



High precision machining and metrology for structures: achievements and open questions

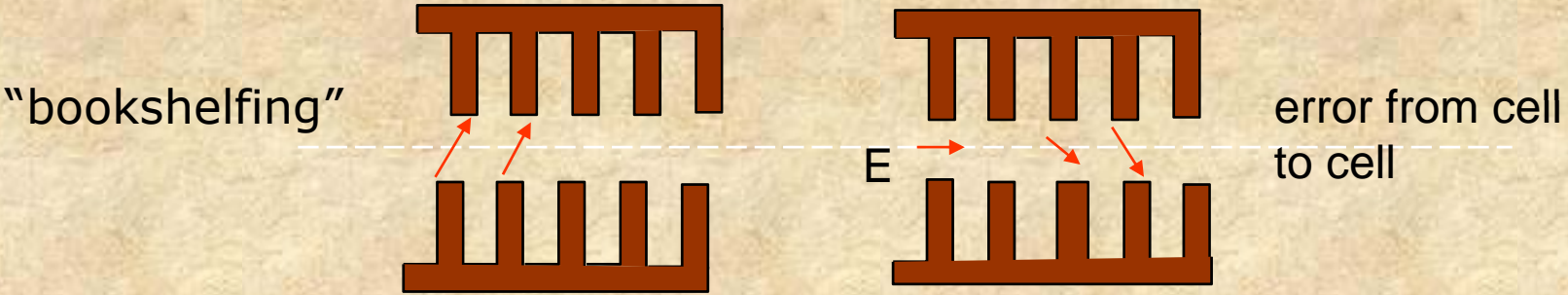
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Why +/- 1 micron precision?

- 0. Frequency matching (deviation of about 4MHz/ μm on cavity radius at 30 GHz)
- 1. Longitudinal alignment precision : $<5 \mu\text{m}$
alignment error of the irises induces transversal kick on the beam (depends on iris aperture)

