

A 3D wireframe model of a Machine Detector Interface. The model consists of several cylindrical components, some of which are connected by flexible, braided tubes. The central part of the model is a large, cylindrical component with a curved top surface. Two vertical cylindrical tubes are positioned on either side of this central component. A horizontal cylindrical tube passes through the center of the central component. A flexible, braided tube enters from the top left and exits from the bottom right. Another flexible, braided tube enters from the bottom left and exits from the top right. The entire model is rendered in a yellow wireframe style against a dark blue background.

Machine Detector Interface

Lau Gagnon / CERN-EN

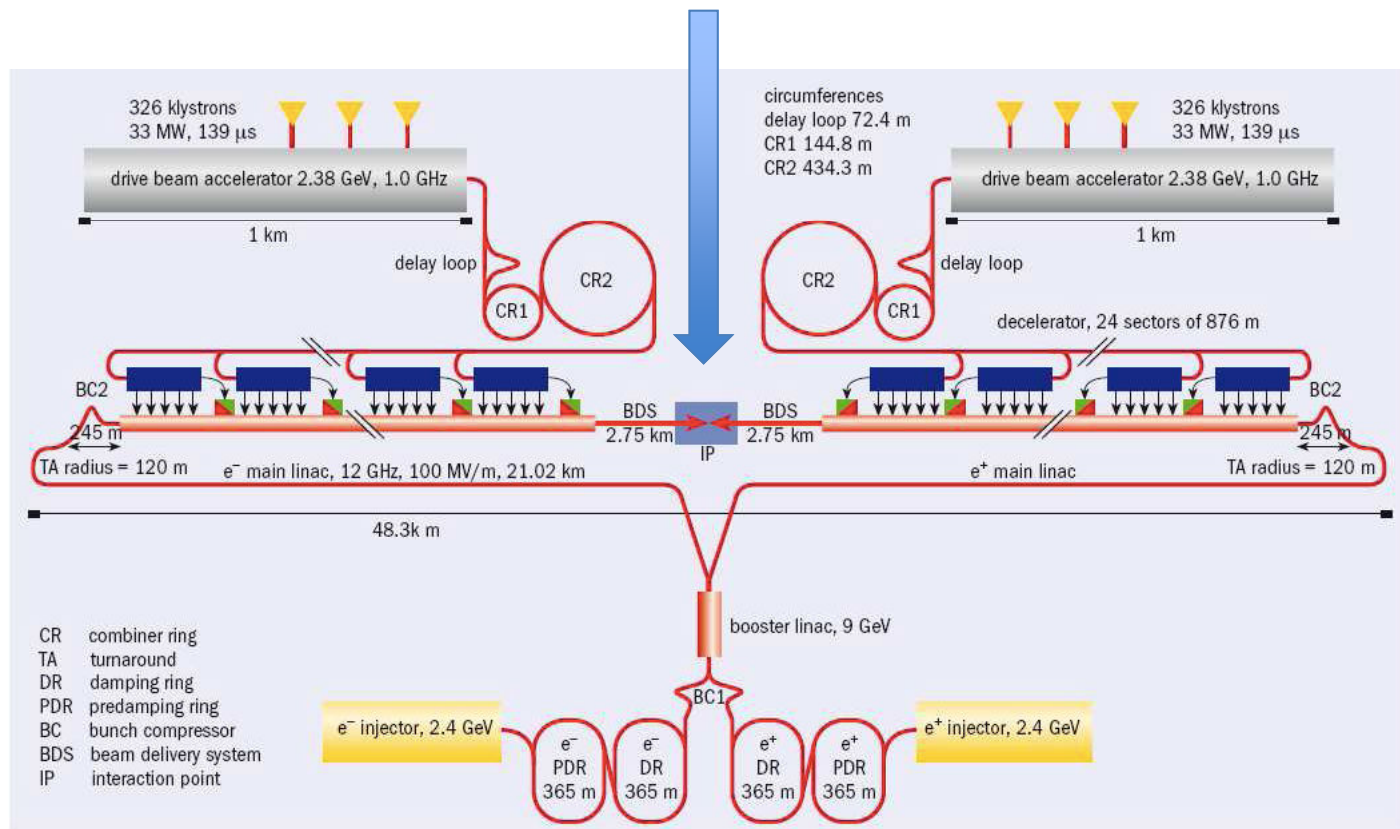
Overview

- ❑ Introduction to Machine Detector Interface
- ❑ QD0 magnet design
- ❑ QD0 stabilisation and integration
- ❑ Backgrounds
- ❑ Post-collision line
- ❑ IP Feedback
- ❑ Other items
- ❑ Conclusion

What is the MDI

The MDI is the part of the CLIC facility (approximately) inside the detector cavern, i.e. the area in which there is a strong coupling of technical sub-systems of the machine and of the physics detectors.

The lines for the spent beams shall also be considered part of the MDI.



CLIC PARAMETERS

Parameter	ILC	CLIC	Impact on MDI
Max. Center of Mass energy [GeV]	1000	3000	Detector design, backgrounds
Luminosity $L_{99\%}$ [$\text{cm}^{-2} \text{sec}^{-1}$]	$2 \cdot 10^{34}$	$2 \cdot 10^{34}$	Instrumentation
Bunch frequency [Hz]	5	50	
Bunch spacing [ns]	369	0.5	Background, IP feedback
# Particles per bunch	$2 \cdot 10^{10}$	$3.7 \cdot 10^9$	
# Bunches per pulse	2670	312	
Bunch train length [μs]	985	0.156	
Beam power per beam [MW]	9	14	Spent beam line
Bunch length [μm]	300	44	
Crossing angle [mrad]	14	20	
Core beam size at IP horizontal σ_x^* [nm]	639	45	
Core beam size at IP vertical σ_y^* [nm]	5.7	0.9	QD0, stabilisation

MDI Priorities

Highest priority for the work until end 2010 are those subjects linked to the “CLIC critical feasibility items”, nota bene:

- Choice of the **magnet technology for the FF magnets**
- **Integration of these magnets** into the detectors, and their alignment
- Feasibility study of **sub-nm active stabilization** of these magnets
- **Luminosity instrumentation**
- **Spent beam disposal**
- **Beam background backsplash** from the post-collision collimators and dumps into the detector
- **Intrapulse-Beam feedback systems** in the interface region

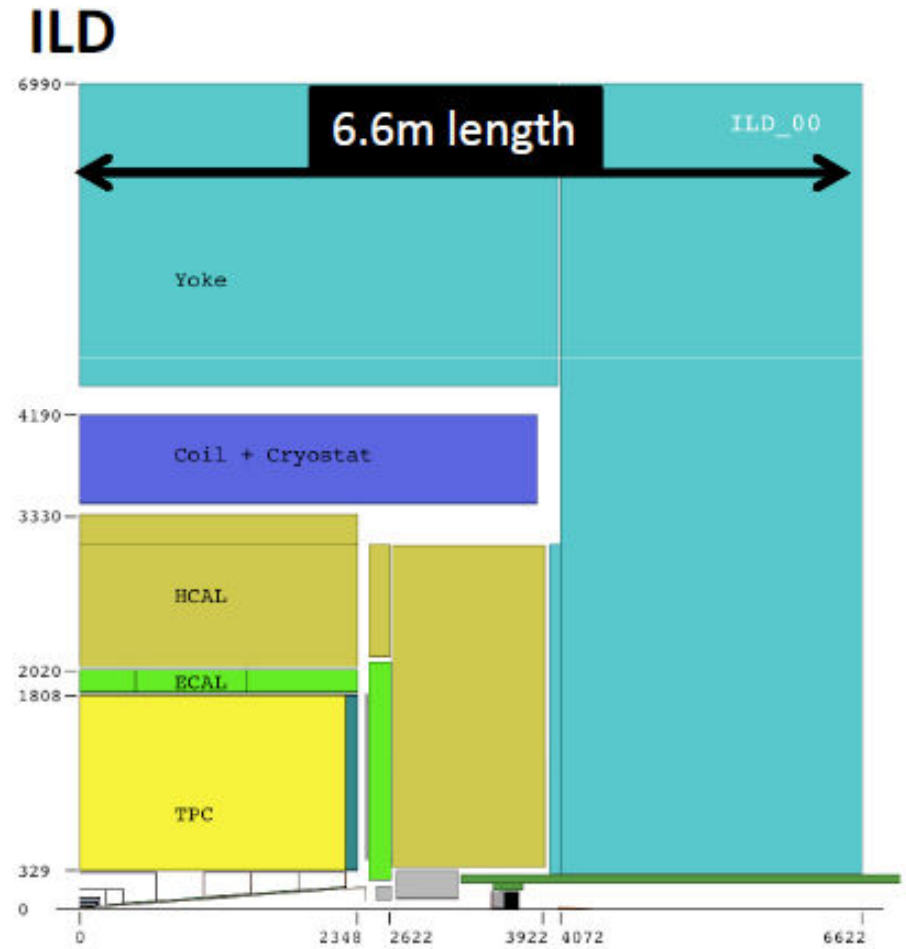
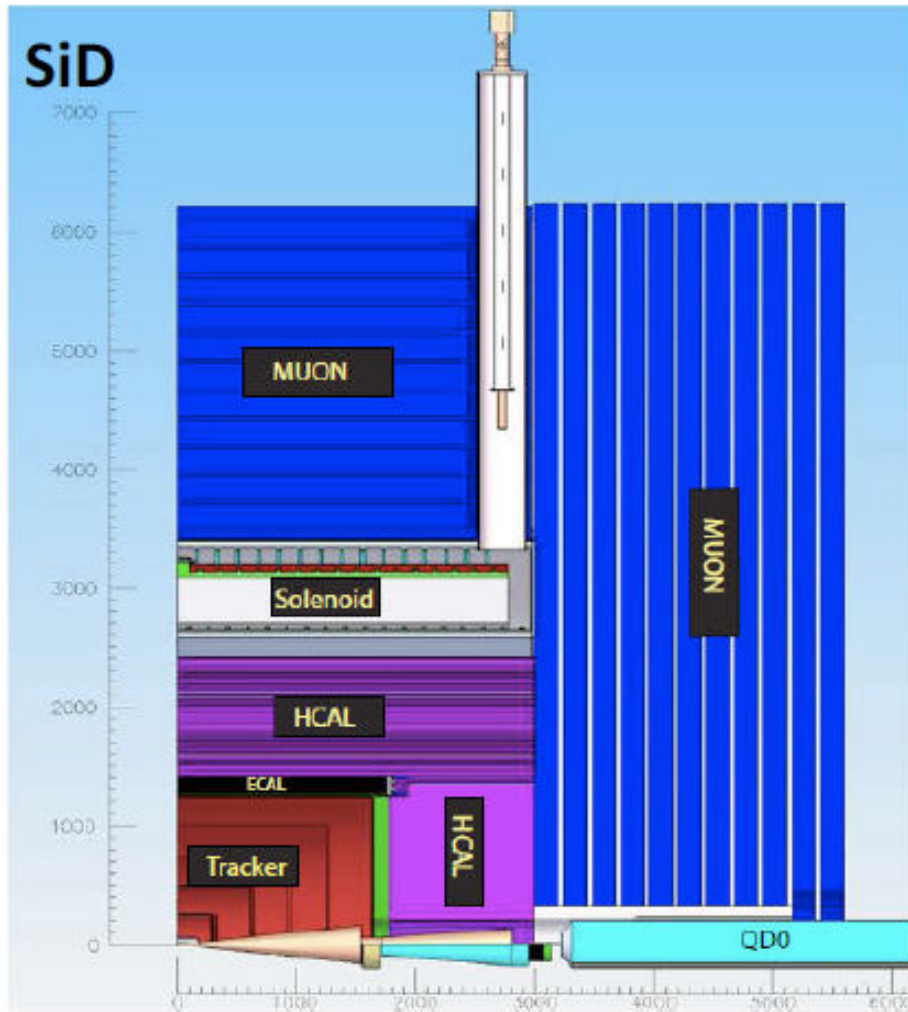
From the CLIC MDI working group mandate

Other items to be addressed in MDI:

- ❑ Issues where the beam delivery system (BDS) influences the beam/**background** conditions for the detector
- ❑ Issues where the BDS physically impacts on the detector
- ❑ Beam **background** and its impact on the forward (det.+accel.) elements, including **backsplash of background particles** from one hardware element to the surrounding elements
- ❑ Beam pipe, beam vacuum and vacuum infrastructure in the interface region
- ❑ Radiation environment and radiation shielding in the interface region
- ❑ Cryogenic operational safety issues in the interface region
- ❑ Magnetic environment in the interface region (shielding of FF quadrupole, correction coils, anti(-DID), stray fields from the detector, etc.)
- ❑ Overall mechanical integration (including the routing of services) in the interface region
- ❑ Pull-push elements and scenarios (detector-to-detector interface)
- ❑ Cavern layout and services (handled principally under CES WG)

