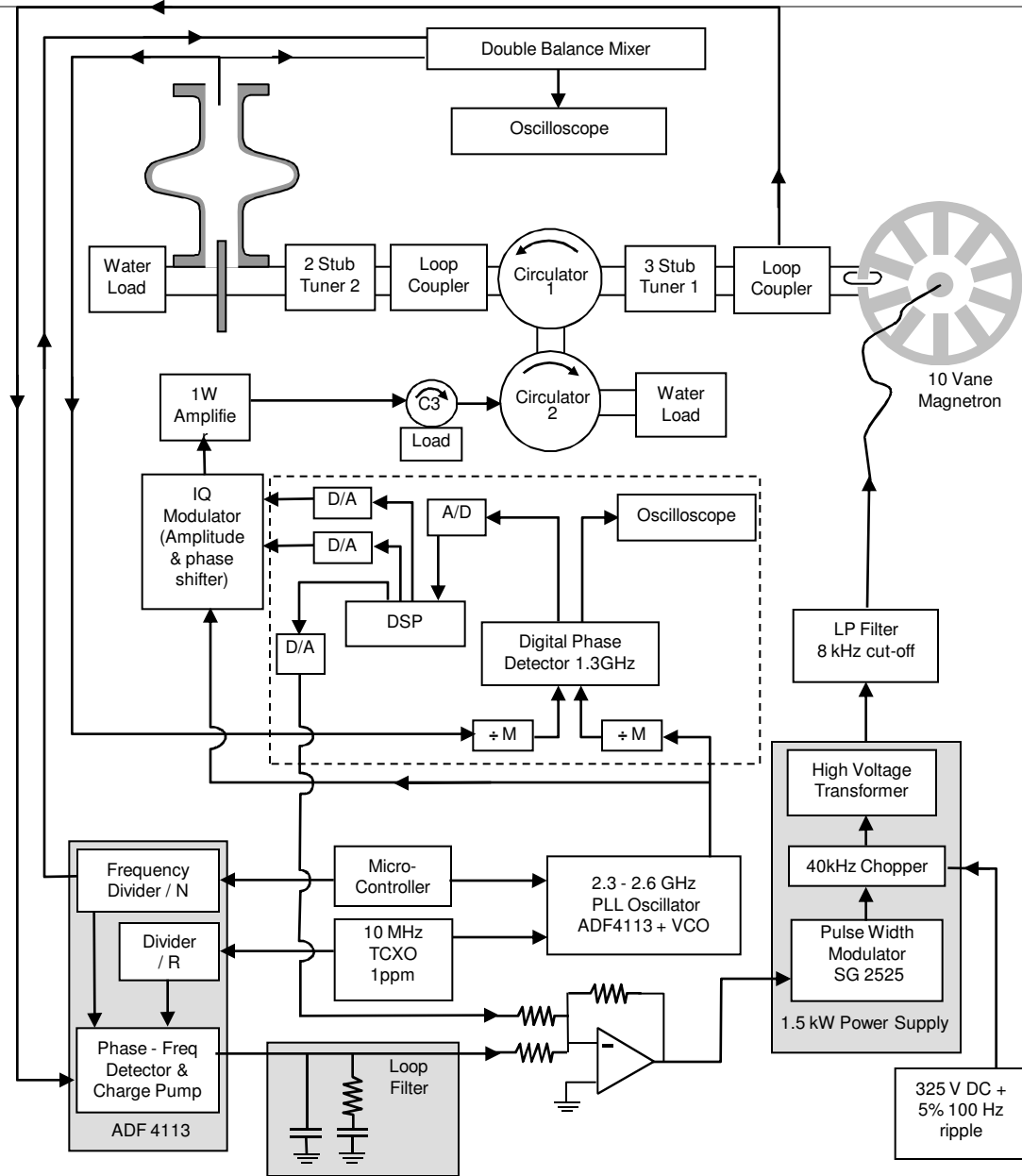
40 mA beam		Two magnetrons per cavity	One Klystron per cavity	One Klystron four cavities
Tube Power	kW	440	880	3250
Duty cycle		0.05	0.05	0.05
Tube unit cost	k£	16	280 ?	520
Magnets, supplies and heater	k£	4 ?	20 ?	40 ?
number of tubes		484	242	62
Tube total cost	k£	9,680 ?	72,600 ?	34,720
Circulator unit cost	k£	14 ?	24 ?	45 ?
Circulator cost	k£	6,776	5,808	2,790
HP phase shifter unit cost	k£	0	0	30 ?
Total phase shifter cost	k£	0	0	7,260
Power of drive amplifier	W	600	60	240
Drive amplifier unit cost	k£	3.00 ?	0.60 ?	1.20 ?
Number of drive amplifiers		484	242	62
Drive amplifier cost	k£	1,452	145	74
Tube + drive + circulator cost	k£	17,908	78,553	44,844
Modulator unit cost	k£	100 ?	200 ?	800 ?
Total modulator cost (Guess!)	k£	48,400 ?	48,400 ?	49,600 ?
Tube life	yrs	2 ?	20 ?	10 ?
Annual tube replacement cost		4840	3630	3472
Efficiency		0.88 ?	0.67 ?	0.67 ?
Intalled RF power	kW	212960	212960	201500
Power consumption	kW	12100	15893	15037
Hours per year		4800	4800	4800
kWh cost	k£	0.00005	0.00005	0.00005
Annual electricity cost	k£	2,904	3,814	3,609
Cost after installation	k£	66,308	126,953	94,444
Cost after 10 years	k£	143,748	201,395	165,254