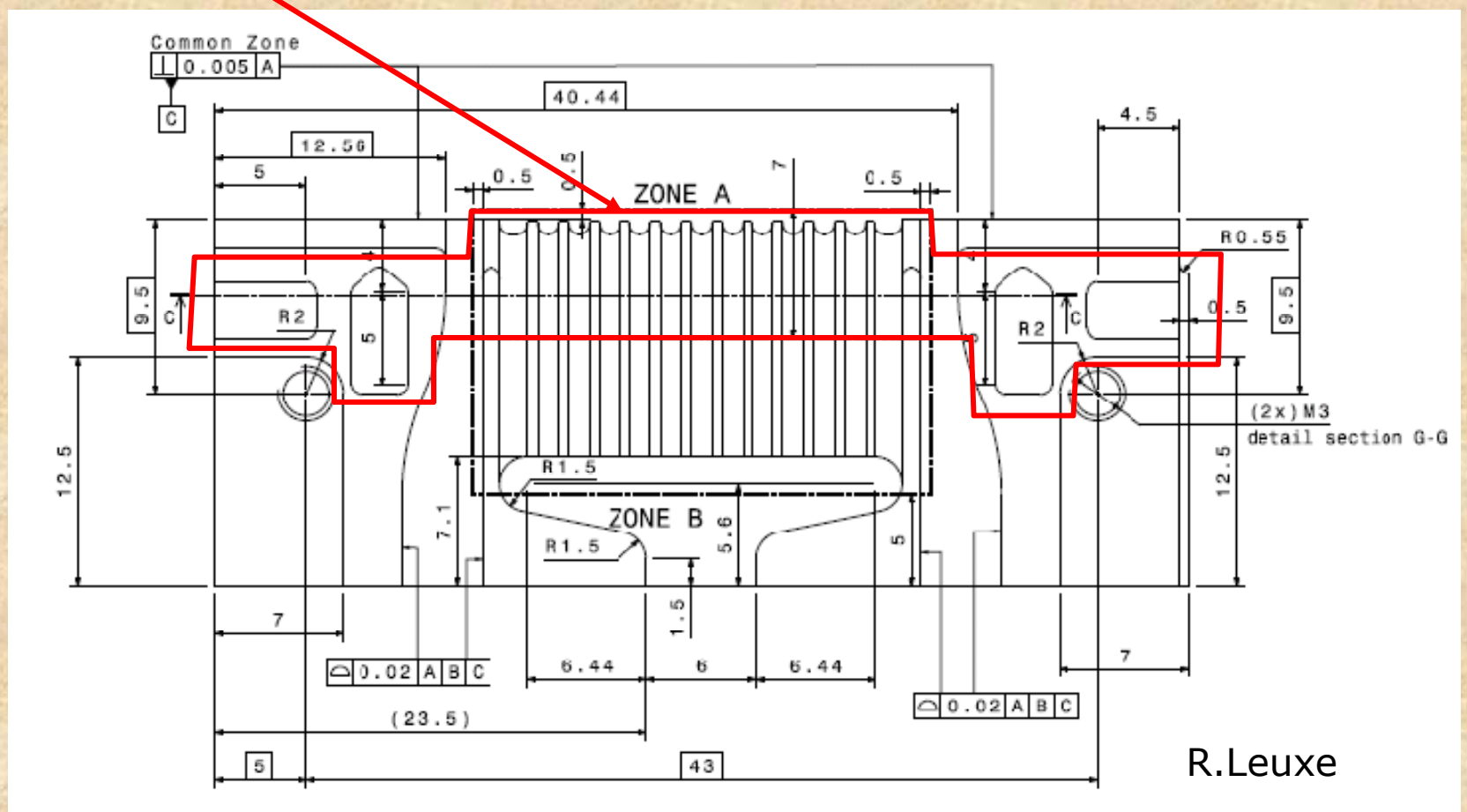


- 2. Avoid steps and kinks on the surfaces (field enhancement β)
- 3. Ra should be around $\frac{1}{4}$ of the skin depth to preserve electrical conductivity ($0.1 \mu\text{m}$)



Tolerances:

5 μm shape tolerance





Ways to approach target accuracy:

1. Production of structures at “acceptable” precision for CTF3/SLAC high power RF-testing (target +/- 0.01 mm on the shape) and exploit the learning curve of firms (Greenfox, Imtec, VDL....)
2. R&D Projects:
KERN, μ -2010 project, EIG, Fraunhofer Inst. ?

Ongoing projects