From the CLIC MDI working group mandate

ILC Detector Concepts



Andre Sailer - LCD Layout - MDI

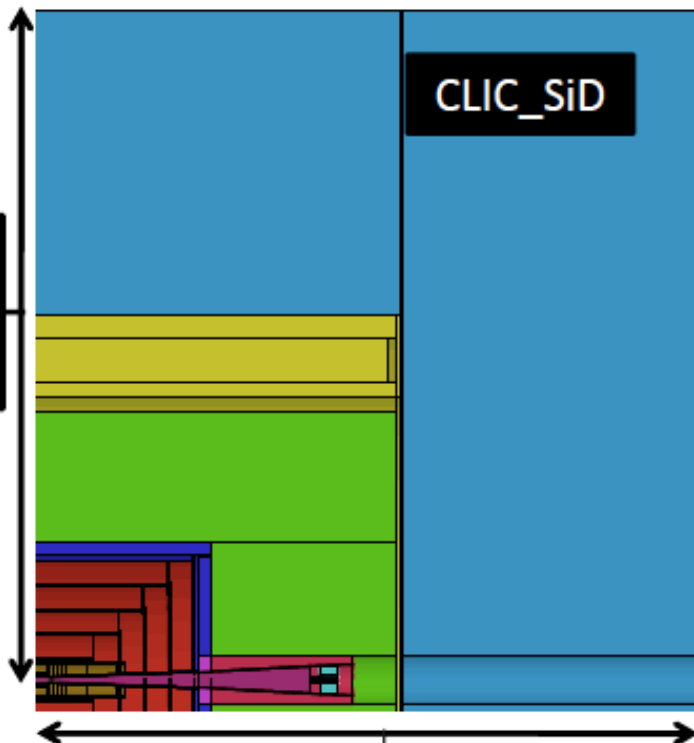
CLIC09 - Machine Detector Interface

From ILC to CLIC Detectors

- Detectors for CLIC (3 TeV) are based on the two Detectors for ILC (500GeV)

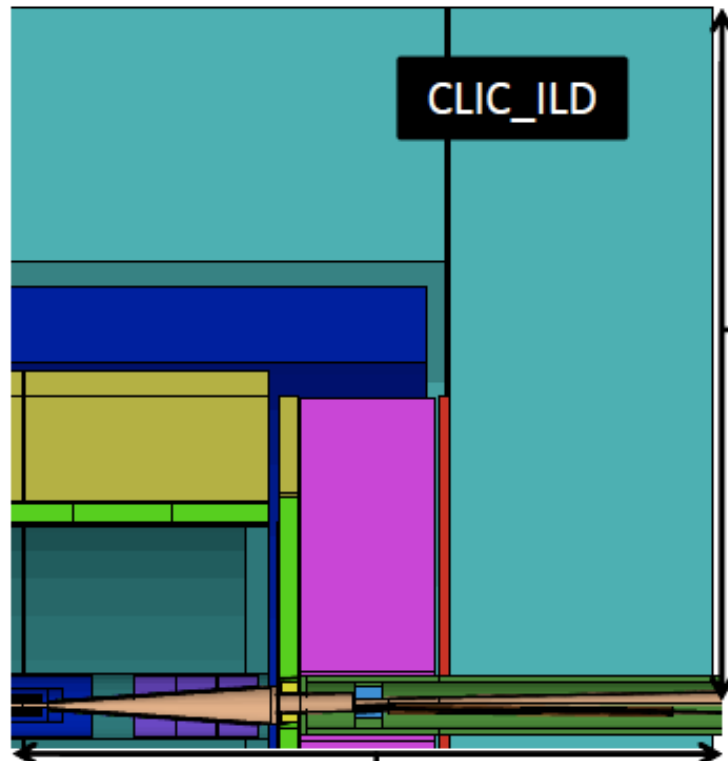
Changes:

- 20 mrad crossing angle (instead of 14 mrad)
- Vertex Detector, due to Beam-Beam Background
- Hadron Calorimeter (due to higher energetic Jets)
- For CLIC_SiD: Moved Coil to 2.9m (CMS Like)



Length: 6.9m

Andre Sailer - LCD Layout - MPI



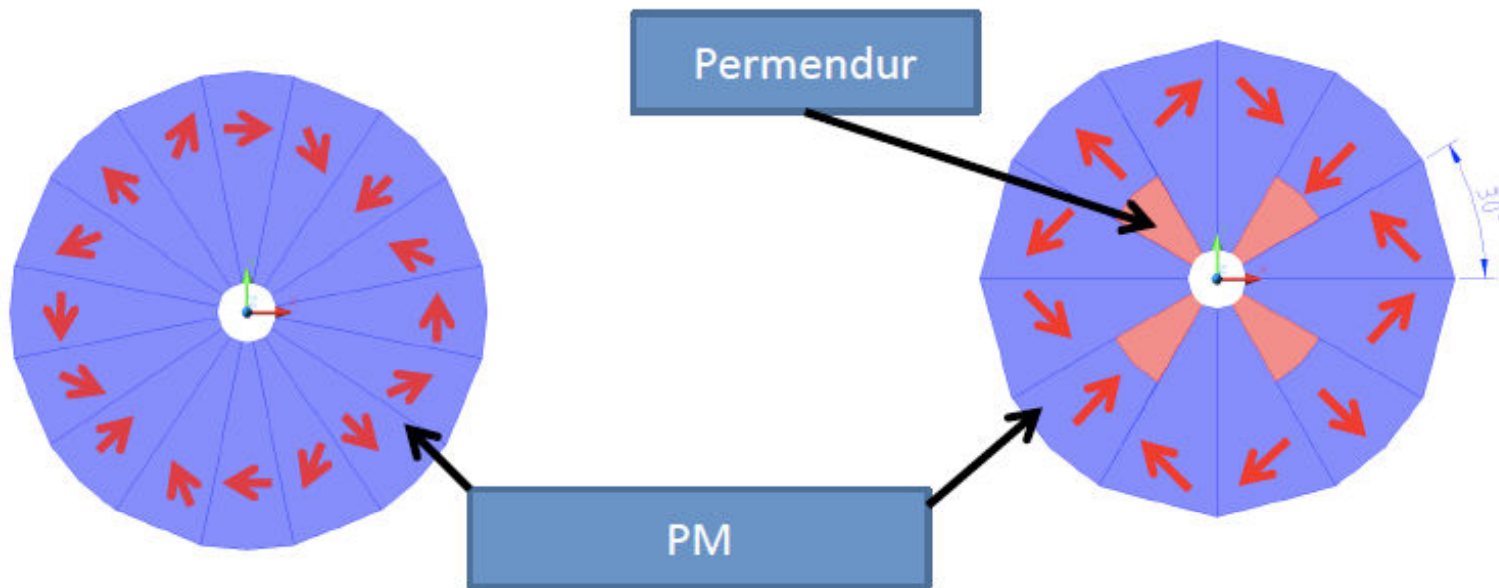
Length: 7.1m (not to Scale)

Final Focus Quadrupole (QD0): Parameters

Parameter	Value
Gradient [T/m]	575
Length [m]	2.73
Aperture radius [mm]	3.83
Outer radius [mm] – <i>for spent beam</i>	< 50
Peak field [T]	2.20
Tunability of gradient from nominal	[-10%, 0%]

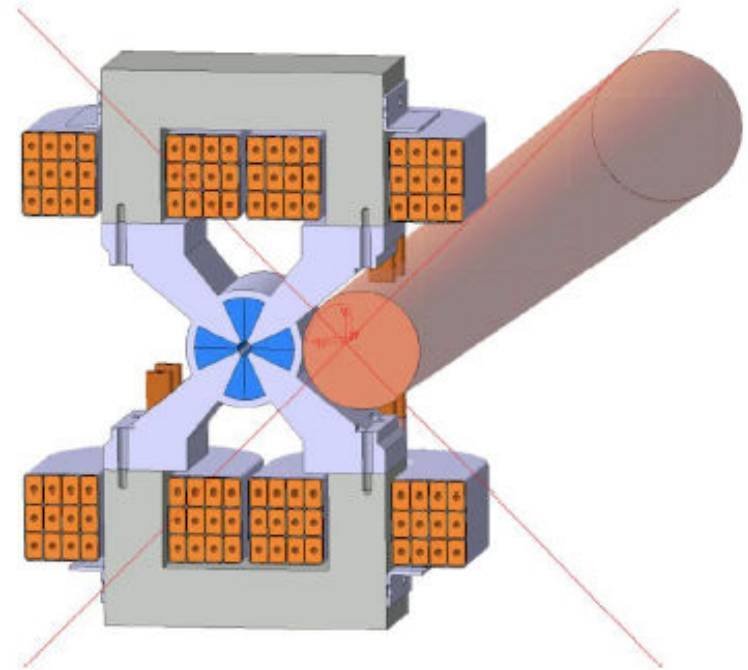
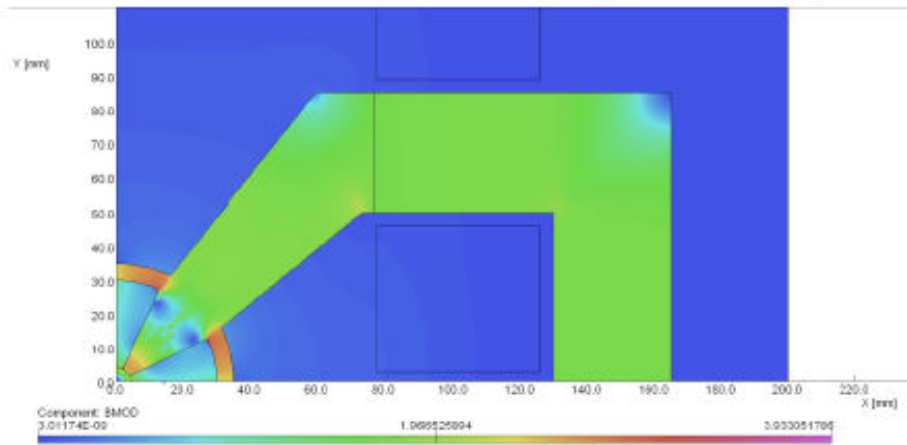
*A conceptual design has recently been proposed by TE-MSC
see presentation by M.Modena tomorrow*

“Halbach” vs. “Super Strong” performances:



	R=3.8 [mm] (no chamber)		R=4.125 [mm]	
Material	Sm ₂ Co ₁₇	Nd ₂ Fe ₁₄ B	Sm ₂ Co ₁₇	Nd ₂ Fe ₁₄ B
Grad [T/m] “Halbach”	450	593	409	540
Grad [T/m] “Super Strong”	564	678	512	615

“Hybrid” approach, Version 2:



	$I_w=5000$ [A]
Grad [T/m] $\text{Sm}_2\text{Co}_{17}$	531
Grad [T/m] $\text{Nd}_2\text{Fe}_{14}\text{B}$	599

- The presence of the “ring” decrease slightly the Gradient (by 15-20 T/m) but will assure a more precise and stiff assembly
- EM Coils design will permit wide operation conditions (with or without water cooling) that can be critical for performances (ex. stabilization)

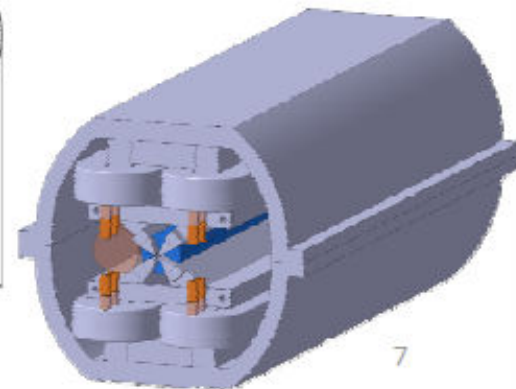
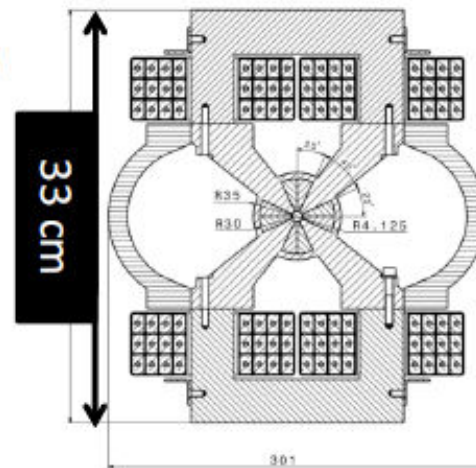
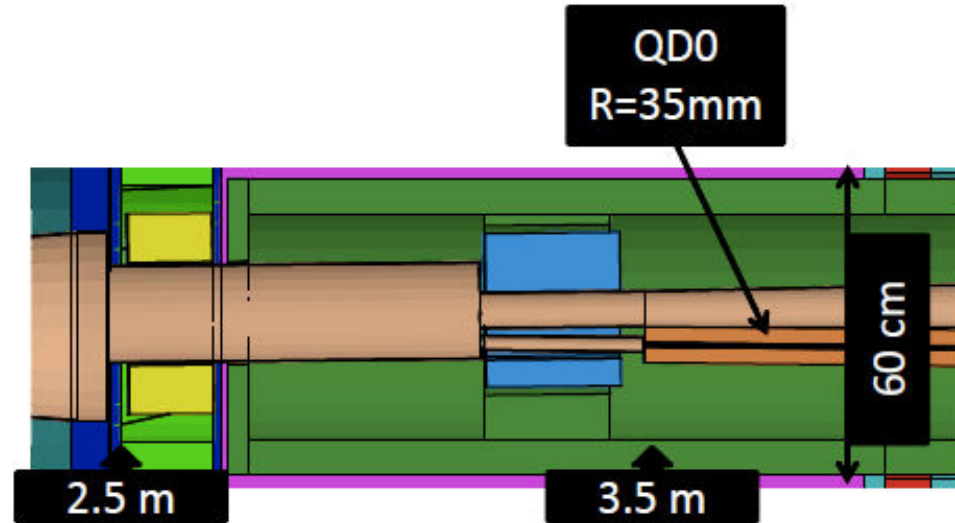
QD0

- Inner radius for Endcaps

- CLIC_ILD: 35 cm
- CLIC_SiD: 26 cm
- Add ~10 cm masking
 - Protect Calorimeter
- Anti-Solenoid?