Status

[14]

[15]

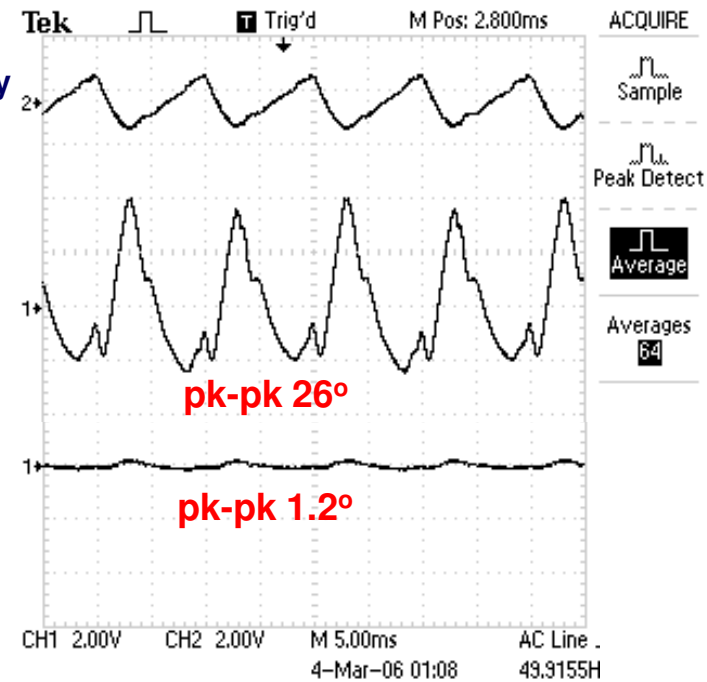
[16]