KERN Feinwerktechnik (D): (CERN order June 2006)

- Machine tool manufacturer (best accurate commercial milling centers in Europe)
- Produced a first prototype (now at CERN metrology), second improved version will follow
- CERN investment: 15K€ + materials

μ-2010: (start March 2007)

- group of French firms/institutes including ENSAM-Cluny and Mikron-France (machine tool manufacturer)
- will deliver a prototype end of July
- CERN investment: materials, investments for further phase to be discussed

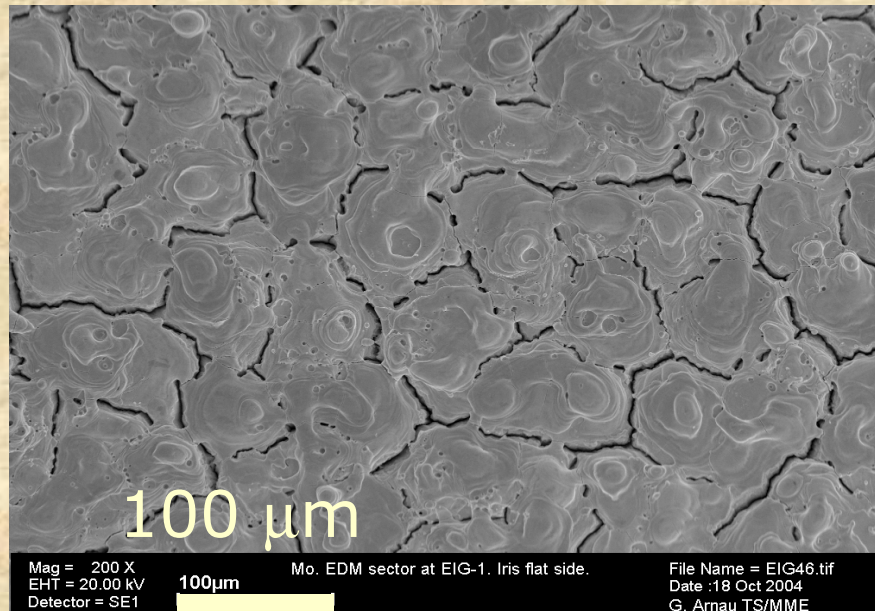
HES-SO Genève: (start Feb 2007, 1y)