- QD0 Prototype

- 33cm height
- – Should fit into forward region
- Easier for CLIC_ILD than for CLIC_SiD
- – How is the Magnet attached to support structure?
- – How far do the coils extend beyond 3.5 m?



QD0 Stabilisation

- ❑ Any movement (vibration) of the QD0 quadrupole would lead to a displacement of the beam at the IP comparable to the movement of the magnet
- ❑ As the vertical spot size is about 1 nm, the quadrupole position must be stabilised to 0.15 nm in the vertical plane and 5 nm in the horizontal plane for frequencies > 4 Hz.
- ❑ Beam-beam feedback will help.
- ❑ A R&D program is under way for the stabilisation, based on passive and active stabilisation and cantilever based stabilisation.
- ❑ The integration in the experiment (push-pull) is still an open issue. Studies are under way.
- ❑ A review of stabilisation options is planned around the end of the year.
- ❑ In case the $L^*=3.5$ m (present baseline) option seems unrealistic, larger L^* values may have to be considered for the CDR

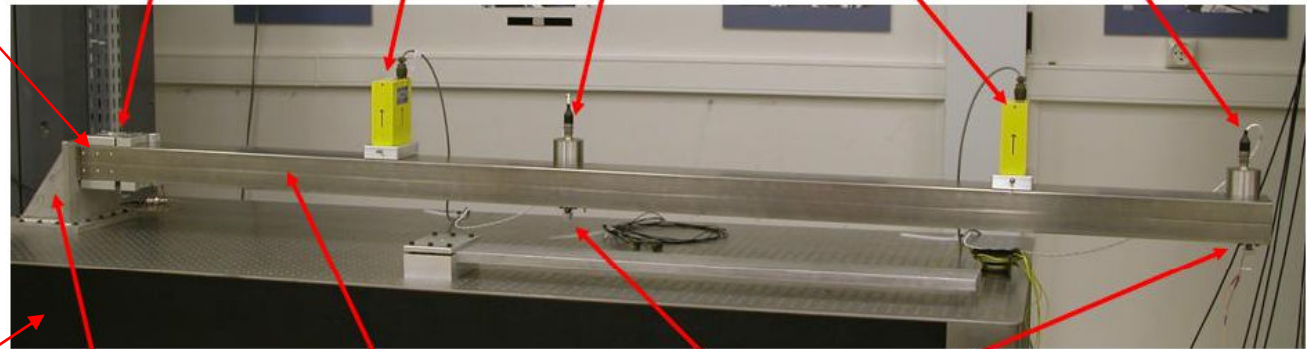
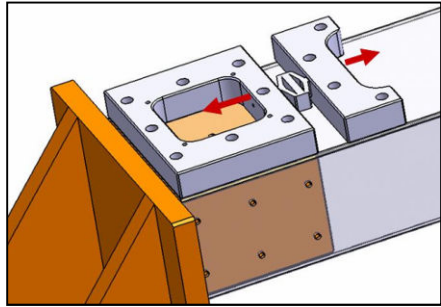
See presentation by A.Jeremie in the parallel session tomorrow

Achieved performance

LAPP active system for resonance rejection

Actuator in flexion

Seismic sensor
(accelerometer and velocity sensor)

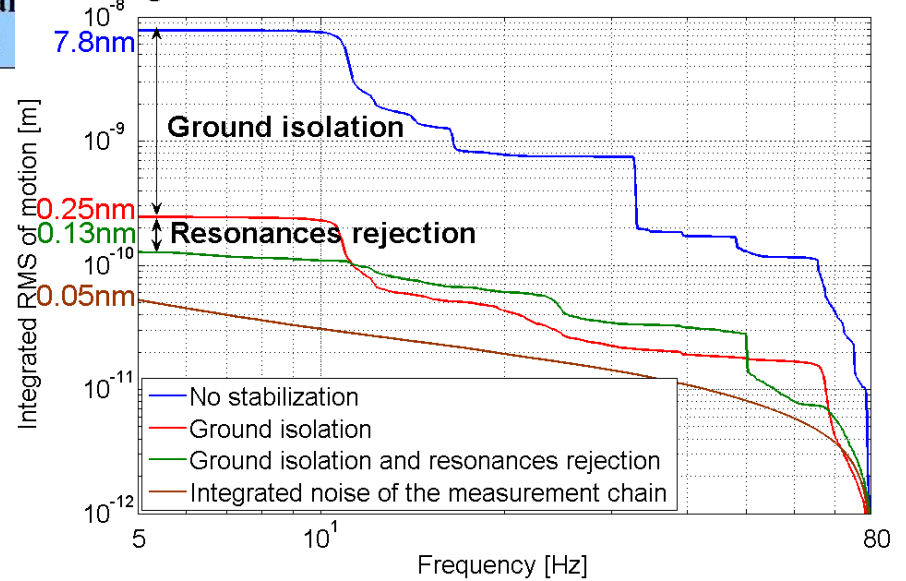


Clamping

Mechanical structure

CERN TMC active table for isolation

Integrated RMS of the beam motion between 5Hz and 80Hz

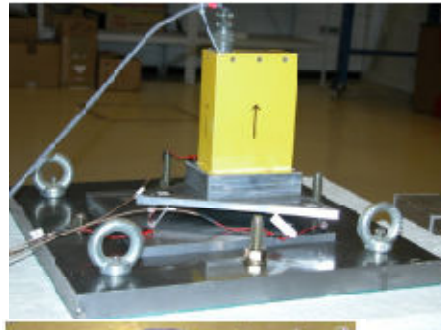


➤ The two first resonances entirely rejected

➤ Achieved integrated rms of 0.13nm at 5Hz

Current work

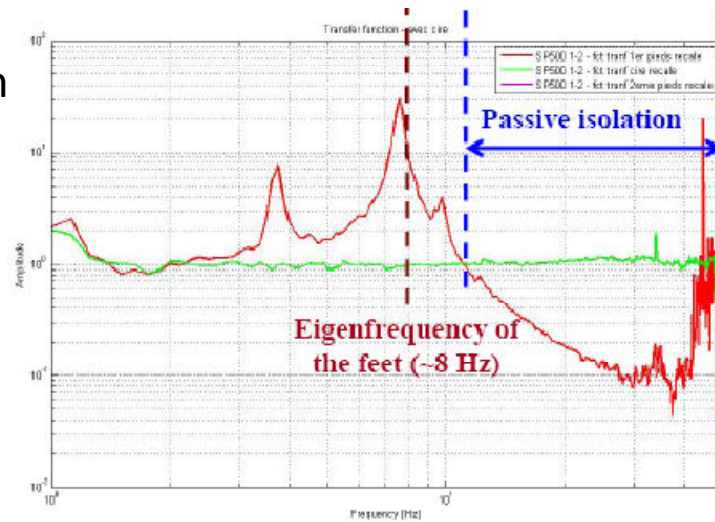
Replace big stabilisation table by a compact passive+active stabilisation system



Active system



Passive system



Instrumentation study (sensors and actuators)

- **Seismometers** (geophones)

- **Accelerometers** (seismic - piezo)

Velocity

Acceleration

electrochemical



Streckeisen
STS2



Guralp
CMG 3T



Guralp
CMG 40T



Eentec
SP500



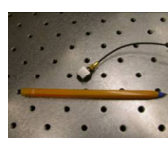
PCB
393B31



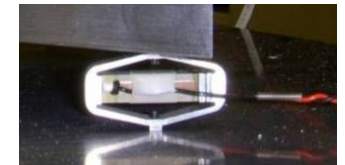
Endevco
86



PCB
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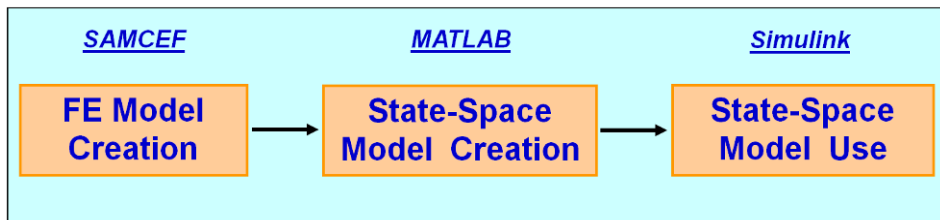
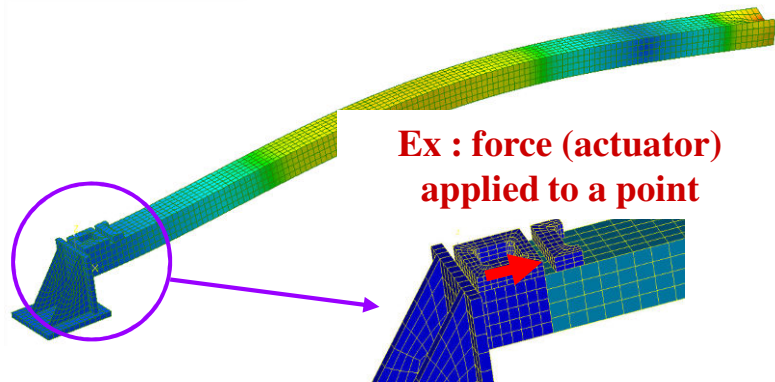


B&K
450B3

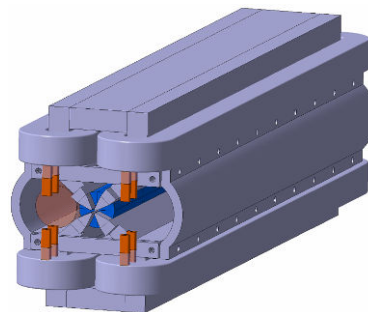


Current work

Simulations

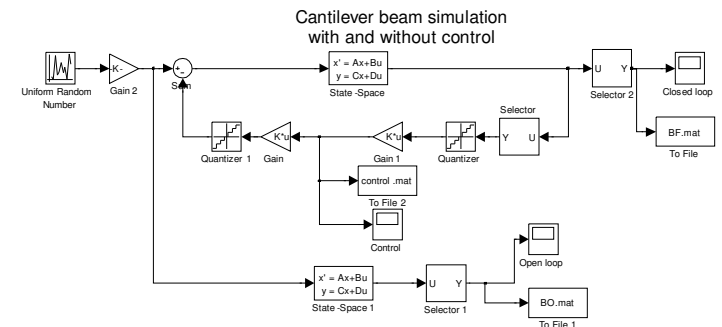
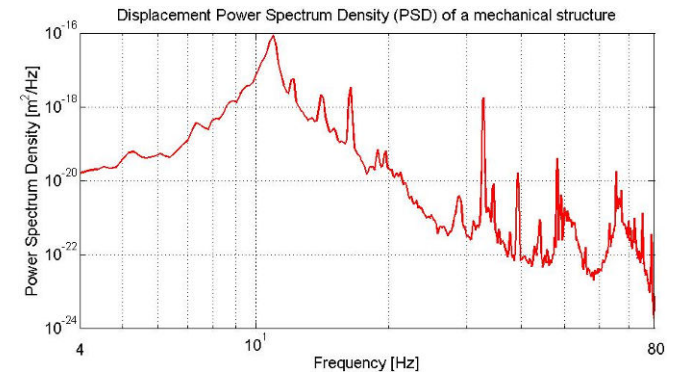