Power supply ripple

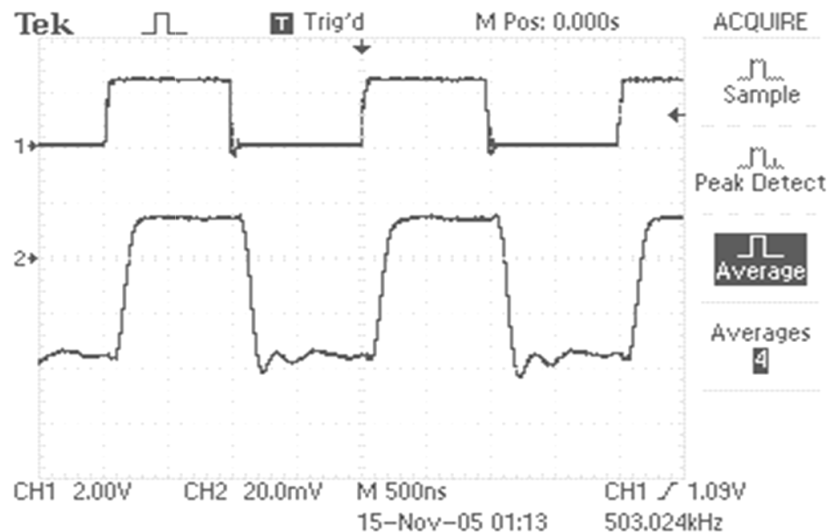
Magnetron phase no LLRF

Magnetron phase with LLRF

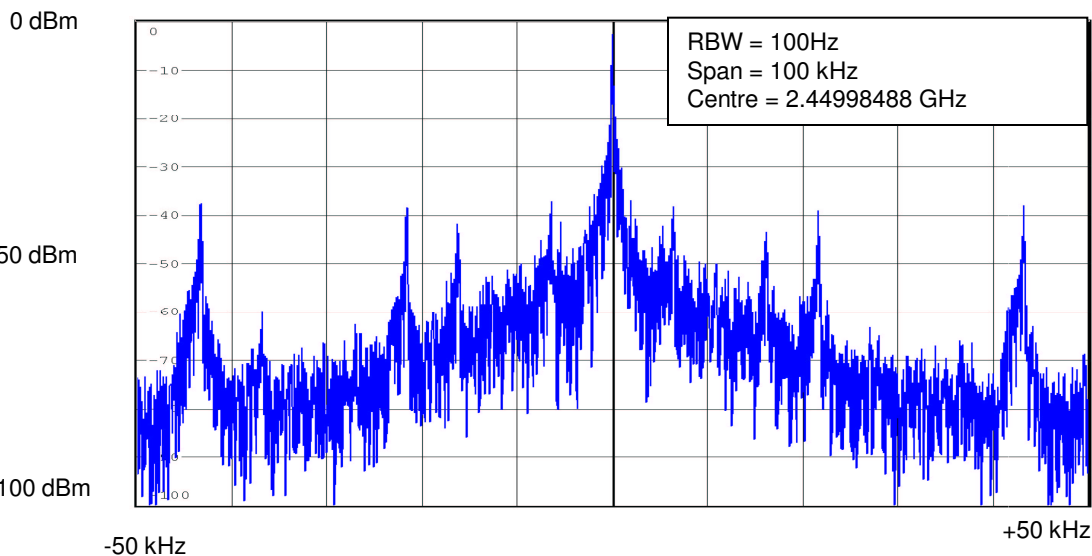


Tahir I., **Dexter A.C** and Carter R.G. "Noise Performance of Frequency and Phase Locked CW Magnetrons operated as current controlled oscillators", IEEE Trans. Elec. Dev, vol 52, no 9, 2005, pp2096-2130

Tahir I., **Dexter A.C** and Carter R.G., "Frequency and Phase Modulation Performance on an Injection-Locked CW Magnetron", IEEE Trans. Elec. Dev, vol. 53, no 7, 2006, pp1721-1729



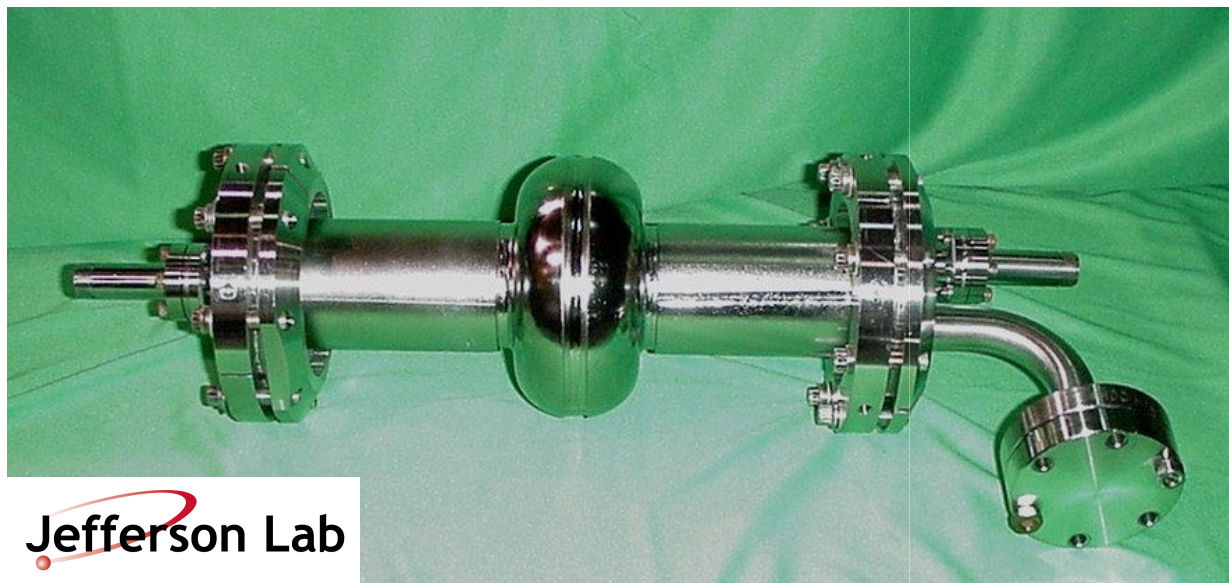
Phase shift keying the magnetron



Locked spectral output

Lancaster has successfully demonstrated the injection locking of a cooker magnetron with as little as -40 dB injection power by fine control the anode current to compensate shifts in the natural frequency of the magnetron.

- Commission the development of a 704MHz Magnetron (440kW)
- Procure standard modulator
- Set up test station with IOT as drive amplifier
- Understand locking characteristics of new magnetron
- Commission advanced modulator with in-pulse current control
- Establish minimum locking power
- Establish two magnetron test stand
- Develop LLRF for simultaneous phase and amplitude control



Demonstration of CW 2.45 GHz magnetron driving a specially manufactured superconducting cavity at JLab due later this month should stimulate more interest.