- EDM machining and surface finishing of refractory metals
- CERN investment: 20 KFr+ materials

EDM :



-Electro discharge machining of refractory metals
(micro-cracks on molybdenum), development in progress



HES-SO Geneva

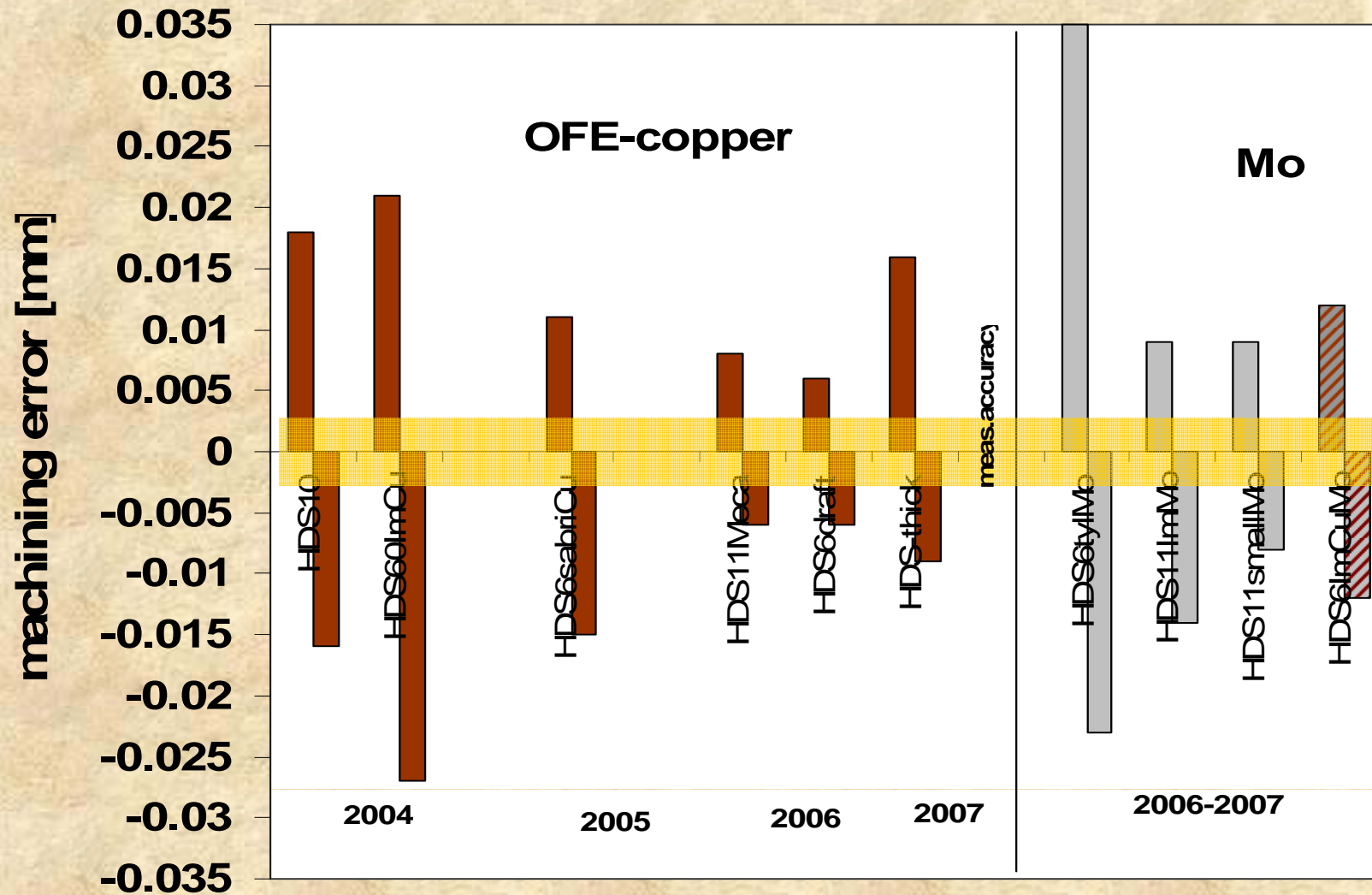
-Parameters to avoid cracks on W are already determined
-Difficult to work in water (black layer); verify the possibility to get clean surfaces when working in oil