FF magnet design



Evgeny Solodko

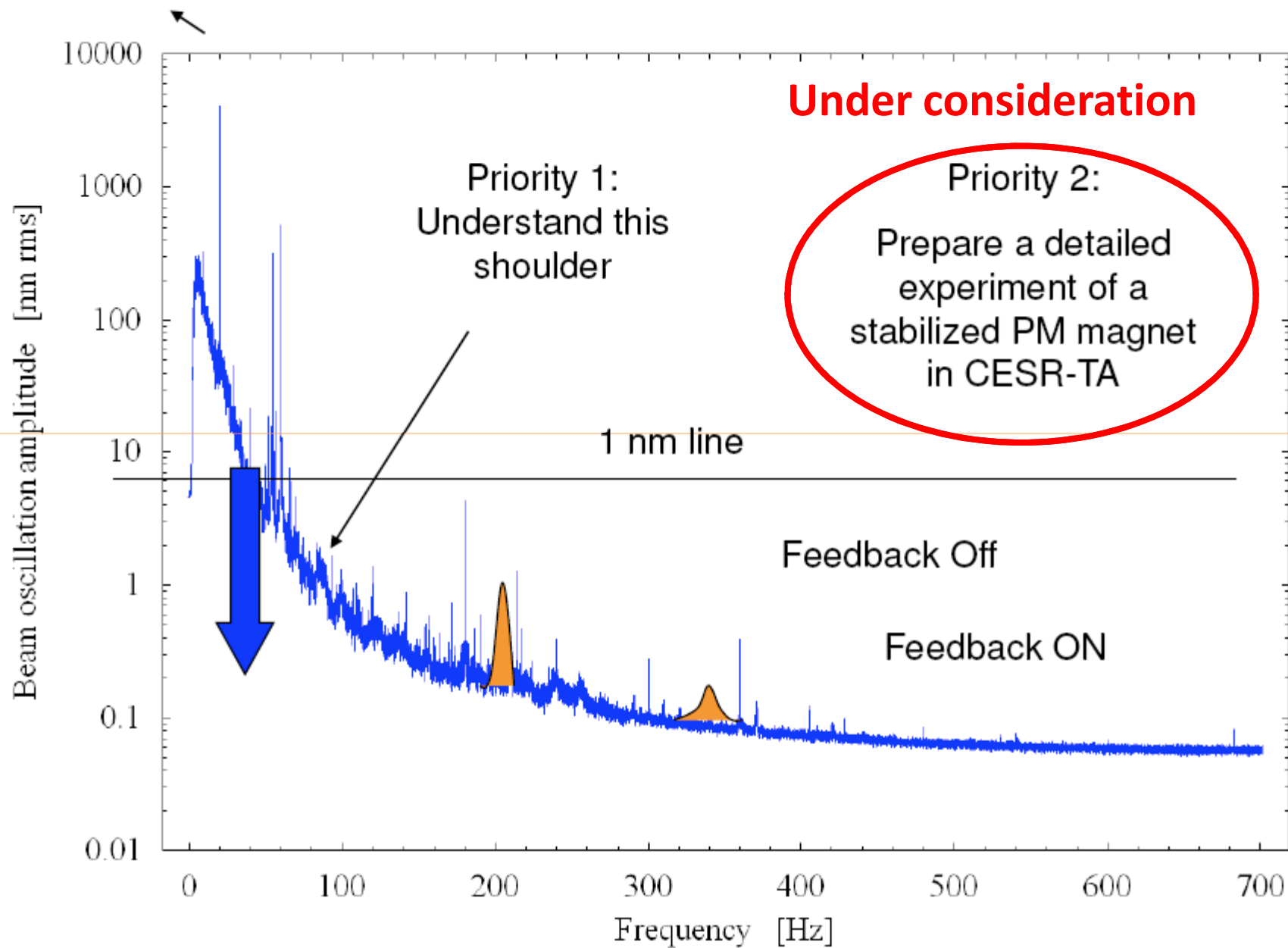
Feedback development



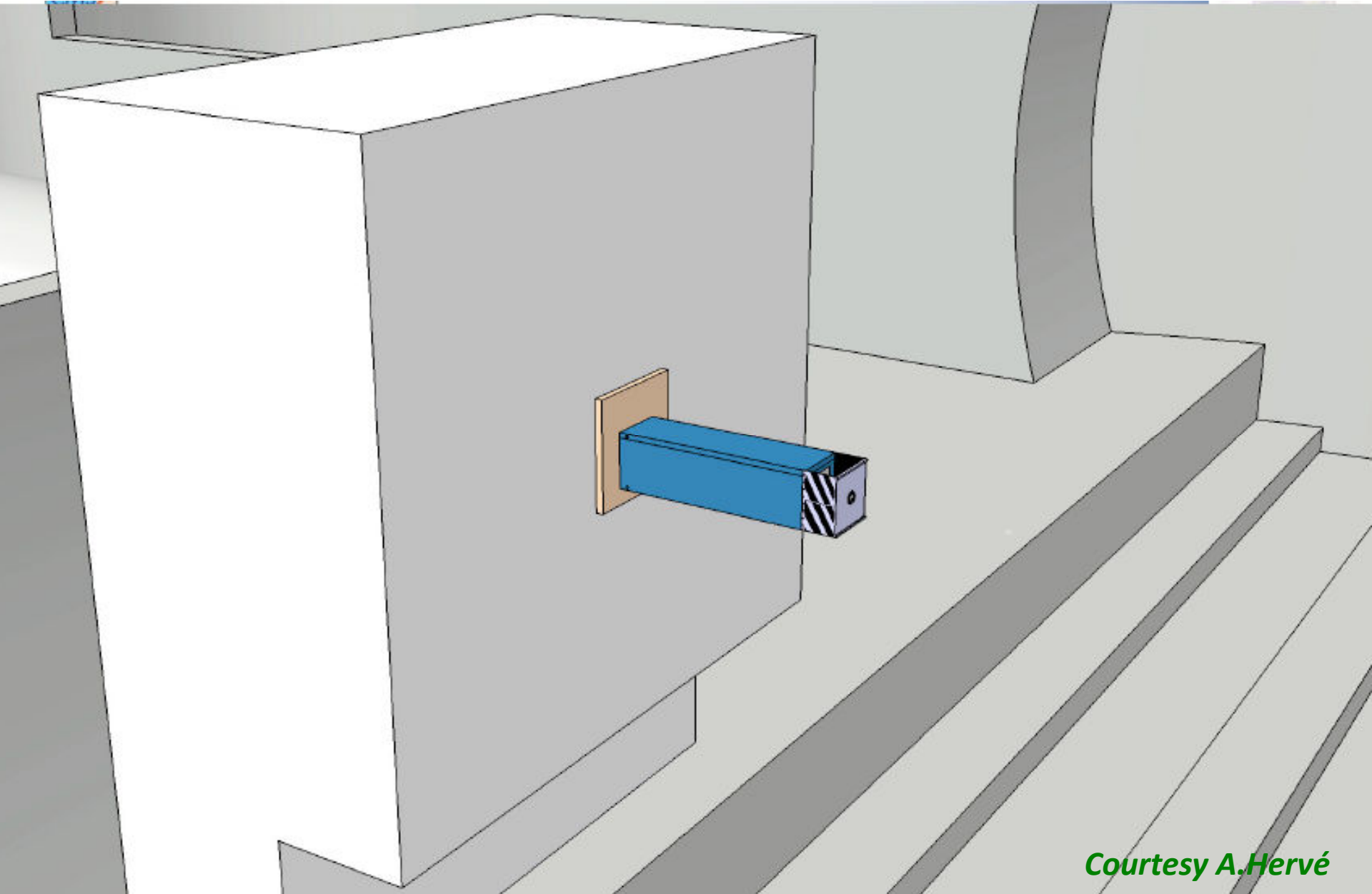
Different strategies studied:

- A knowledge only at strategic points
- A local model for the disturbances amplified by eigenfrequencies.
- A complete model

Perspectives for the future



QD0 Integration concept: first ideas



Courtesy A.Hervé

Vibration measurements (e.g. recently in CMS cavern, with cooling off by Artoos, Guinhard) suggest once more that:

- ❑ The QD0 quadrupole shall NOT be suspended from the detector
- ❑ However, it must penetrate in the experiment to maintain peak luminosity
- ❑ The QD0 supporting system must be strengthened (and shortened?)

Solutions may exist if opening the experiment on the IP is abandoned.

This implies that special efforts must be made in the machine and experiment, insulating e.g. rotating machines and water pipes mechanically

See presentation by A.Hervé tomorrow

BDS/MDI IMPACT ON DETECTOR, BACKGROUNDS

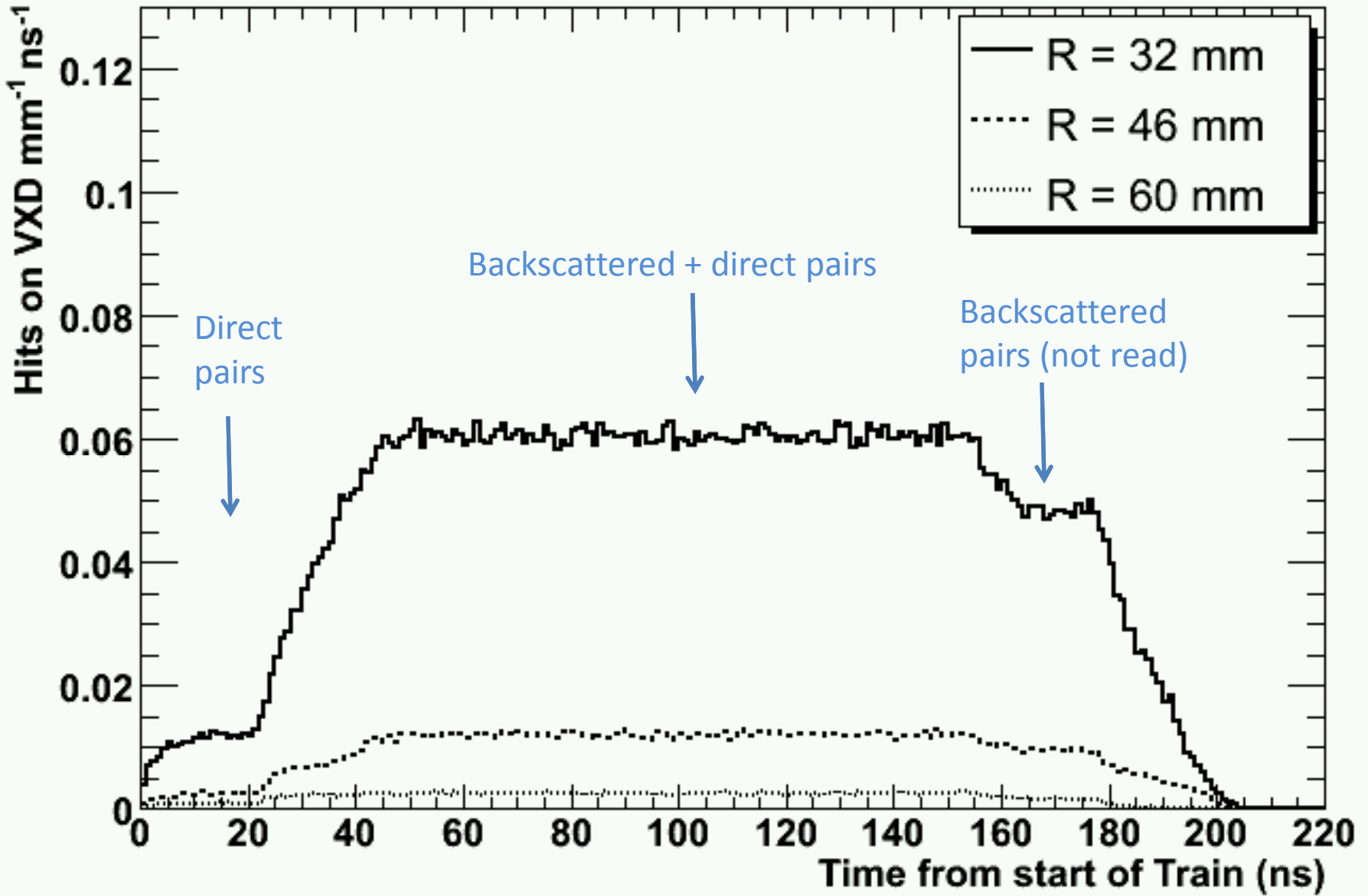
Various effects occurring in the Beam Delivery System and Interaction Region impact significantly on luminosity, backgrounds and detector performance.