Machining technology applied so far to manufacture structures

- technology used so far: CNC milling, at high cutting speed (spindles at 20000-50000 rpm)
- positioning accuracy of the machine tools is 5 μm , two machines below 1 μm (range \sim 300 mm-500 mm)
- carbide or diamond (on copper only) tools (ball nose mills)

Achieved shape accuracy

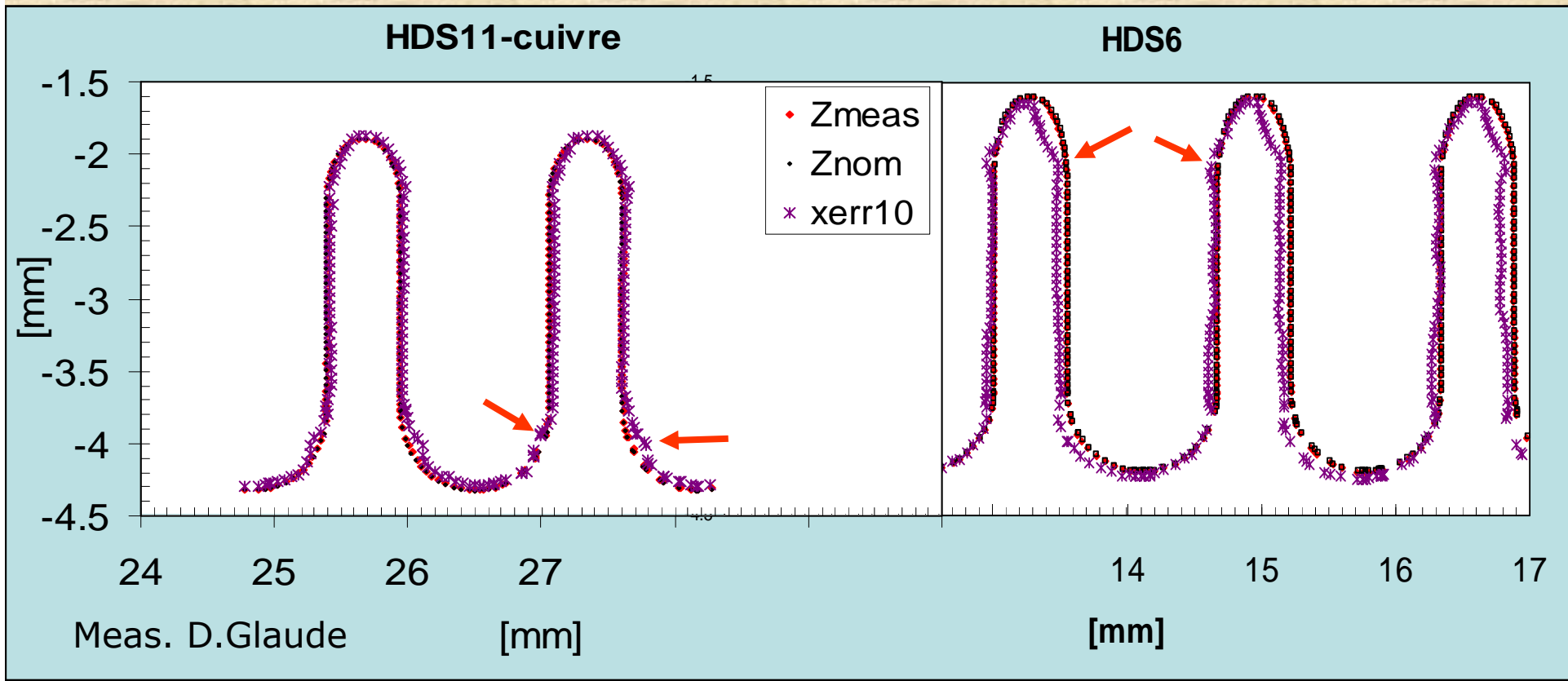


Surface finishing on copper, Ra=0.1-0.4 μm



Metrology on copper quadrants

Measurement: coordinate measuring machine, contact with 0.1N force, accuracy $\pm 3 \mu\text{m}$ (at CERN), scan pt. by pt. on the surfacein parallel with RF low power control

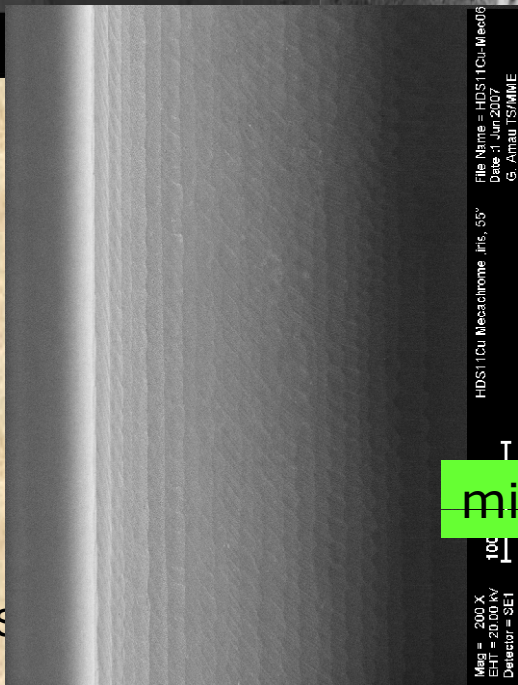
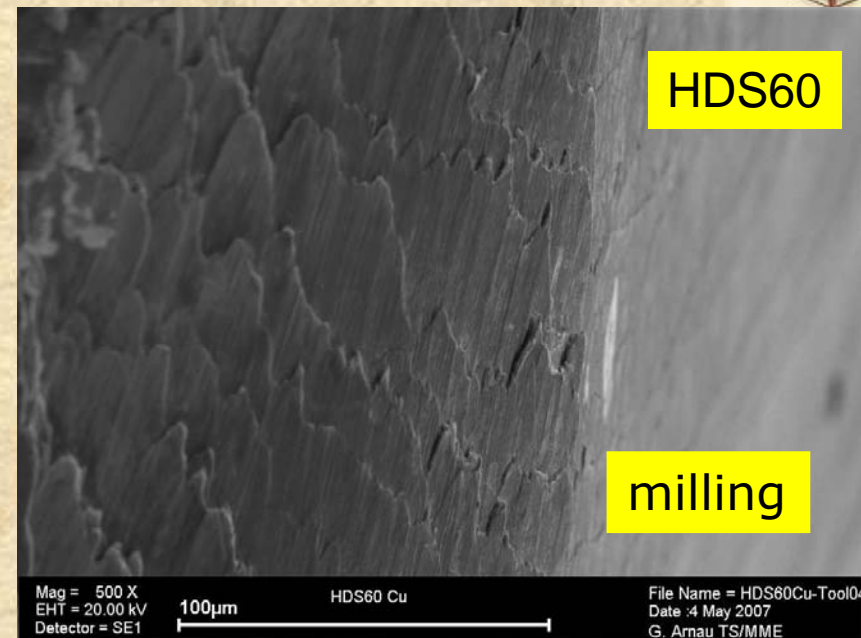
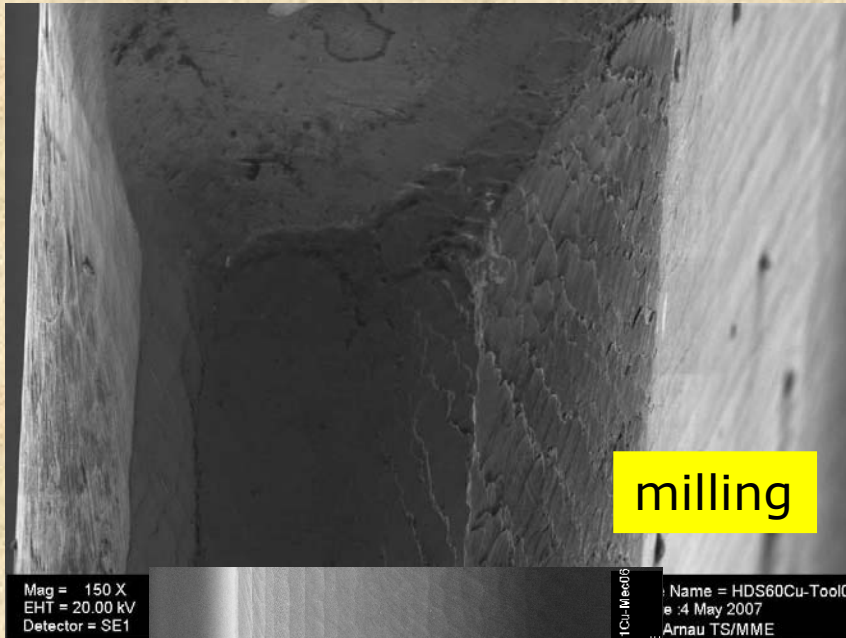