Effect	Consequences	How to deal with
Coherent pairs	Main background. Tails in CM energy Blow-up, e^+e^+ , e^-e^-	Spent beam Crossing angle Detector design
Incoherent pairs	Backgrounds, e^+e^+ , e^-e^-	Detector
$\gamma\gamma \rightarrow$ hadrons	Backgrounds, radiation	Horiz. beam size at IP
Neutrons from dumps	Background via backscattering through spent beam aperture	Masks? Dump design and location
Muons from collimation	Backgrounds, e.g. catastrophic Bremsstrahlung	Magnetic shielding
Solenoid field + crossing angle	Couples to beam, luminosity reduction	Anti-solenoid <i>Crab cavities</i>

Pair production - Spent beam line

- ❑ Beam-beam interaction blows up & disrupts particles of opposite sign of main beam
- ❑ Pair production limits the minimum radius of the vertex detector
- ❑ Backscattering would cause serious background and radiation problems for the detector
- ❑ Therefore particles leaving the IP at up to 10 mrad must be transported away cleanly
- ❑ The energy contained in the outgoing beam is huge (14 MW) and must be dumped properly. A dump baseline design exists (ILC) but remains to be validated.
- ❑ The spent beam lines also houses instrumentation for luminosity monitoring, the background conditions for these detectors must be optimised
- ❑ Neutrons in the spent beam line and from the dumps remain to be simulated

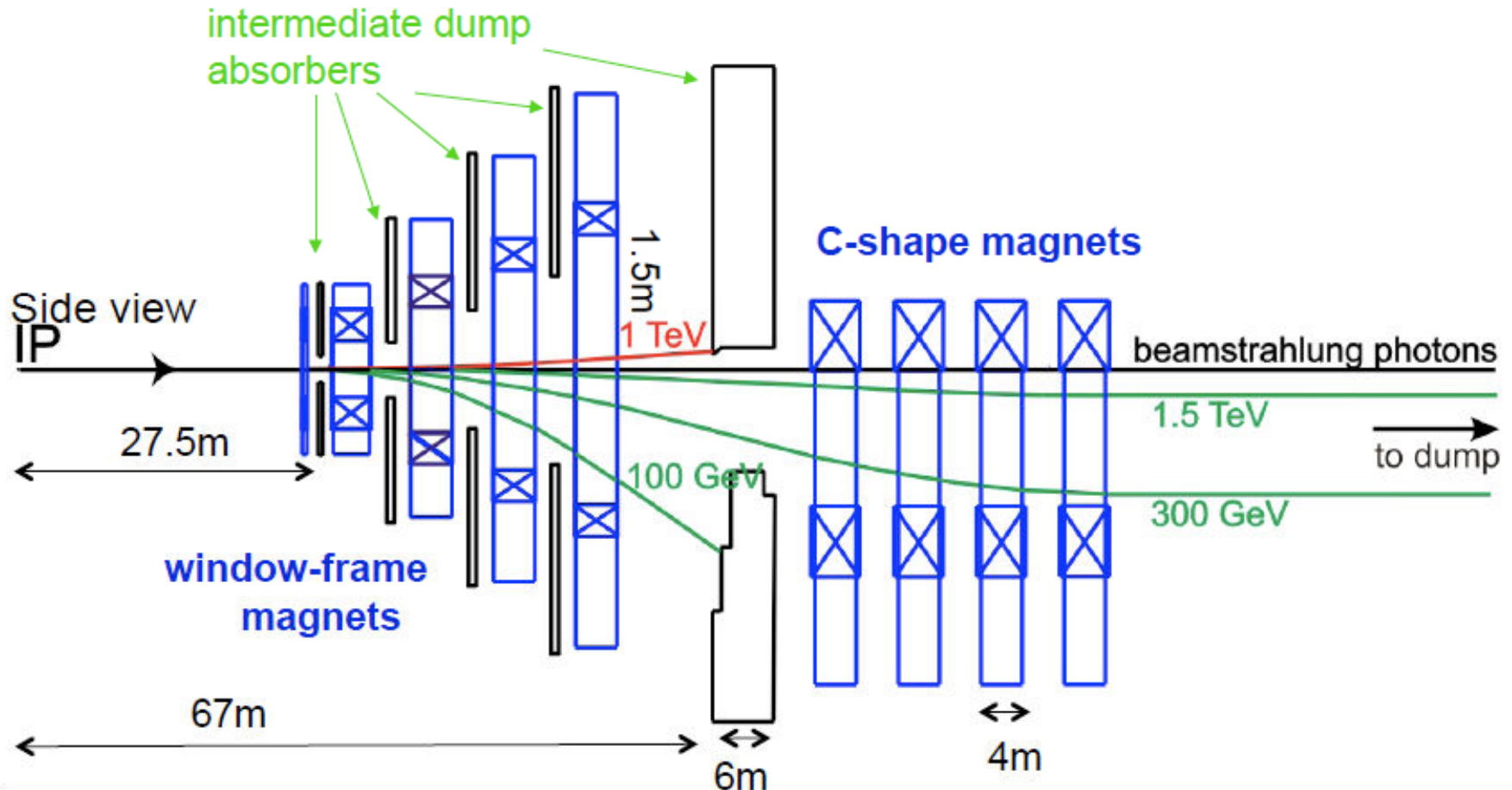
See presentations in the parallel sessions



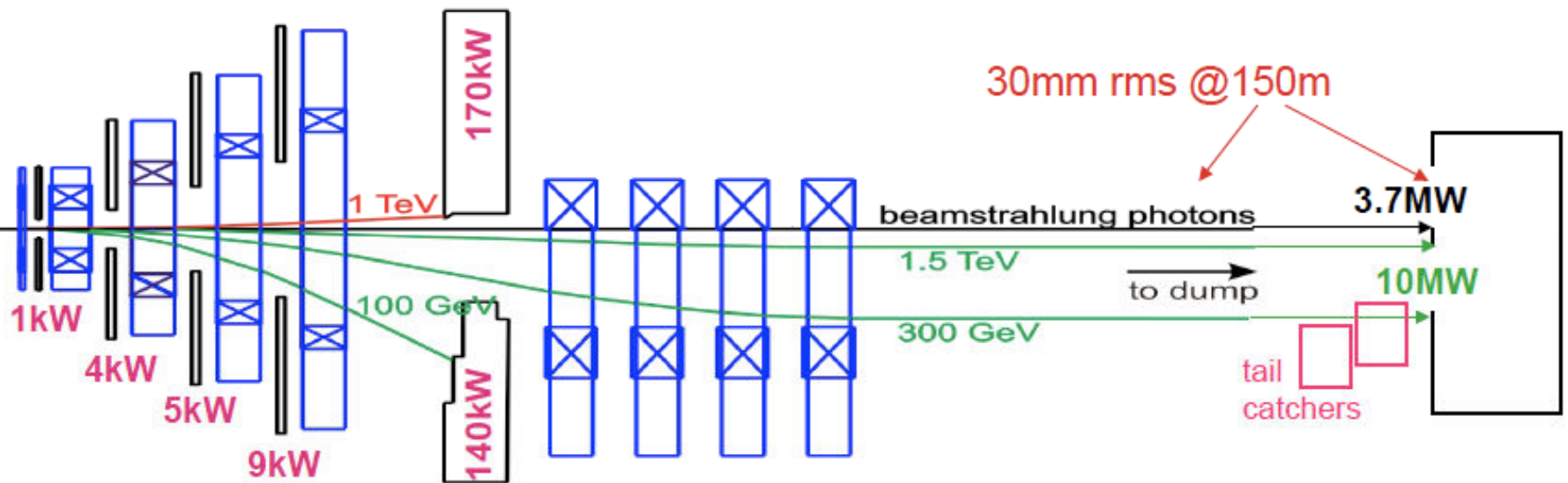
Present Conceptual Design (A. Ferrari, M. Salt et al)

Baseline: vertical chicane with dipole magnets to separate

1. particles from the e^+, e^- pairs with the wrong-sign charge and low energy tail
2. disrupted beam, beamstrahlung photon



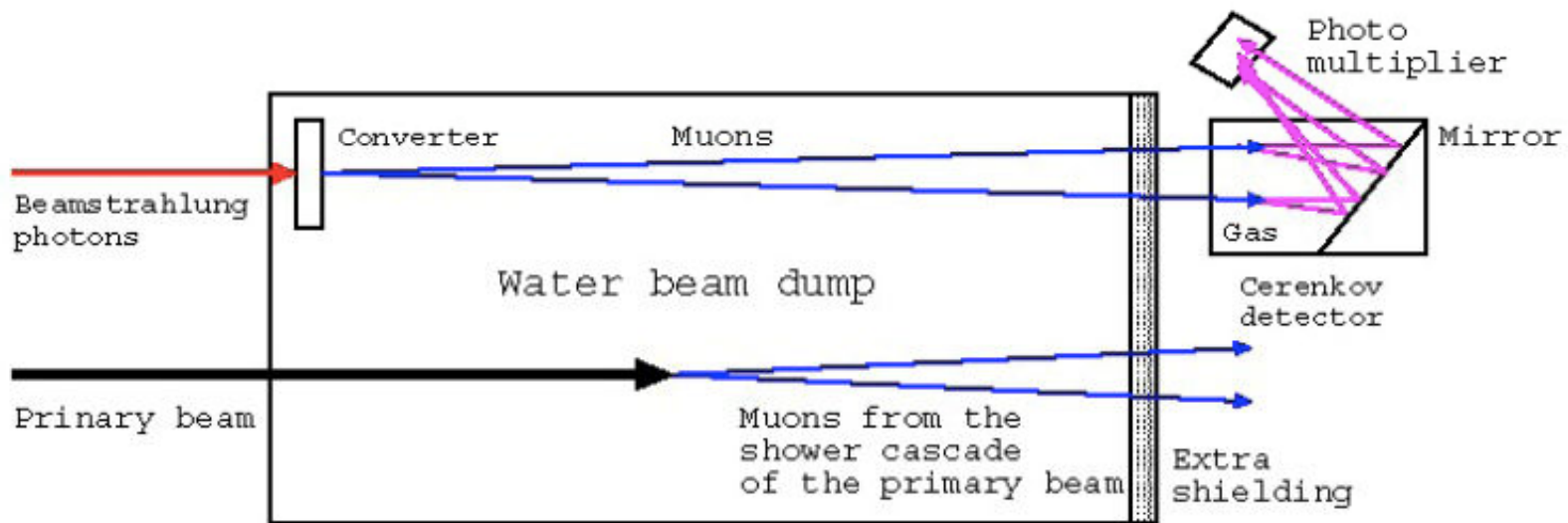
Power Deposition in Main Dump



Luminosity Monitoring: $\mu^+\mu^-$ pair production

- Converter in main dump \rightarrow muons
- Cherenkov detector
 - $\sim 4 \text{ E5}$ photons/bunch

EUROTeV-Report-2008- 016 .



\rightarrow To be studied in more detail: background, converter, detector, etc..