Possible sources of the error in 3D milling

- Most important:** Error on tool diameter, tool length, tool run-out (dynamic dimensions)
 - Error on tool shape
 - Tool flexure (larger tools at 12GHz should be favourable)
 - Tool consumption during machining
-
- Temperature stability and dynamics of the machine tool
 - Positioning accuracy of the machine tool (machine tools with higher nominal accuracy have given better surface finish)

Surface quality: on copper



Surface quality still worse than diamond turning

5/7/2007 TS

Image: G.Arnau-Izquierdo

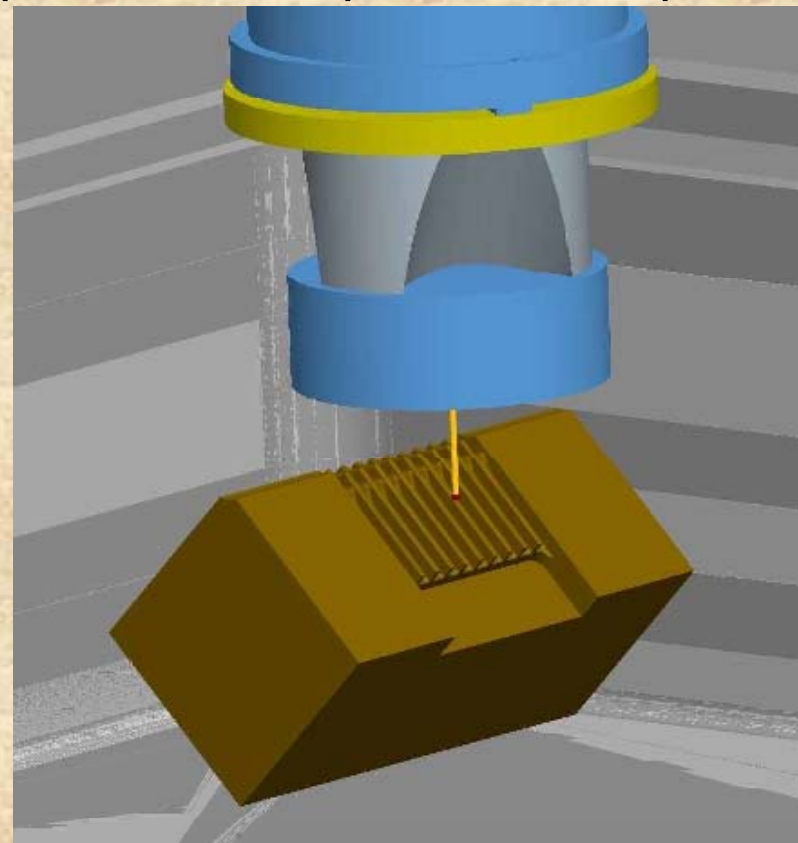
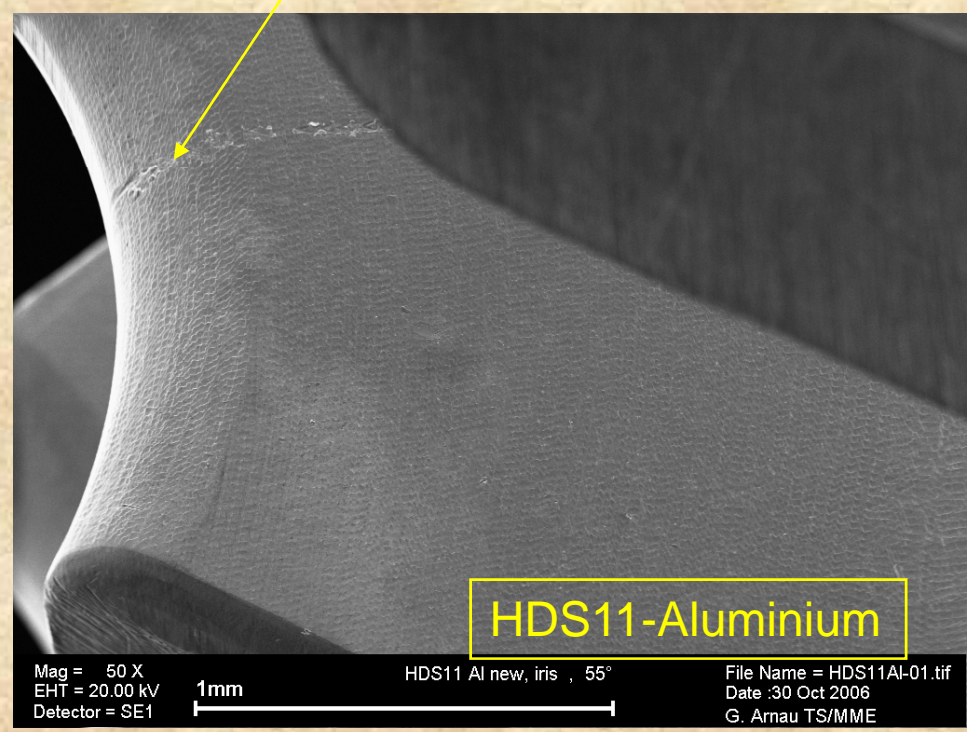
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Metrology

Requires high accuracy, ideally $0.1 \mu\text{m}$ to control at $1 \mu\text{m}$ level
Force of the sensor should be low (0.1 N leaves marks)
Available optical methods are not adapted for complex 3D shapes

Trace of sensor contact





Conclusions:

- Realistic goal for 2010 should be to demonstrate +/- 3-5 μm on a copper structure of 250-300 mm (CLIC size)
- +/- 1 μm needs major R&D investment and the market is still marginal for parts of this size
- Improving internal competence for high precision machining is necessary: through follow up, training or doing
- Internally we do not have a metrology equipment to control reliably below +/- 5-10 μm accuracy: needs better sensor (lower forces) and better CMM (higher positioning accuracy)
- Manpower for metrology is limited and feedback cannot be given fast to firms