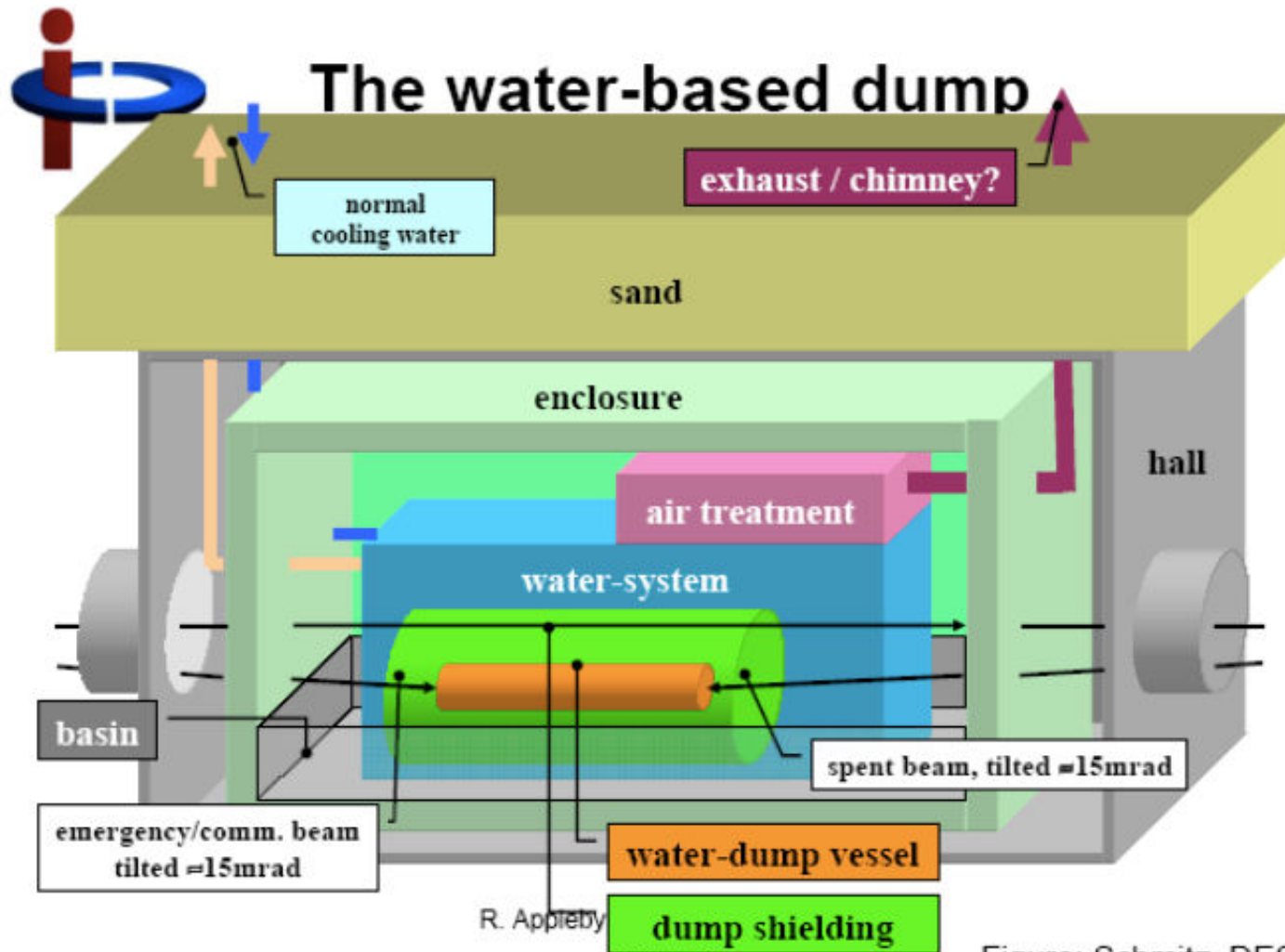
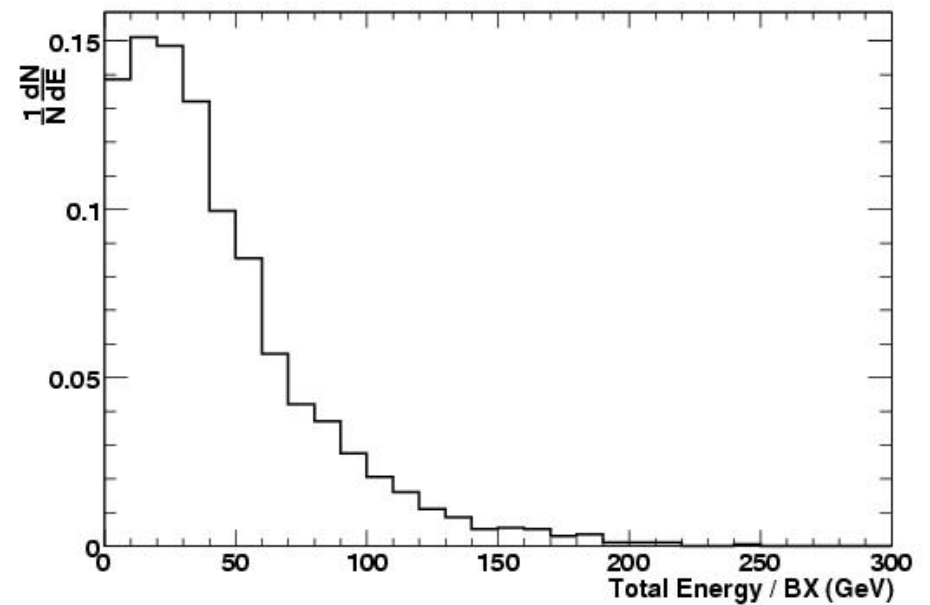
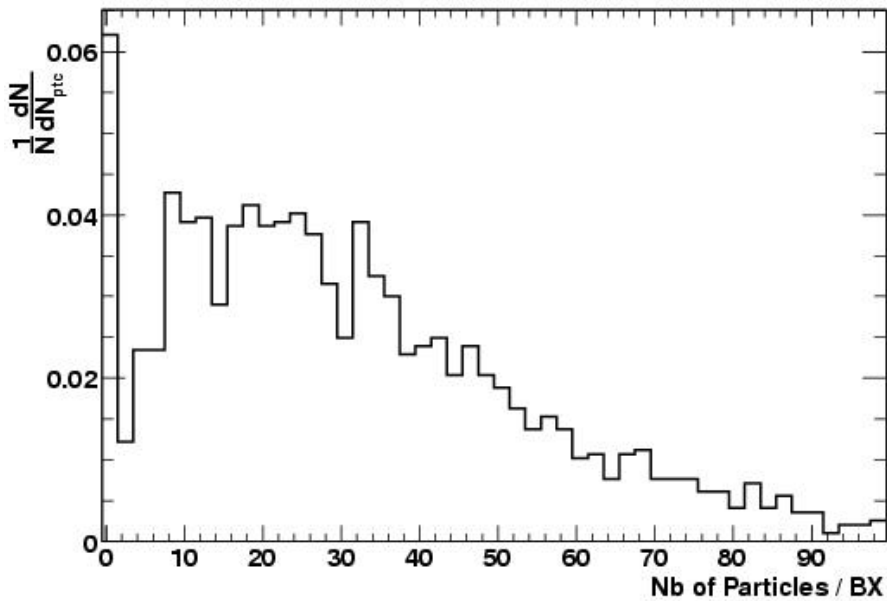


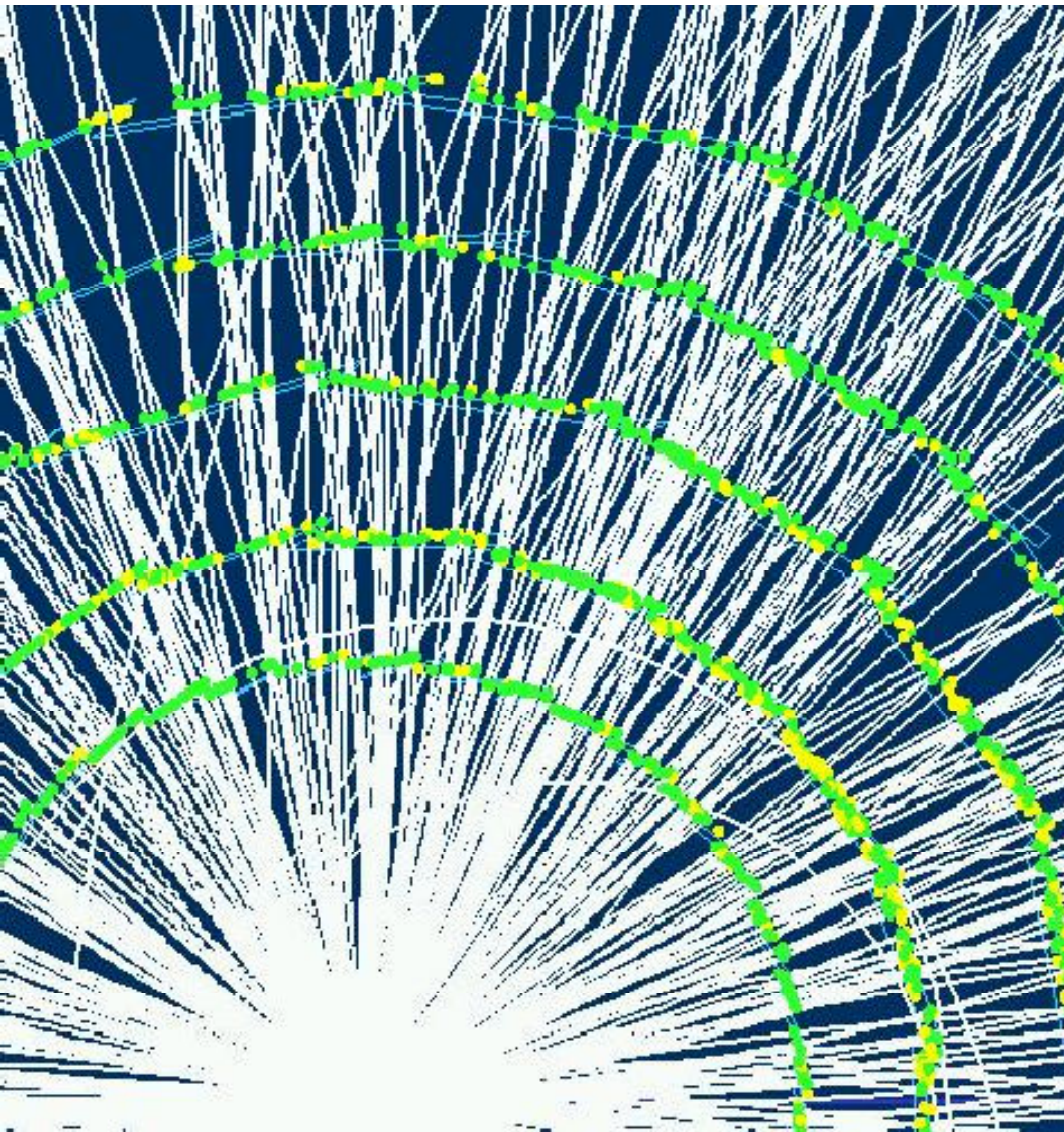
Figure: Schmitz, DESY

$\gamma\gamma \rightarrow$ Hadrons

This process gives a particle density in the vertex detector which is only about a factor of 4 lower than the background from incoherent pairs:



Courtesy M.Battaglia and D.Schulte

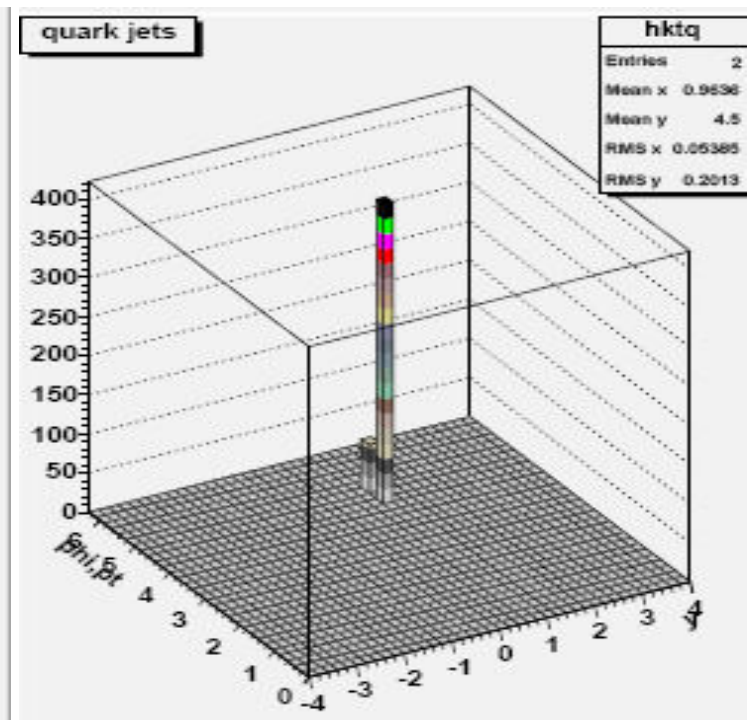
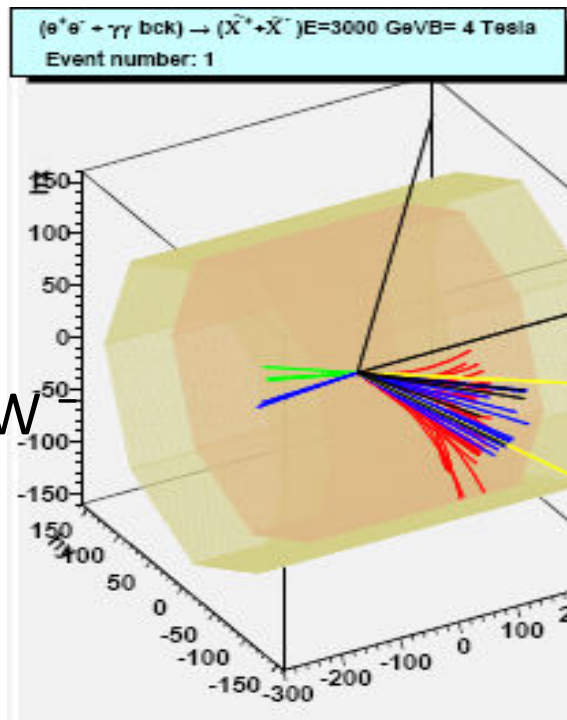


**50 Bunch crossings of
 $\gamma\gamma \rightarrow$ hadrons background
in the vertex detector**



**850 tracks reconstructed
by local pattern
recognition**

Courtesy M.Battaglia



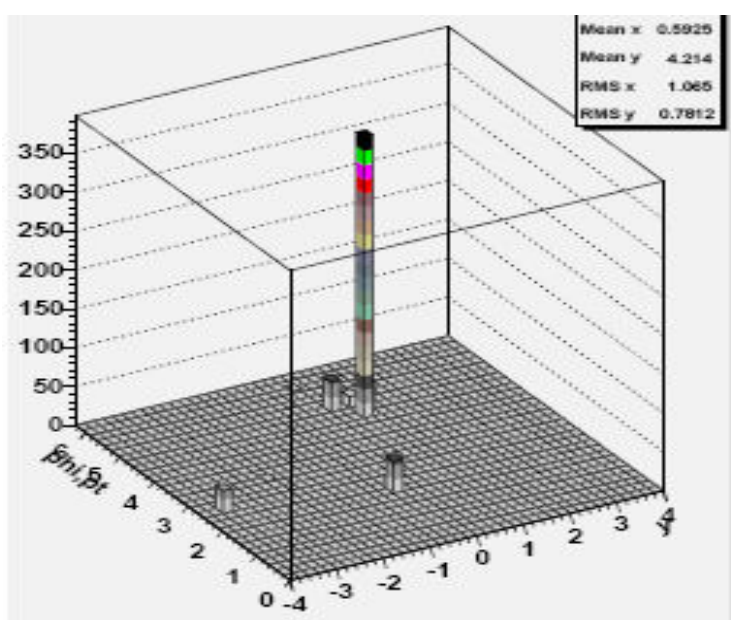
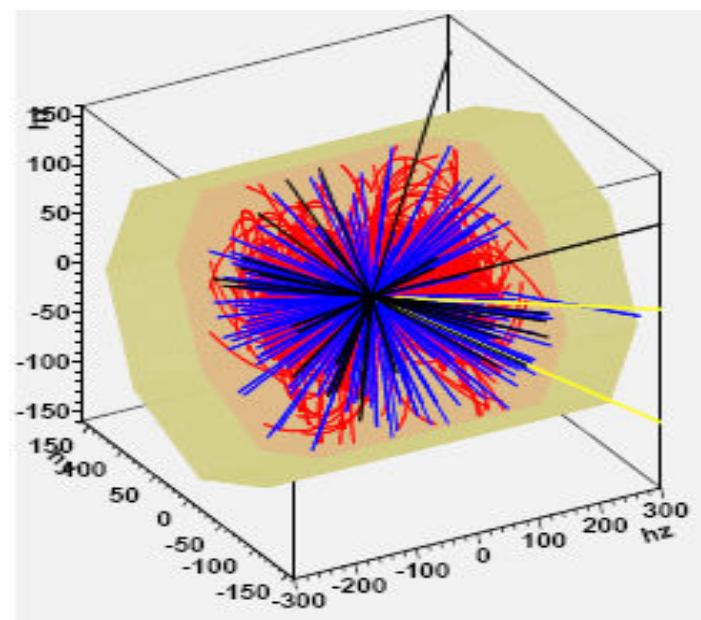
$$e^+ + e^- \rightarrow \chi^+ + \chi^-$$

$$\rightarrow \chi^0 + \chi^0 + W^+ + W^-$$

Without $\gamma\gamma$

Idem with 20 Bx
 $\gamma\gamma \rightarrow$ hadrons
pile up.

The background may spoil the jet energy resolution and affect discrimination variables e.g missing energy, Θ ,
But low E, P_t particles.



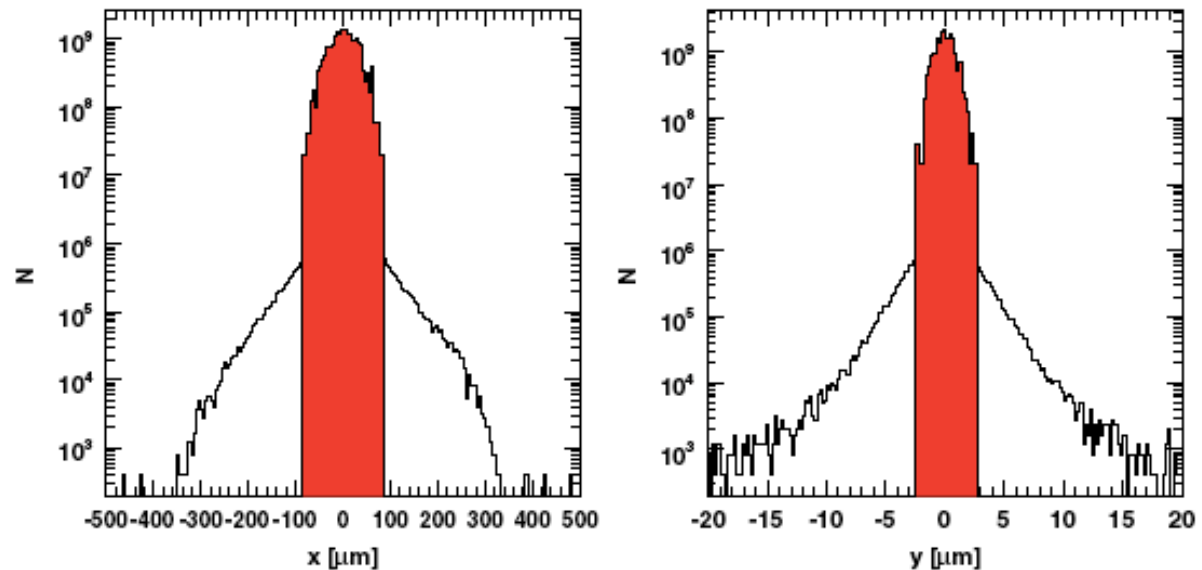
Courtesy JJ.Blaising

Muons from beam halo

Beam tails are scraped away by a collimation system in the BDS.

Below we show simulated profiles of the beam at the BDS entrance (core of beam in red)

*From I. Agapov et al,
2009, to be published*



From these simulations one estimates that a fraction $2 \cdot 10^{-4}$ hit the collimators, i.e. about $2.4 \cdot 10^8$ particles per train assuming a total flux of $1.24 \cdot 10^{12}$ per train. Preliminary estimates indicate that out of those $\sim 2 \cdot 10^5$ would reach the detectors.

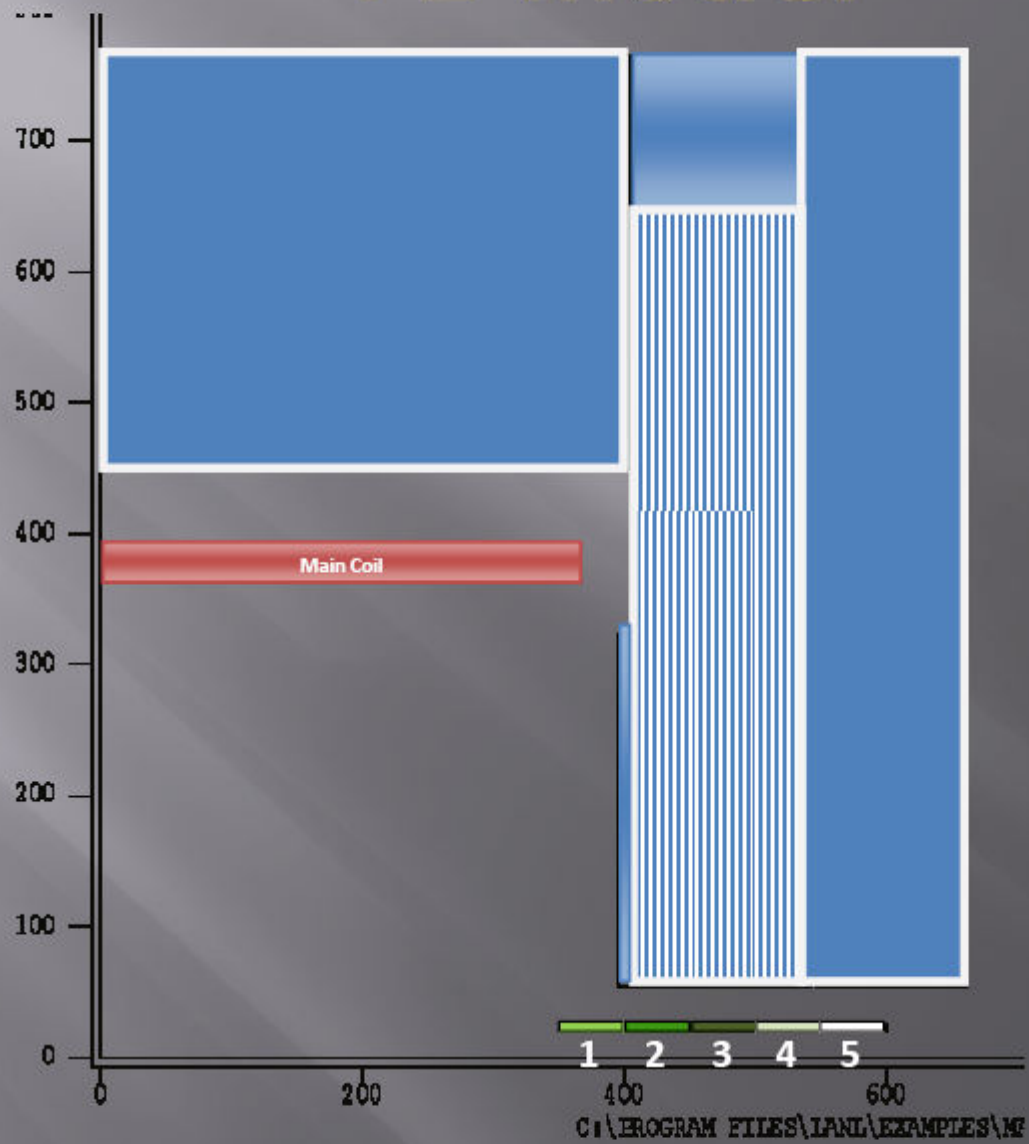
The final rates remain to be studied with BDSIM using the final and detailed geometry

See presentation by H. Burkhardt in BDS parallel session

ANTI-SOLENOID, ANTI-DID

- ❑ In the presence of a crossing angle, the beam couples to the longitudinal field of the main detector solenoid.
- ❑ The solenoid field would also affect the long-term stability of the permanent magnets in the QD0 quadrupole.
- ❑ A proposal has been made for a compensating solenoid around the QD0 quadrupole
See presentation tomorrow by B.Dalena
- ❑ Its mechanical design, integration in the detector and impact on the QD0 stabilisation remains to be studied
- ❑ The anti-DID effect has been simulated, in particular its impact on the luminosity
See presentation tomorrow by B.Dalena

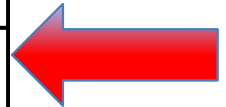
FE model



Intra-Pulse Feedback

Summary of latency times of different FONT tests:

Test	Facility	Train length [ns]	Bunch spacing [ns]	Latency [ns]
FONT1 (2001-2)	NLCTA (SLAC)	170	0.087	67
FONT2 (2003-4)	NLCTA (SLAC)	170	0.087	54
FONT3 (2004-5)	ATF (KEK)	56	2.8	23
FONT4 (2006-7)	ATF (KEK)	420	140	132

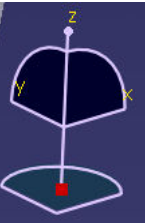


Note: 23 ns is the **TOTAL** latency time: 10 ns (tof + signal return time)
plus 13 ns (electronics)

Scales with distance
(Almost) invariant

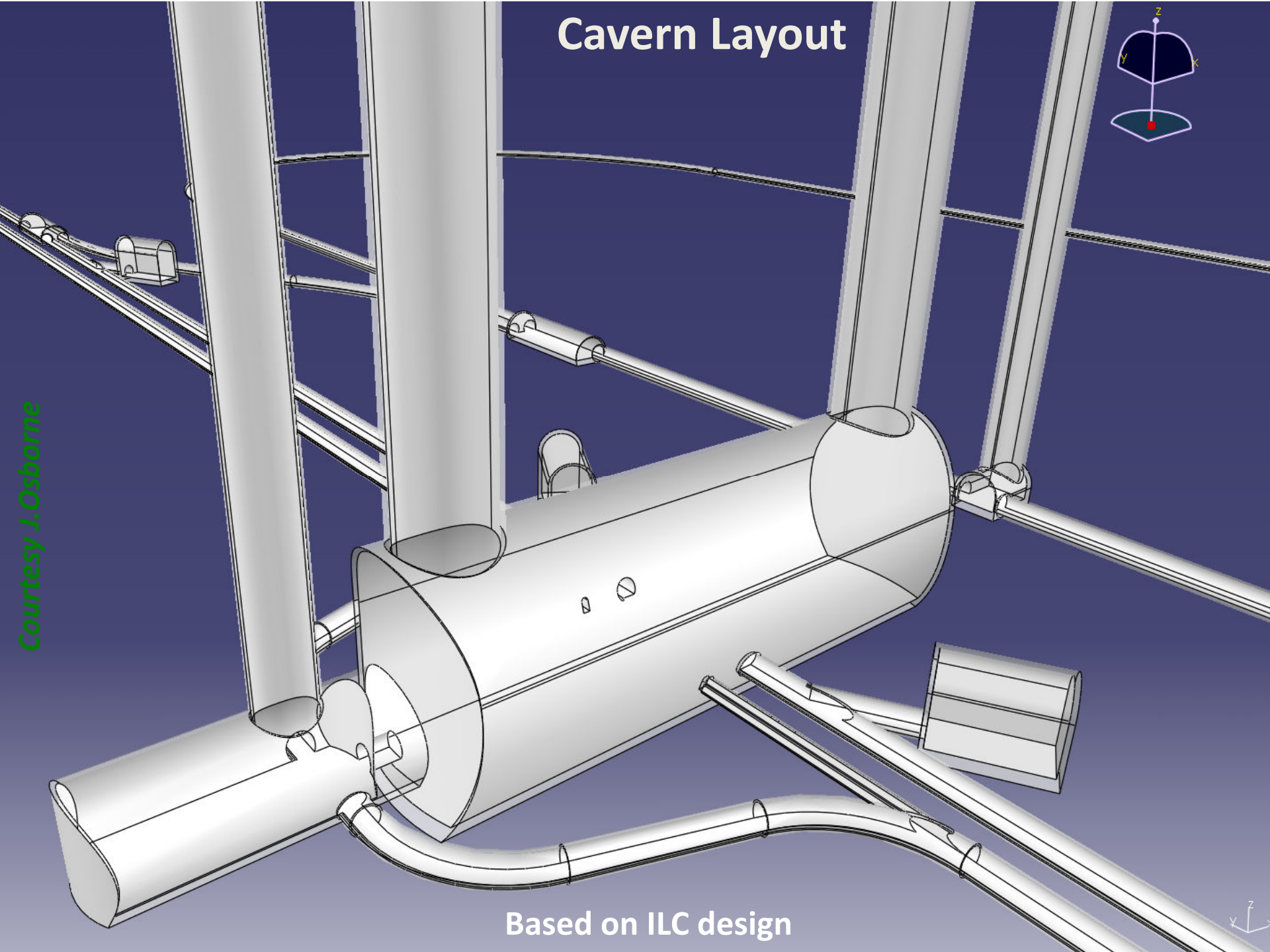
Latest status will be reported by J.Resta Lopez

Cavern Layout

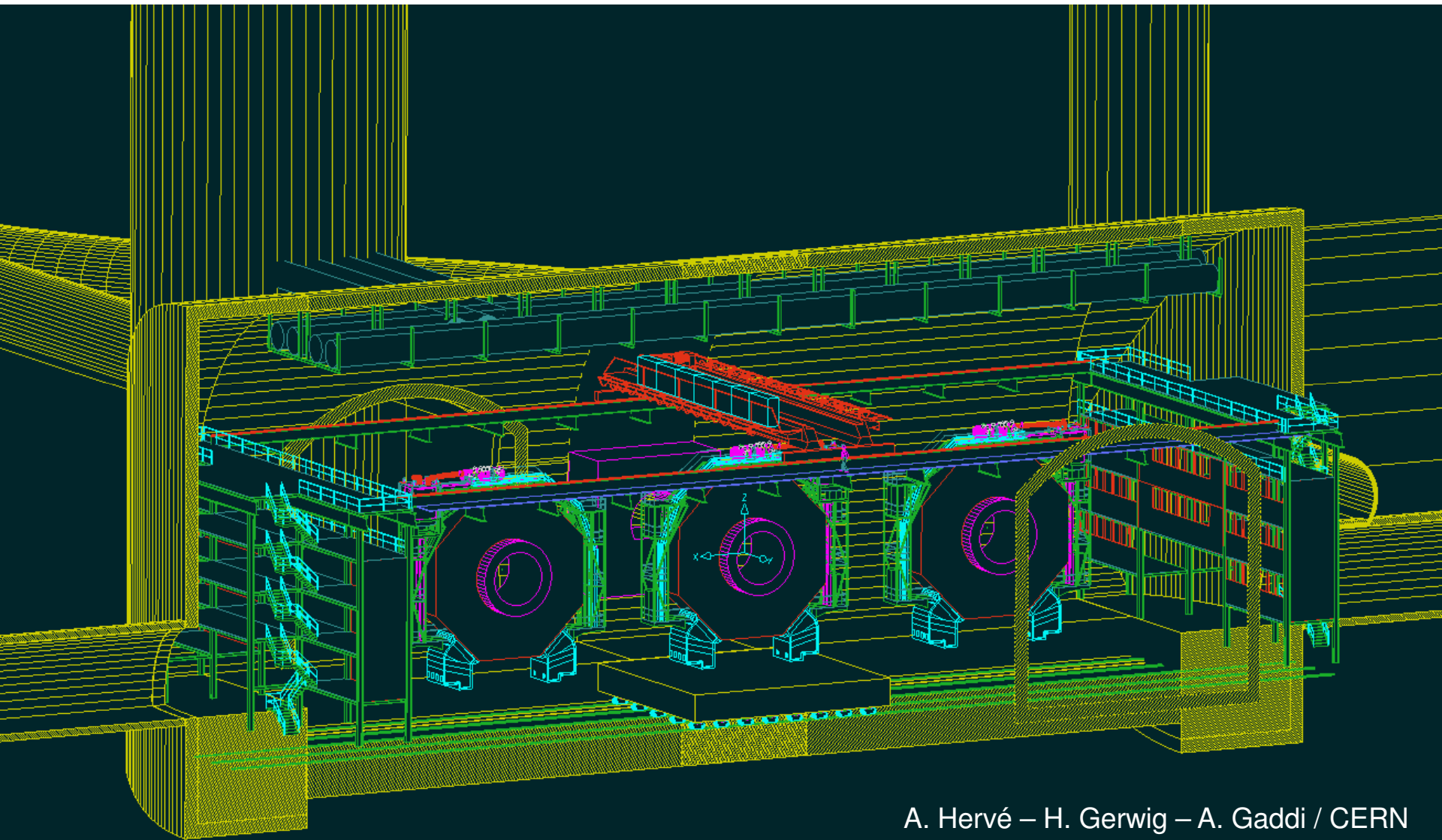


Courtesy J. Osborne

Based on ILC design

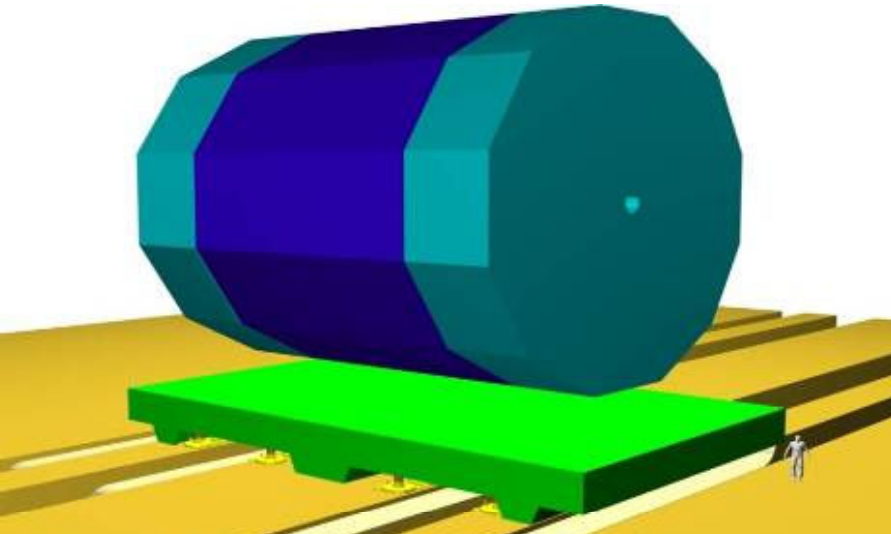


Cavern layout



A. Hervé – H. Gerwig – A. Gaddi / CERN

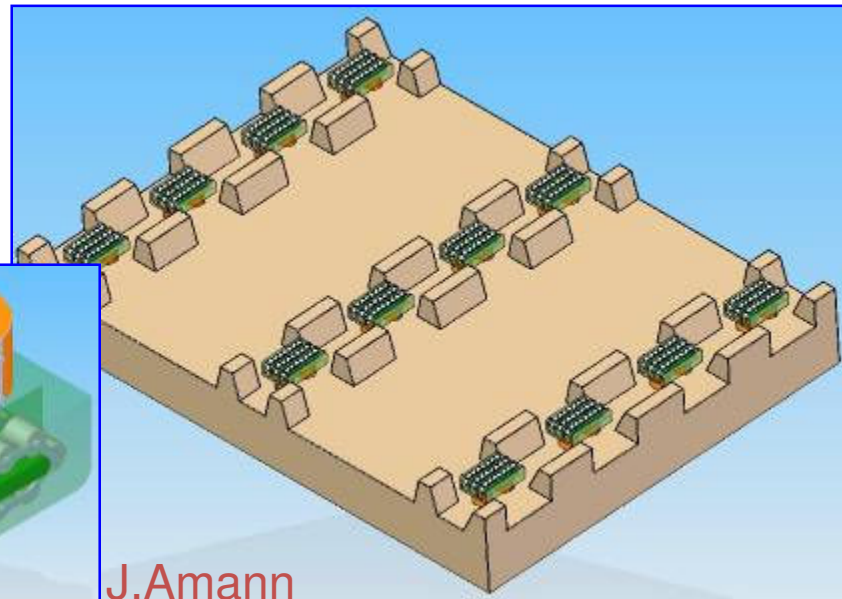
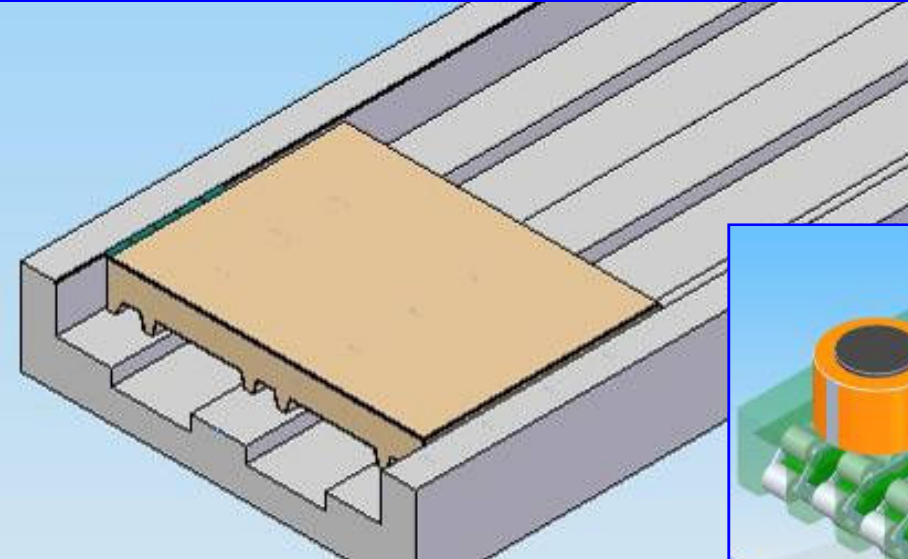
Detector moving



Concept of the platform, A.Herve, H.Gerwig



Air-pads at CMS – move 2000T



J.Amann

Summary and Conclusions

- ❑ The Machine Detector Interface region is full of challenges:
 - QD0 quadrupole
 - Its stabilisation and integration
 - Intra-pulse feedback system
 - Backgrounds
 - Handle the beam power of the spent beam
 - Vacuum
 - Civil engineering and services
 -
- ❑ Work is going on enthusiastically to cope with these challenges towards a plausible solution for the CDR
- ❑ More details in the parallel sessions
- ❑ Thanks to the colleagues in the MDI group for their input